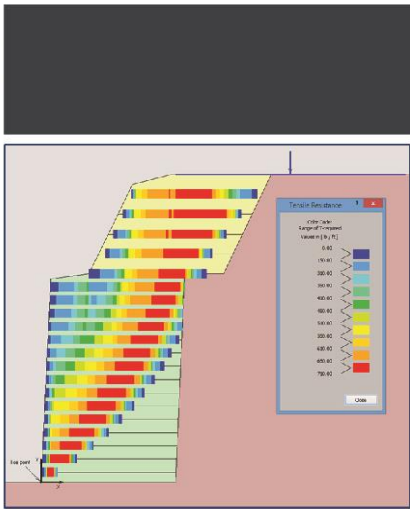


# **ReSSA+**

# ***Overview and Instructive Examples***

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Emeritus Professor***





LIMIT EQUILIBRIUM DESIGN FRAMEWORK FOR MSE STRUCTURES WITH EXTENSIBLE REINFORCEMENT



Technical Report Documentation Page			
1. Report No. FHWA-HIF-17-004	2. Government Accession No.	3. Recipient's Catalog No.	
4. Title and Subtitle Limit Equilibrium Design Framework for MSE Structures with Extensible Reinforcement		5. Report Date October 2016	
		6. Performing Organization Code	
7. Principal Investigator(s): See Acknowledgements for Authors and Contributors  Dov Leshchinsky, Ph.D <sup>1</sup> , Ora Leshchinsky, P.E. <sup>1</sup> , Brian Zelenko, P.E., John Horne, Ph.D., P.E.		8. Performing Organization Report No.	
9. Performing Organization Name and Address  Parsons Brinckerhoff 1015 Half Street, SE, Suite 650 Washington, DC 20003  <sup>1</sup> ADAMA Engineering, Inc., 12042 SE Sunnyside Rd., Suite 711, Clackamas, OR 97015		10. Work Unit No. (TRAIS)	
		11. Contract or Grant No. DTFH6114D00047-5010	
12. Sponsoring Agency Name and Address Federal Highway Administration HIBT-20 Office of Bridge Technology 1200 New Jersey Avenue, SE Washington, DC 20005		13. Type of Report and Period	
		14. Sponsoring Agency Code	
15. Supplementary Notes  FHWA COR – Silas Nichols, P.E. FHWA Alt. COR – Khalid Mohamed, P.E.			
16. Abstract  Current design of reinforced soil structures in the U.S. distinguishes between slopes and walls using the batter angle as a criterion. Using a unified approach in limit state design of reinforced 'walls' and 'slopes' should diminish confusion while enabling a wide and consistent usage in solving geotechnical problems such as complex geometries and soil profiles. Limit equilibrium (LE) analysis has been used successfully in the design of complex and critical (e.g., tall dams) for many decades. Limit state analysis, including LE, assumes that the <i>design</i> strength of the soil is mobilized. Presented is a LE framework, limited to extensible reinforcement, which enables the designer to find the tensile force distribution in each layer required at a limit state. This approach is restricted to Allowable Stress Design (ASD). Three example problems are presented.			
17. Key Words  Mechanically Stabilized Earth Wall Design, MSE Wall Design, Limit Equilibrium, Geotechnical, Extensible reinforcement		18. Distribution Statement  No restrictions.	
19. Security Classif. (of this report)  UNCLASSIFIED	20. Security Classif. (of this  UNCLASSIFIED	21. No. of Pages  120	22. Price

# ***Roadmap of Presentation***

- ***Why Limit State analysis is needed?***
- ***Limit Equilibrium Analysis: Global Approach***
- ***The Safety Map Tool***
- ***Limit Equilibrium Analysis: Baseline Solution***
- ***Limit Equilibrium: Design Approach***
- ***Limit Equilibrium: Instructive Examples***
- ***Concluding Remarks***

# ***Why Limit State Check is Needed?***

- ***Limit State failure is a realistic possibility***
- ***Such state is avoided by assigning adequate margins of safety in design***
- ***To quantify such margins, one needs to reliably predict limit state conditions***
- ***Limit State implies that soil strength is fully mobilized anywhere within the reinforced mass; stability then is hinging on the reinforcement tensile resistance***
- ***This state is also called 'Internal Stability'***

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# *Global Limit Equilibrium (LE)*

- *Simple to use; applicable to complex problems*
- *Vast experience*
- *Reinforced soil is subset of slope stability analysis*
- *Compatibility between dissimilar materials may need to be considered → Consequently, present scope is limited to extensible reinforcement*
- *Global LE design is half-cooked → Strength of reinforcement is examined globally while the locally required strength, including connections, is overlooked → Potential local overstressing*
- *It does not deal explicitly with 'Internal Stability' → It provides a narrow design insight*

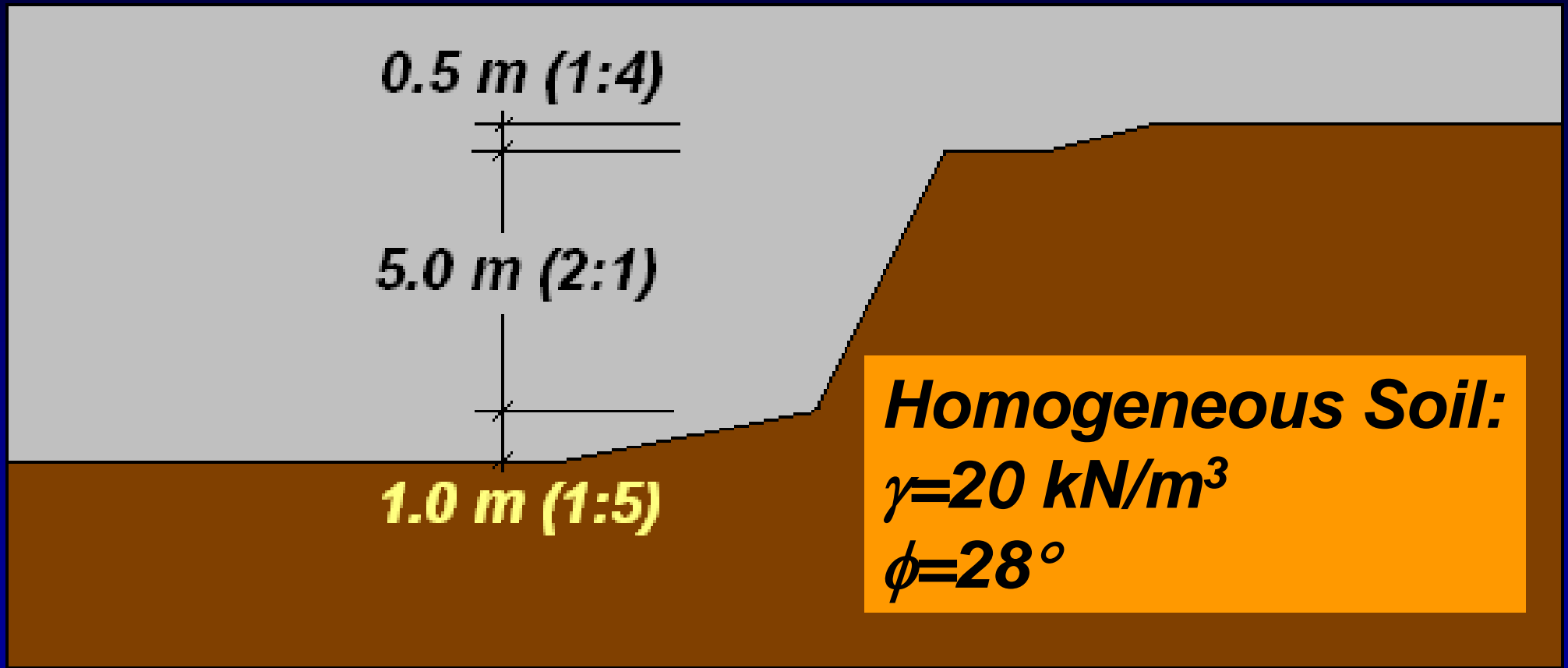
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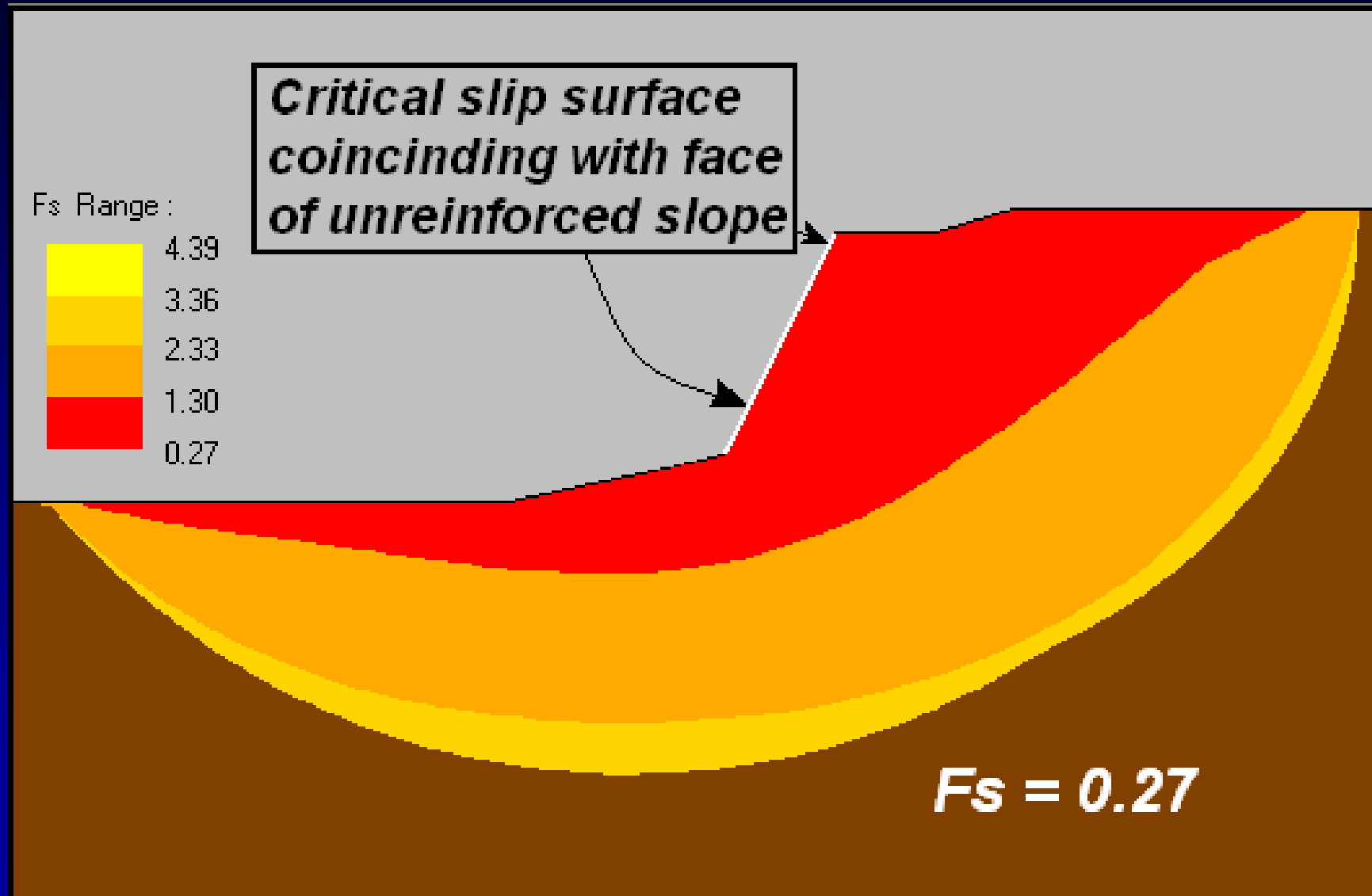
# *The Safety Map Tool*

- *Baker and Leshchinsky (2001) introduced the concept of, and coined the term, **Safety Map***
- ***Safety Map** = Visual diagnostic tool for the state of stability of a reinforced mass*
- *Design Objective: Select strength & layout of reinforcement to produce as uniform safety factors within the reinforced mass as practically possible = Efficiency*

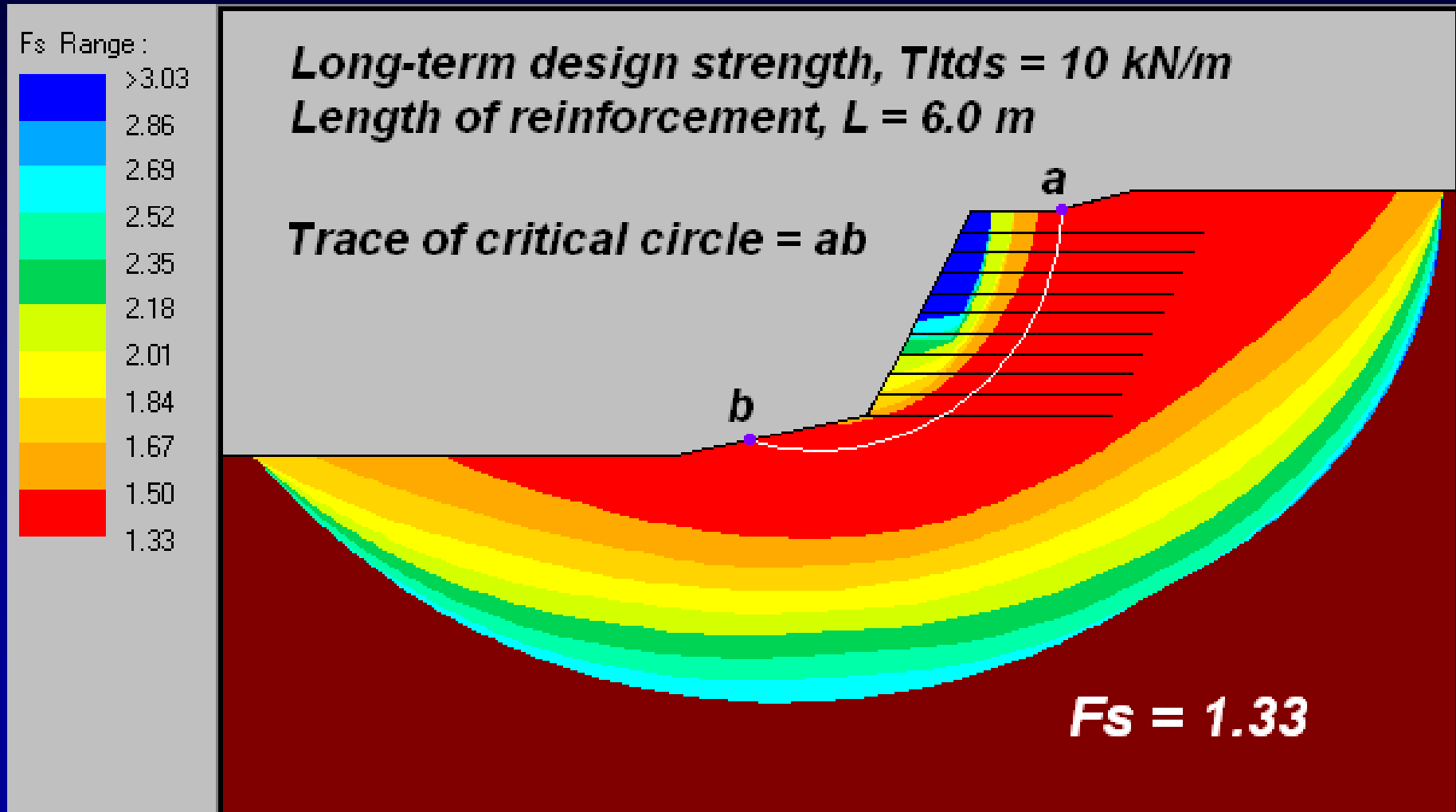
# *Example Problem: Effects of Water*



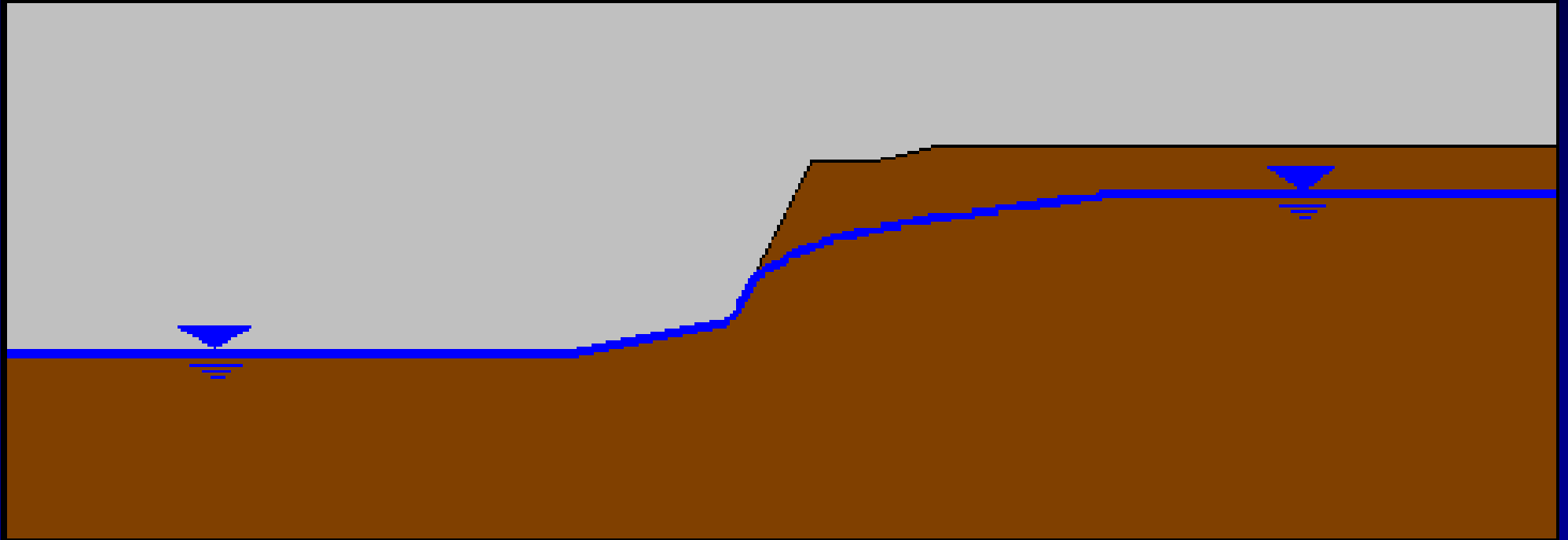
# Unreinforced Dry Problem



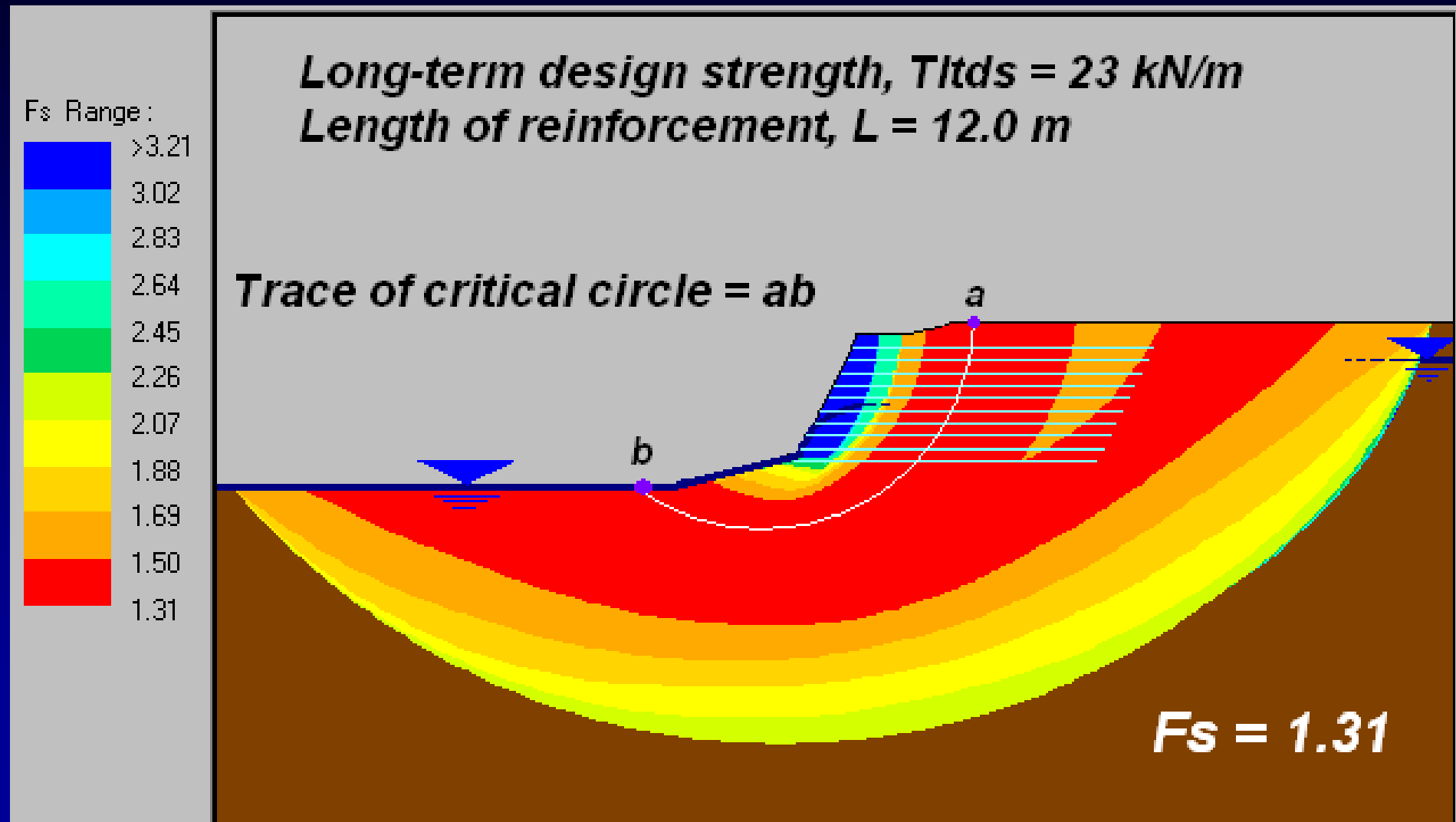
# Reinforcement for Dry Problem using Circular Arc (Bishop)



# *Seepage into Design of Dry Reinforced Slope*



# Redesigned Reinforcement for Water



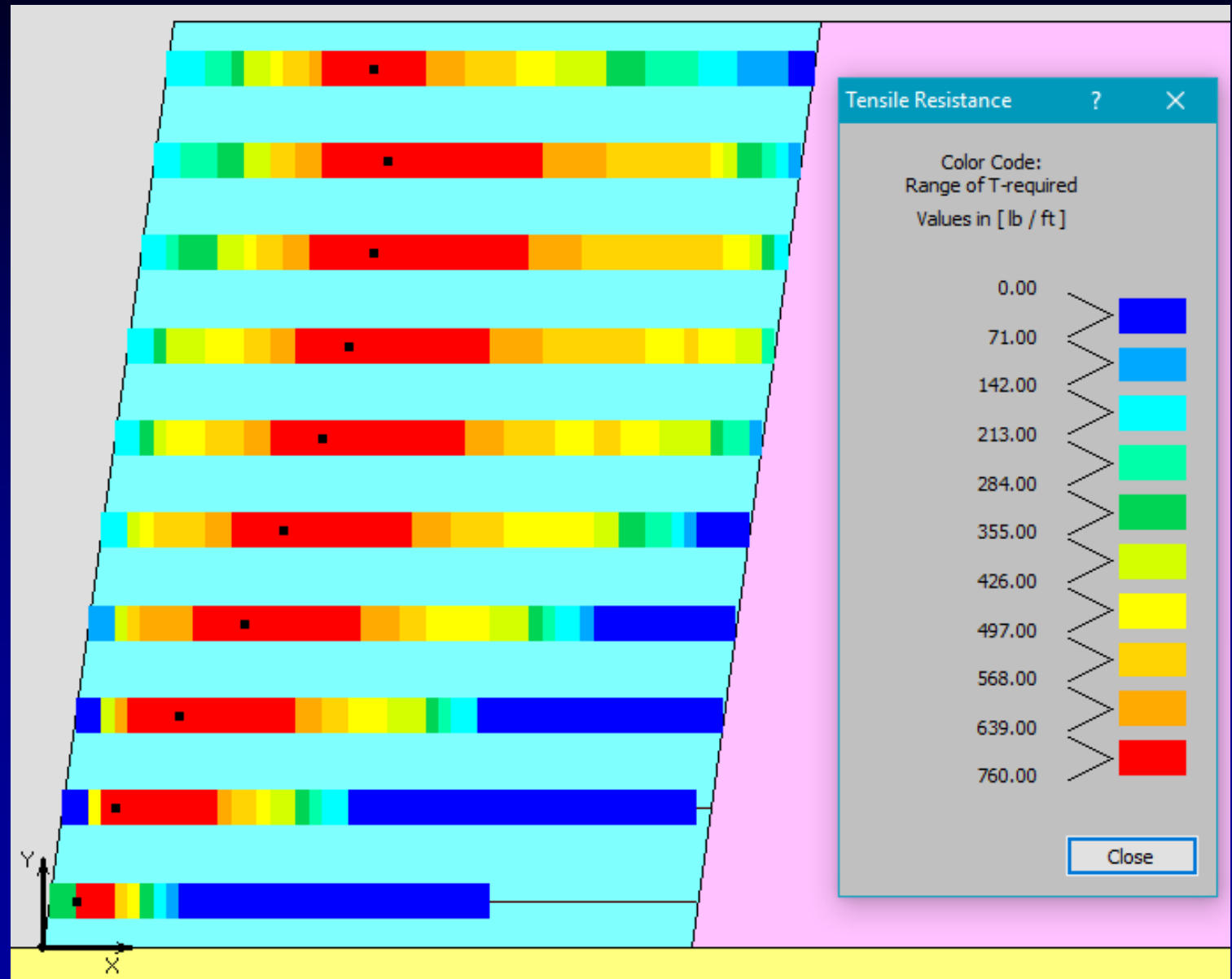
# ***Roadmap of Presentation***

- *Why Limit State analysis is needed?*
- *Available Limit State Methods of Analysis*
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# *Inverse of Safety Map...*

- *Safety Map finds the spatial distribution of the safety factors,  $SF$ , in the reinforced soil problem*
- *Conversely, the LE **Framework** (ReSSA+) produces the tensile resistance needed for  $F_s = SF = 1.0$  everywhere*
- *The **Framework** approach produces the baseline solution: **Tension Map**,  $T(x)$ , including  $T_{max}$  and  $T_o$  for each layer → It leads to a rational and robust selection of reinforcement and facing*

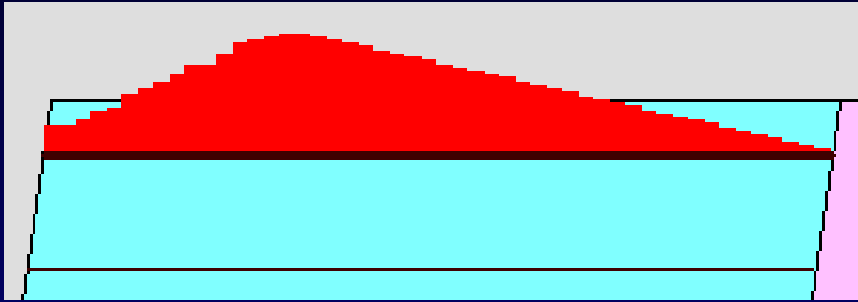
# Example of Tension Map: Visualization of $T(x)$



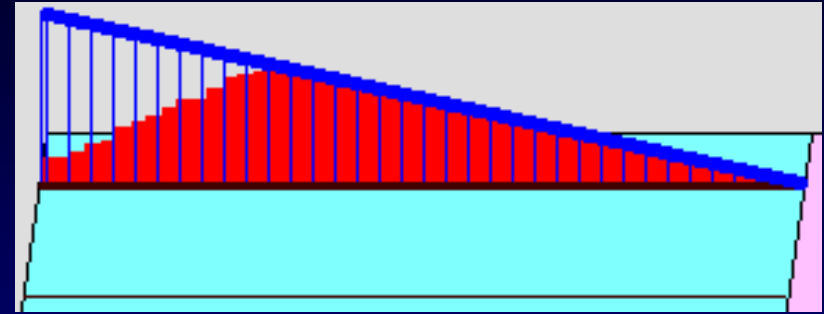
# ***The Framework: Process in Nutshell***

- *Check numerous test bodies → Set  $SF=1.0$  and calculate  $T(x)$  for each layer*
- *Use a systematic top-down process assessing many surfaces emerging at the slope*
- *For  $T(x)$  failure along any surface is equally likely →  $T(x)$  is termed **Baseline Solution** → **Tension Map***
- *The tension,  $T(x)$ , may be limited by pullout at the rear and/or front ends*

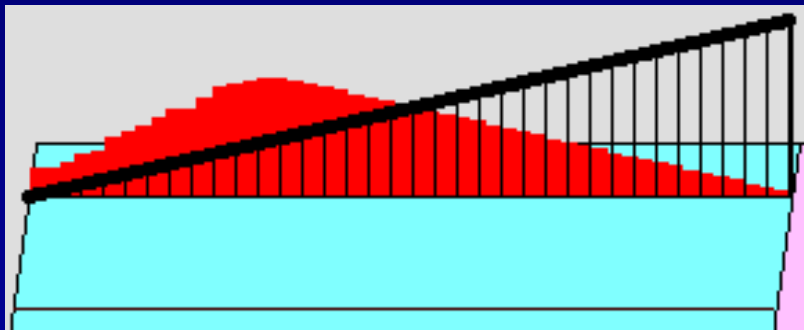
# Details: Baseline & Pullout (front and rear pullouts not function of $T_{max}$ )



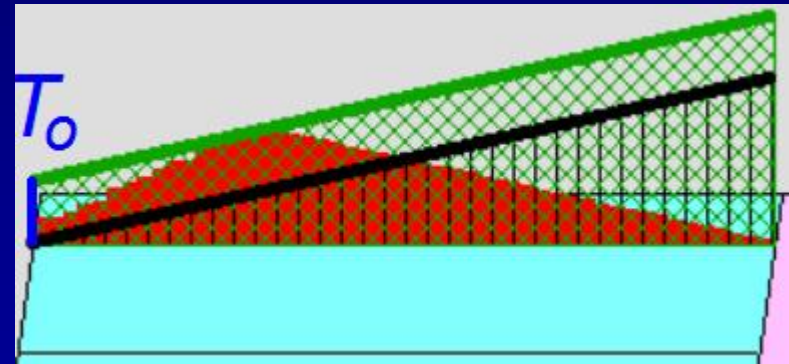
1.  $T(x)$



2. Rear pullout constraint



3. Front pullout... oops



4. Adjust front pullout  
→ Upwards shift is  $T_0$

# ***Roadmap of Presentation***

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# ***Advancement of Current Design***

- ***Application of the LE design approach is split into two stages: Internal Stability and Global Stability***
- ***Internal stability considers the distribution of tensile loading in all reinforcements***
- ***Unlike previous design, this enables direct consideration of geometry, loading conditions, reinforcement layout, pullout resistance, etc.***
- ***Global stability is consistent with current design***

# Stage 1: 'Internal Stability'

- Select  $SF=Fs=1.0$  on soil strength
- Use framework to find  $T(x)$  including  $T_{max}$  &  $T_o$
- Determine  $\max(T_{max})$  to select geosynthetic
- $LTDS = F_{s\text{-strength}} \times \max(T_{max-i})$  where  $F_{s\text{-strength}} = 1.5$
- $T_{ult} = LTDS \times RF_{cr} \times RF_d \times RF_{id}$
- Stage 1 is a rational and robust alternative to existing approaches → Consistent with principles of LE and is not arbitrary

## ***Stage 2: Global Stability***

- ***Select reinforcement and facing following Stage 1***
- ***Conduct global slope stability analysis to ascertain that for the selected facing, layout and strength reinforcement,  $F_s$  is greater than, say, 1.30 or 1.50, for all feasible failure geometries***
- ***If needed, increase the length and/or strength of reinforcement to meet the prescribed  $F_s$***

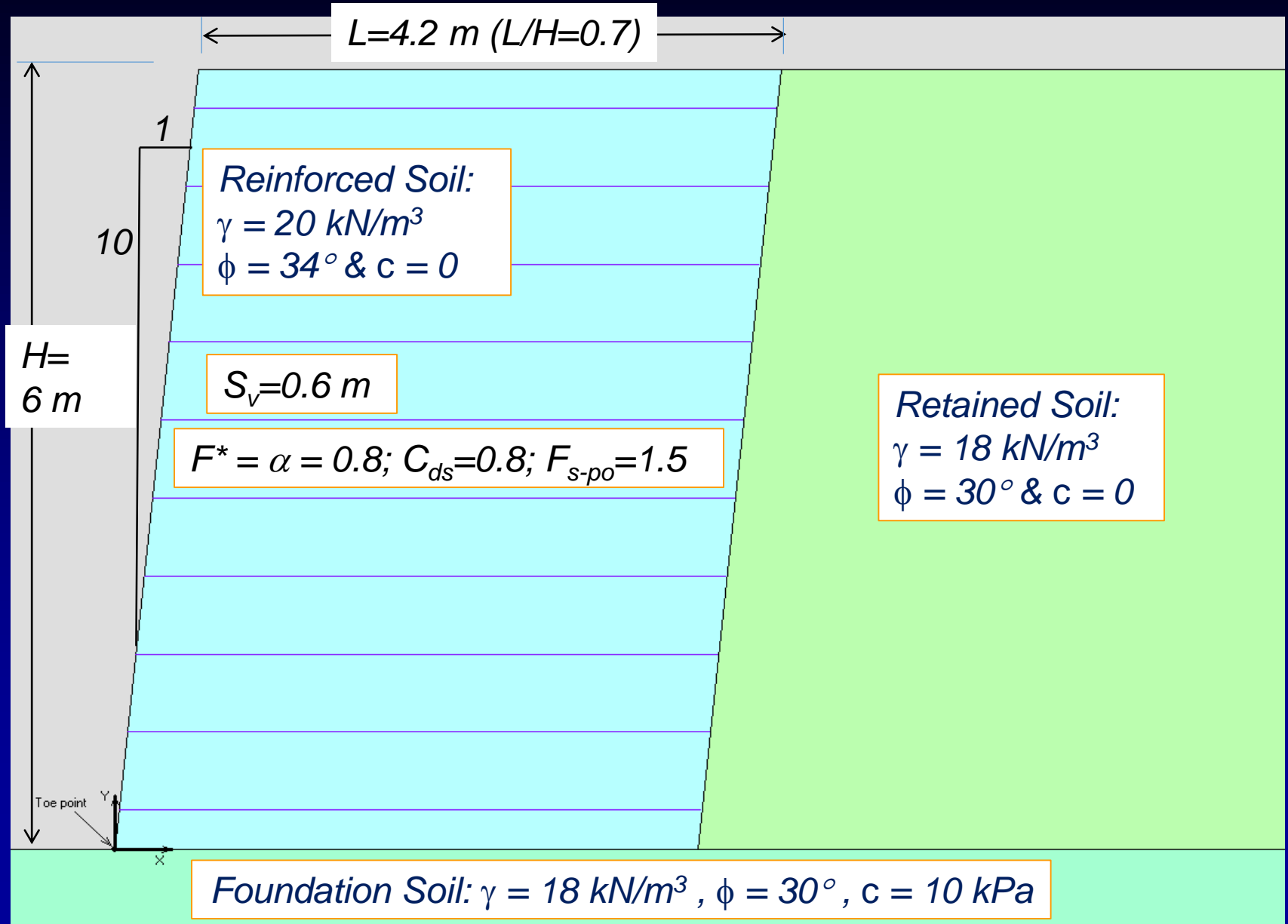
# Why Two Stages: Stage 1 & Stage 2?

- **Stage 1** examines local needs for limit state thus preventing potential overstressing in **Stage 2** by adequately selecting reinforcement → **Stage 1** provides rational basis for selecting LTDS & Facing to be used in **Stage 2**
- **Stage 2** is standard LE in reinforced soil design → Deals with global stability including sliding and foundation's failure → Along critical slip surface all layers are assumed to carry equal  $T_{max}$ , limited by front and back pullout
- **Stage 2** alone does not render connection load

# ***Roadmap of Presentation***

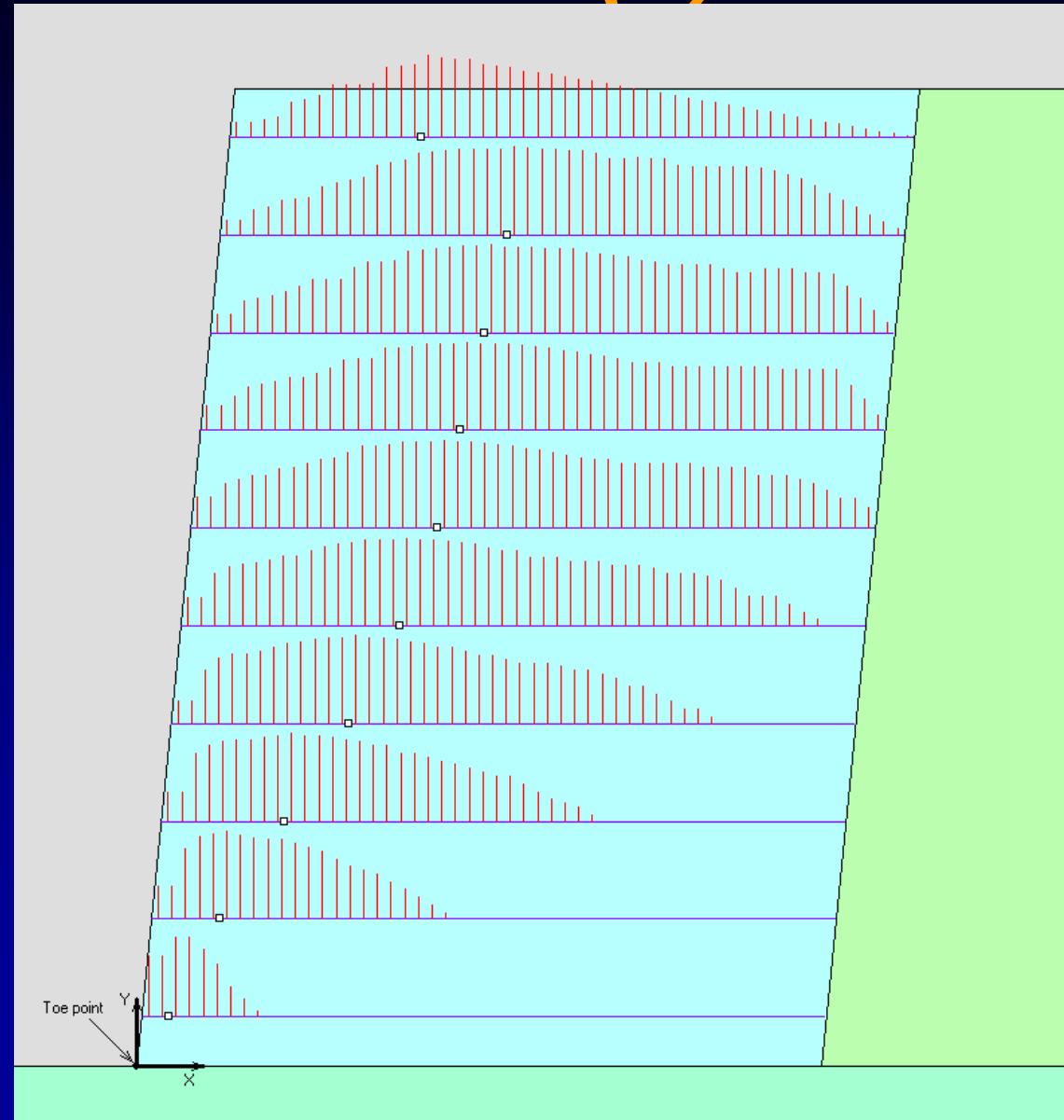
- *Why Limit State analysis is needed?*
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# Benchmark Problem



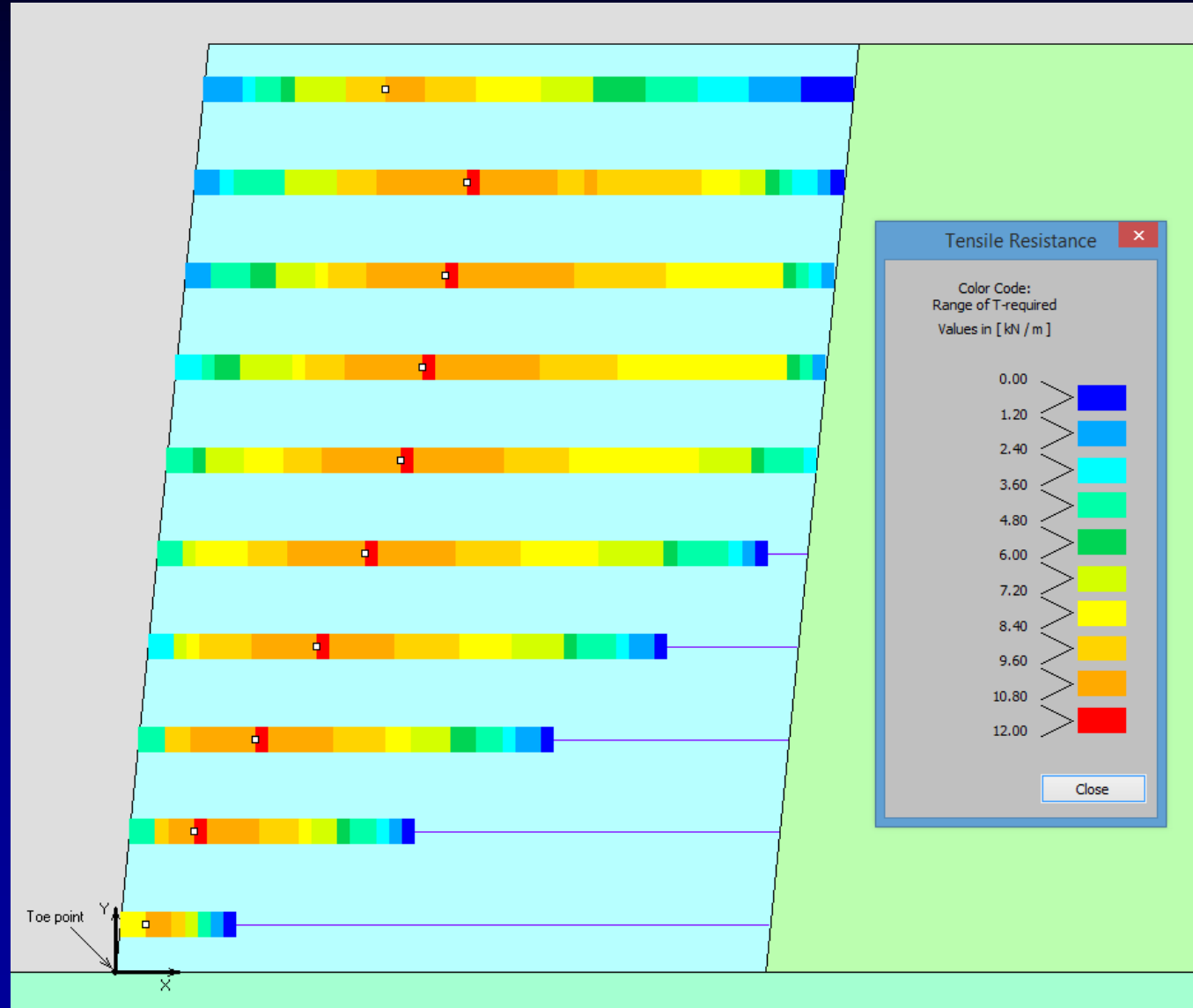
# Computed Distribution of $T(x)$

***Unlike assumptions in current design, the locus of  $T_{max}$  does not develop along a singular slip surface. It is influenced by pullout resistance and compound failures, both of which are directly accounted for.***

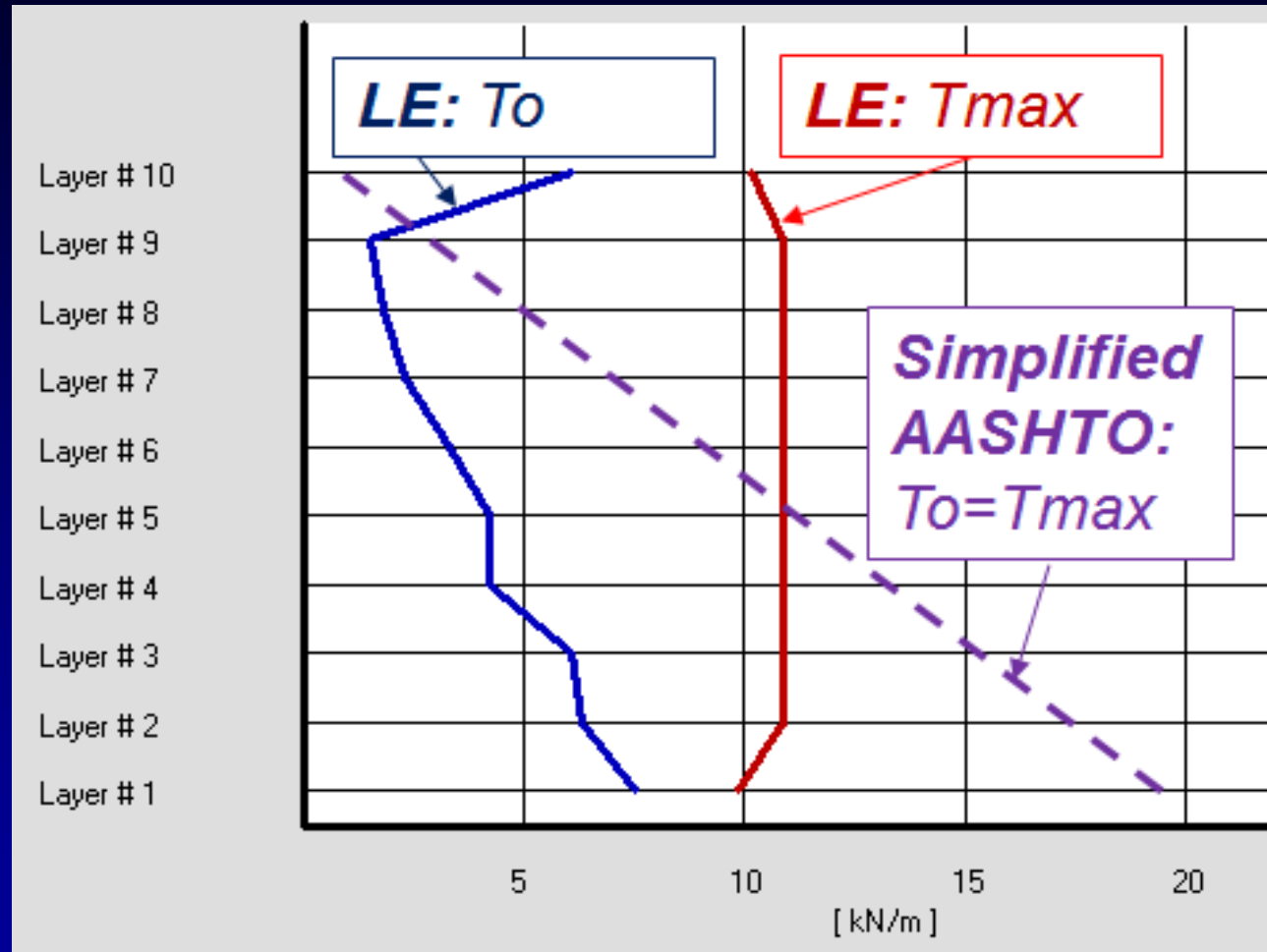


# ***Tension Map (note locus of $T_{max}$ )***

***The mobilization of tension in each reinforcement can be visualized through the Tension Map.***



# $T_{max}$ and $T_o$ Distribution

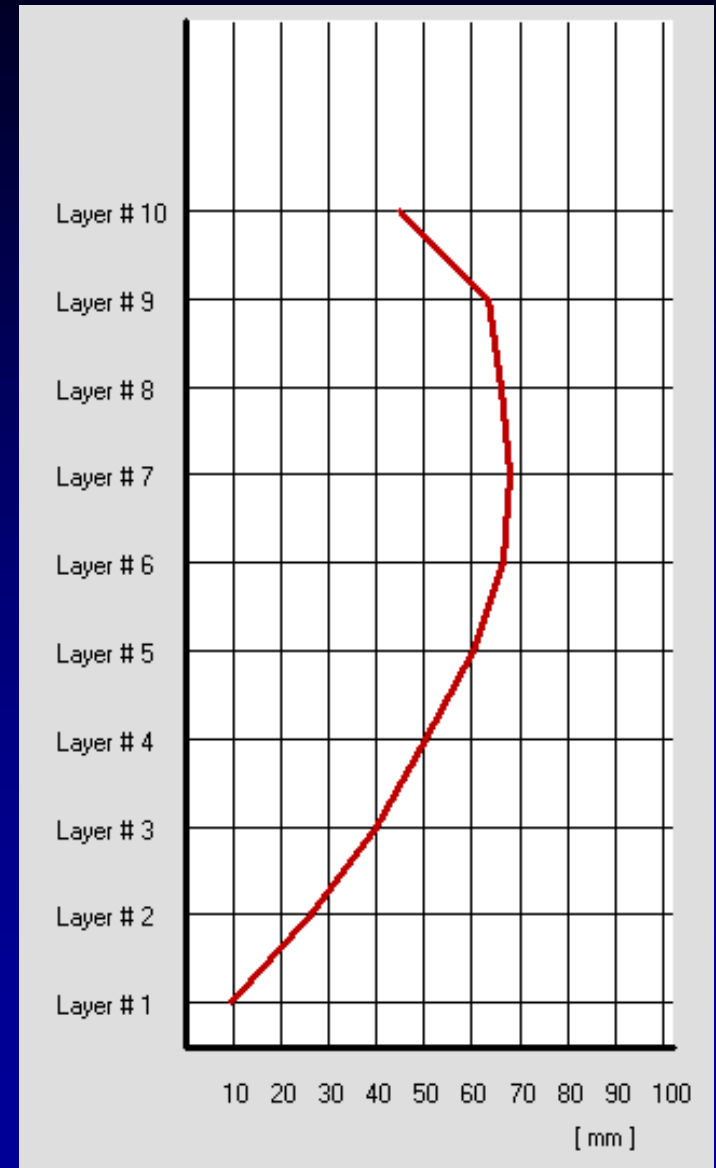


$\max(T_{max})$ : **LE**  $\rightarrow$  10.9 kN/m **AASHTO**  $\rightarrow$  19.3 kN/m

# Horizontal Displacement Distribution

***Knowing the distribution of tensile loading, estimates of lateral displacement can be assessed at a limit state.***

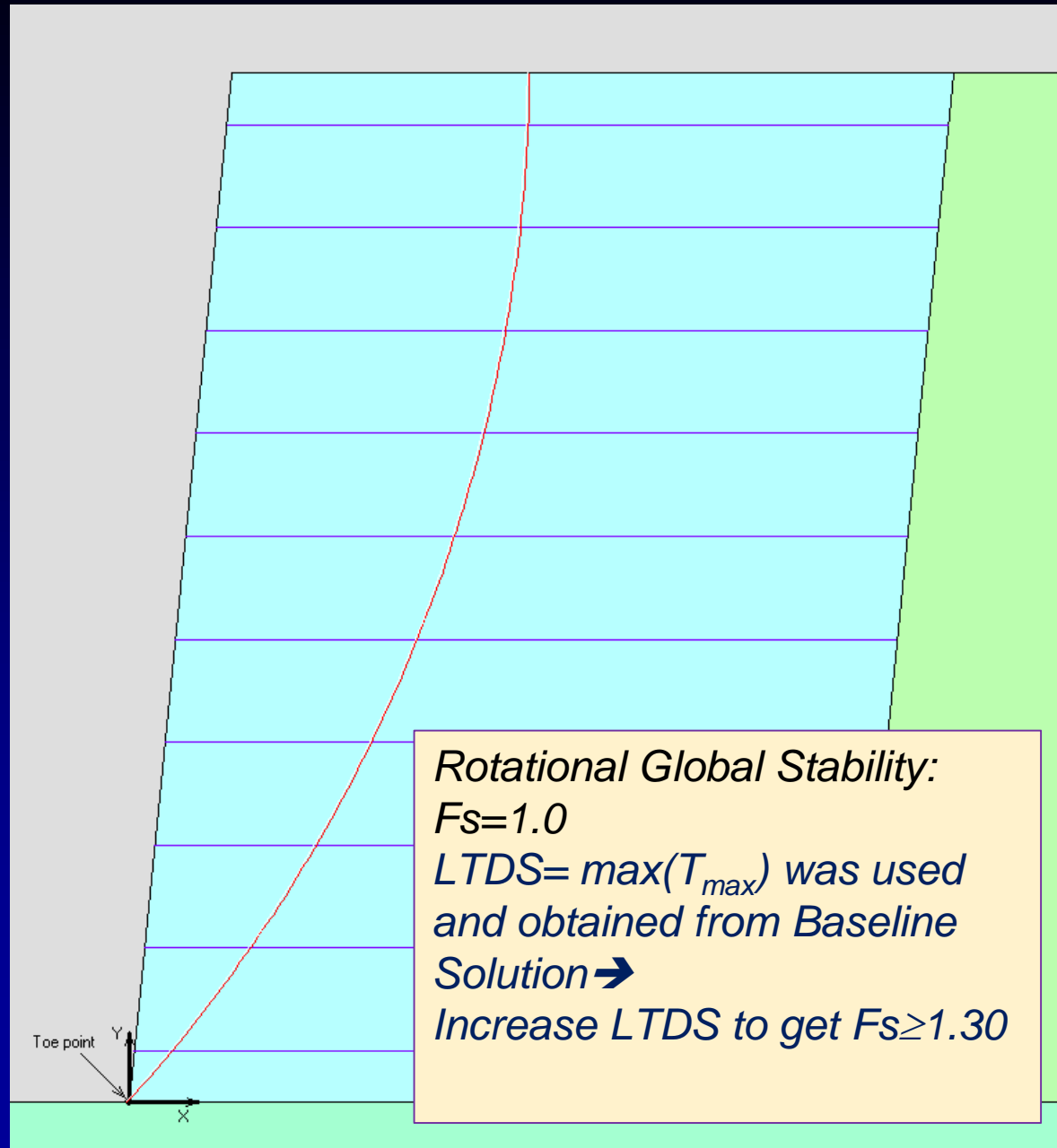
***Shown is the computed face profile for reinforcement stiffness of  $J=500 \text{ kN/m}$  (Note that it is for  $F_s=1.0$ ; i.e., soil strength is fully mobilized)***



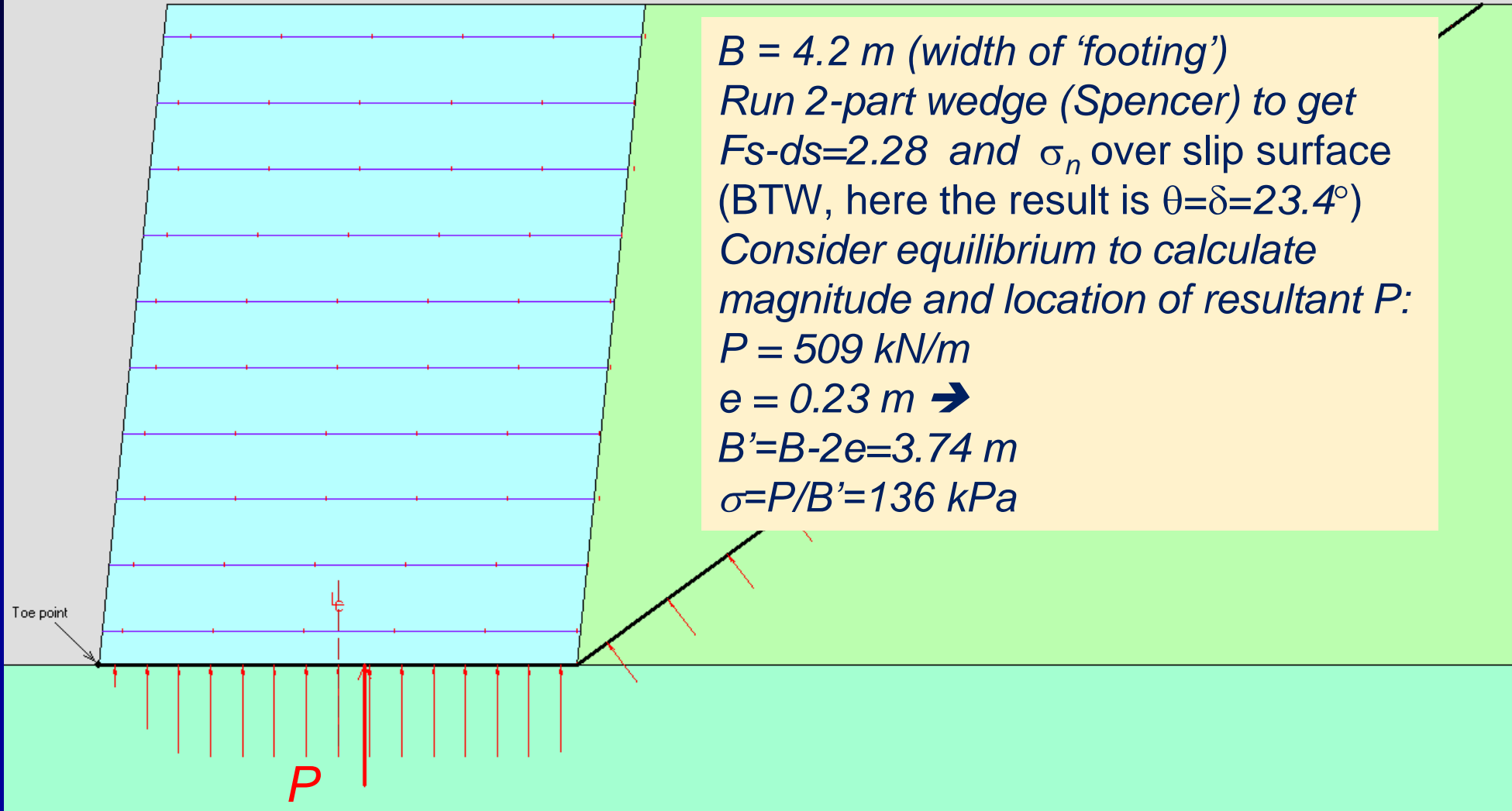
# Global Stability

**Global stability (Stage 2)** is assessed here using *Bishop's method*.

**The reinforcement strength was determined from Stage 1 (Baseline Solution)**

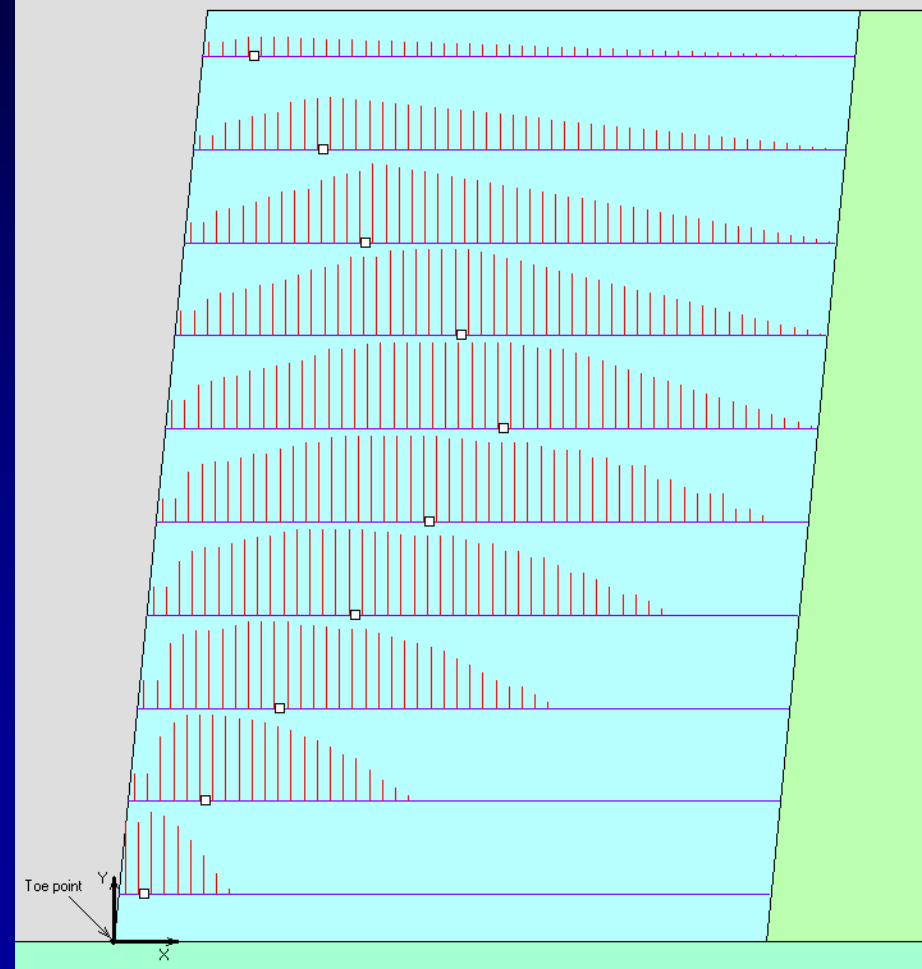
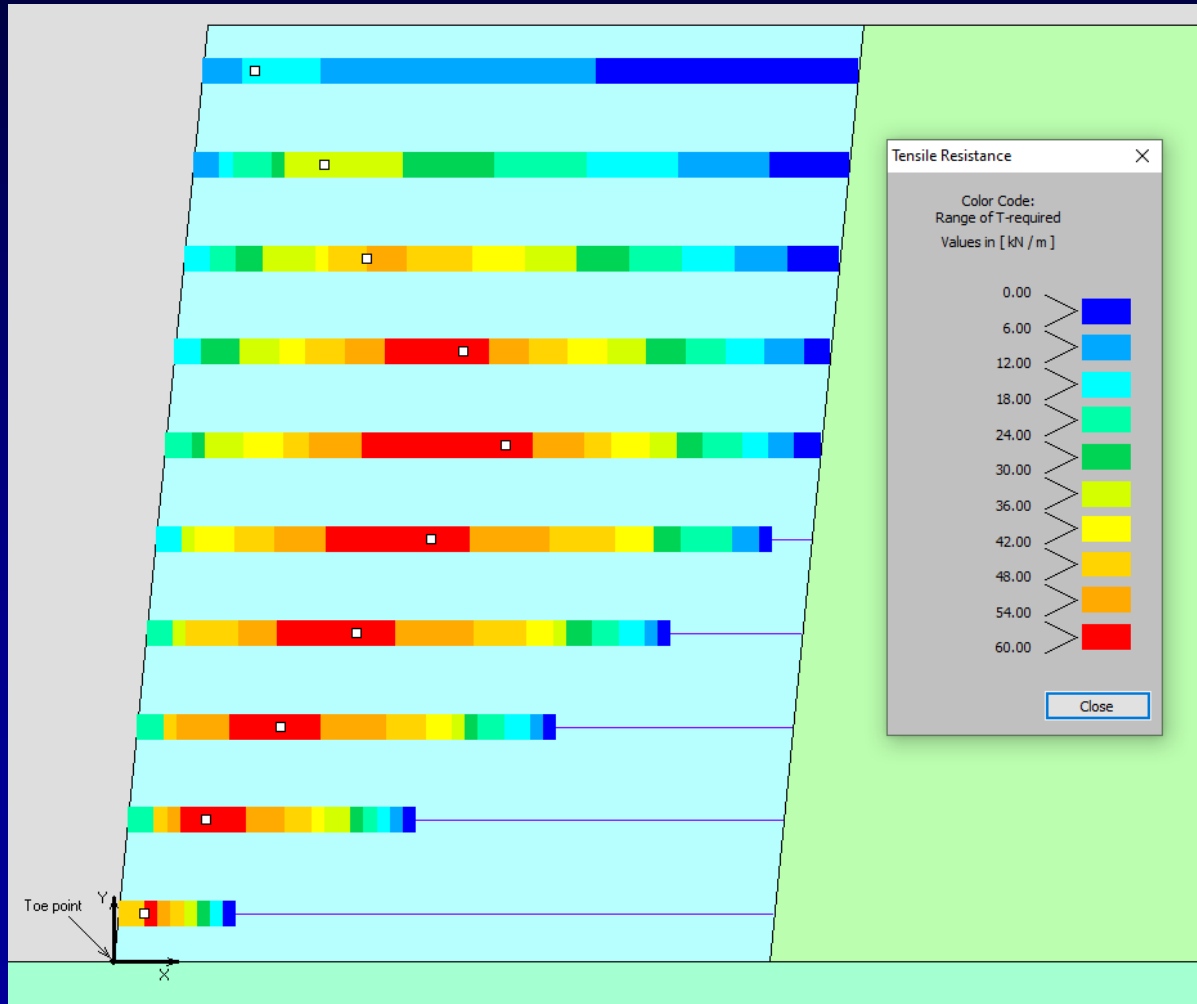


# Data for Bearing Capacity and Eccentricity Derived from Rigorous Direct Sliding

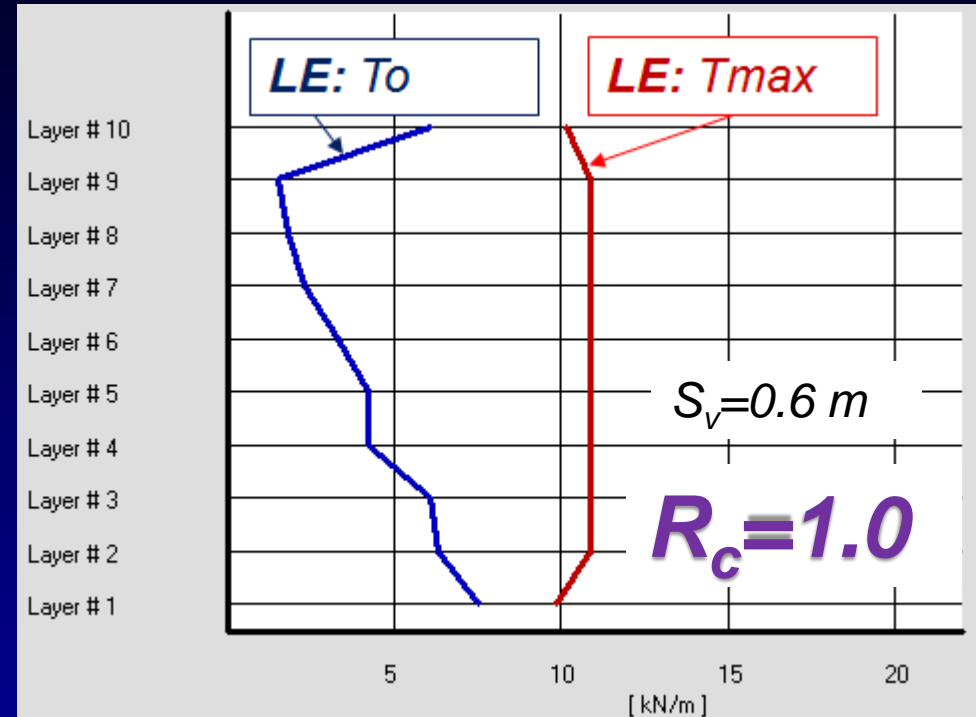
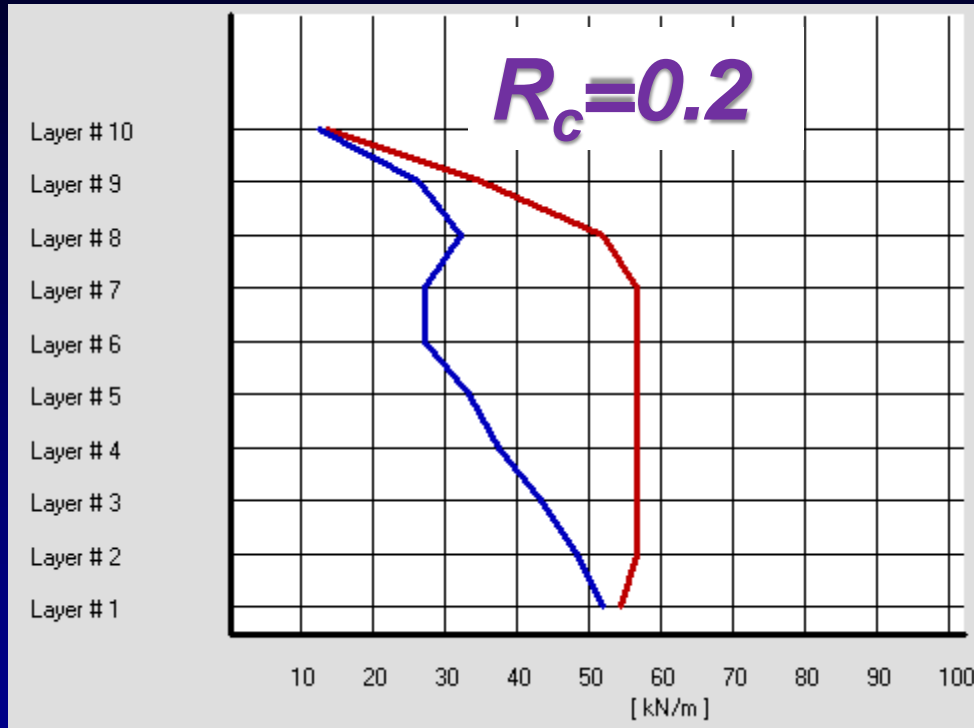


# Computed Distribution of $T(x)$ : Straps Having Coverage Ratio of $R_c=0.2$

*Note impact of rear pullout*



# Effects of $R_c$ on $T_{max}$ and $T_o$

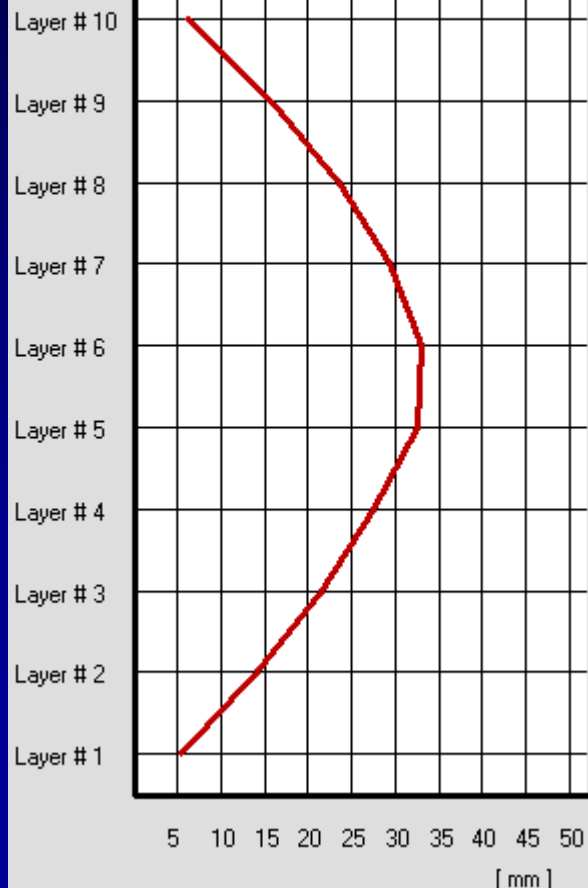


**Note the different drawings scale for  $T_{max}$  and  $T_o$ .**  
**Due to smaller front and rear pullout resistance:**

1.  $T_{max}$  in upper layers is small
2.  $T_o$  is relatively large in most layers

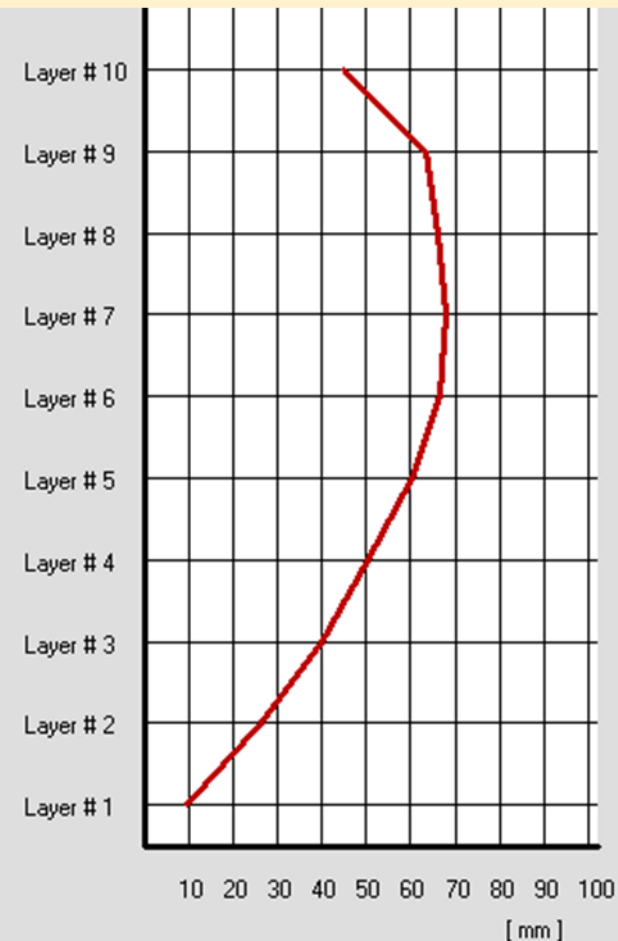
# Effects of Reduced $R_c$ on Displacements

**For straps,  $J$  was taken as 5,000 kN/m**

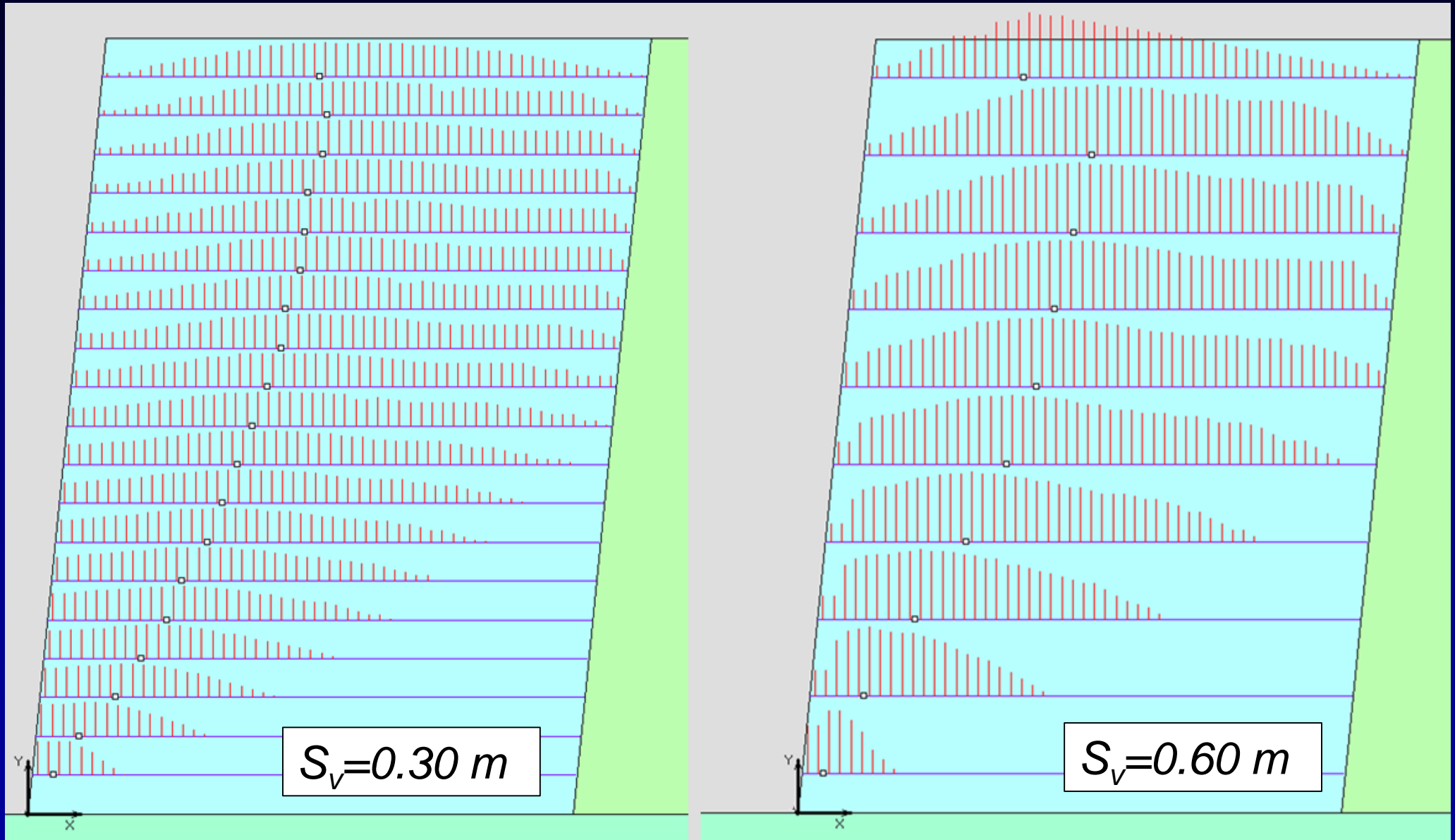


**$\Delta$  profile for  $J=500$  kN/m**

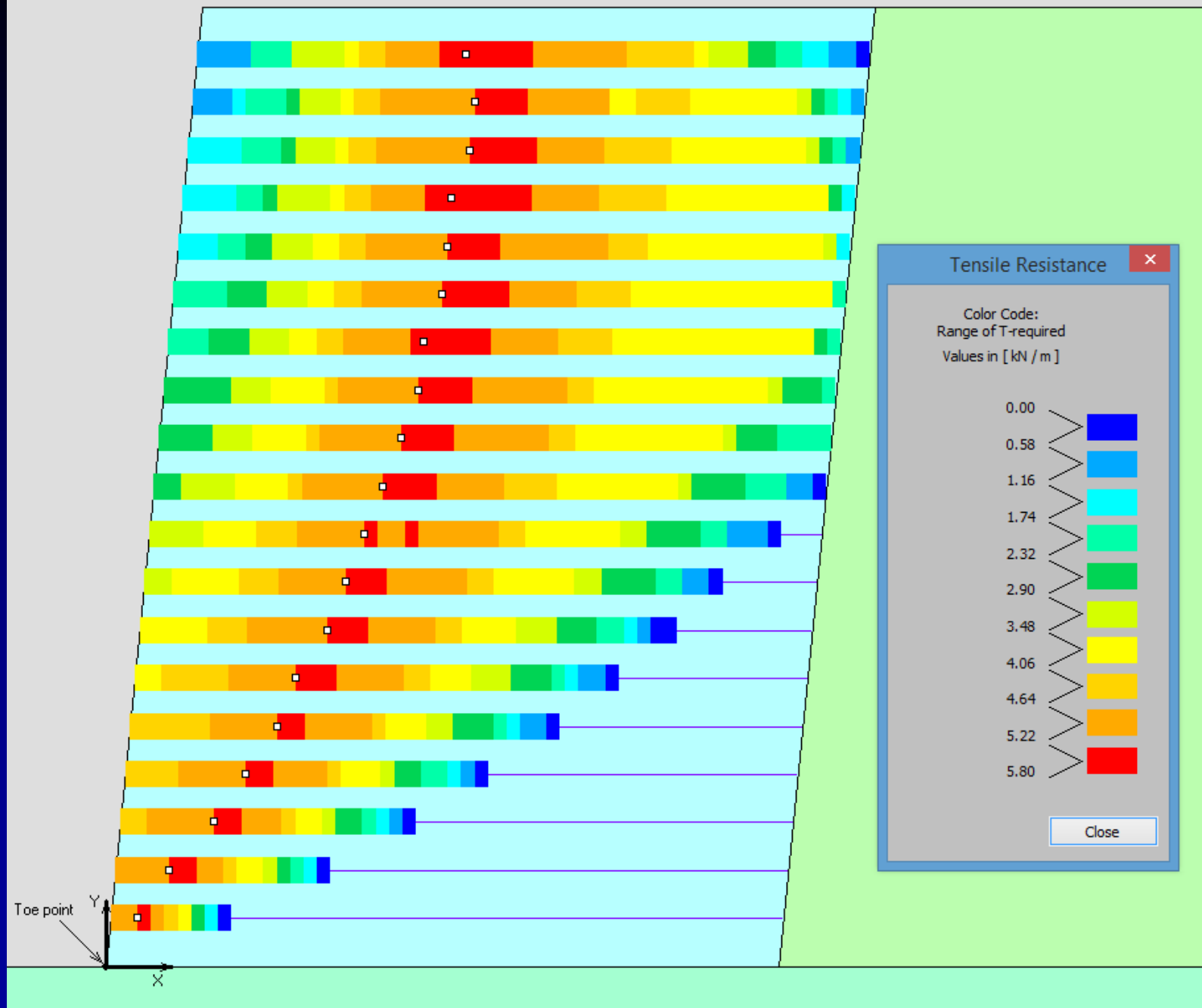
**(For  $F_s=1.0$ ; i.e., soil strength is fully mobilized)**



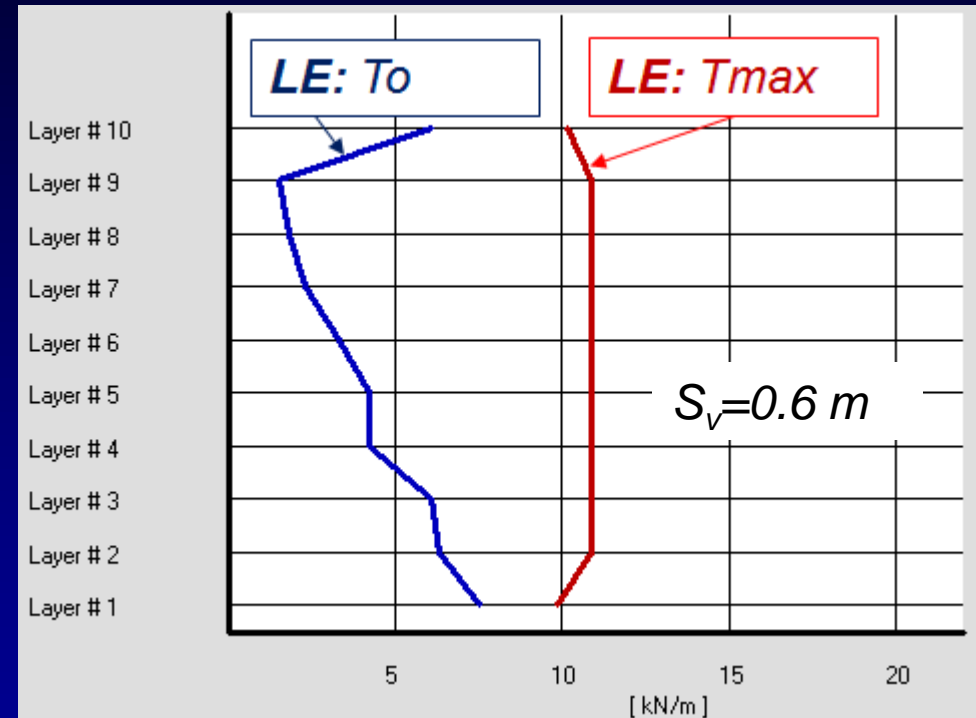
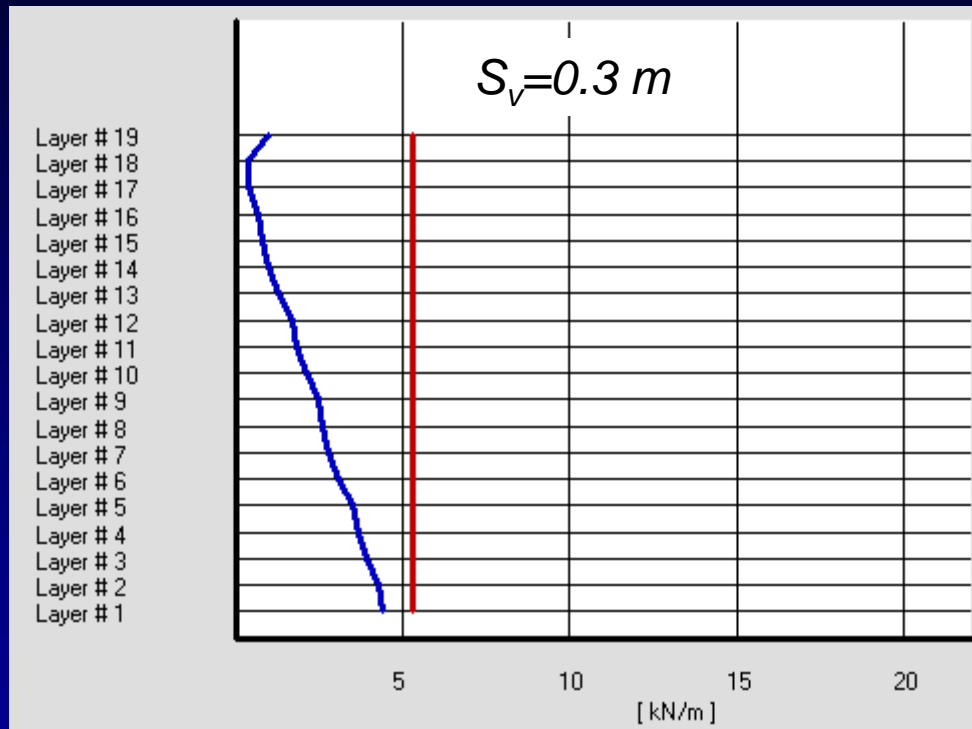
# Close Reinforcement Spacing – $T_{max}$ Decreases



# Tension Map $S_v=0.3m$

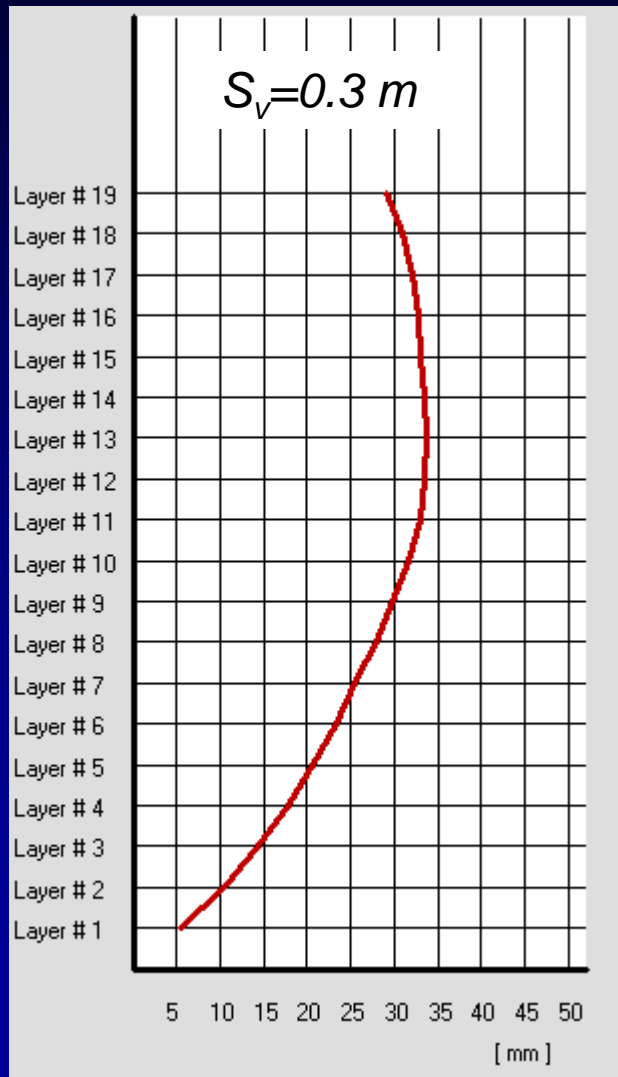


# Effects of Reduced $S_v$ : $T_{max}$ and $T_o$

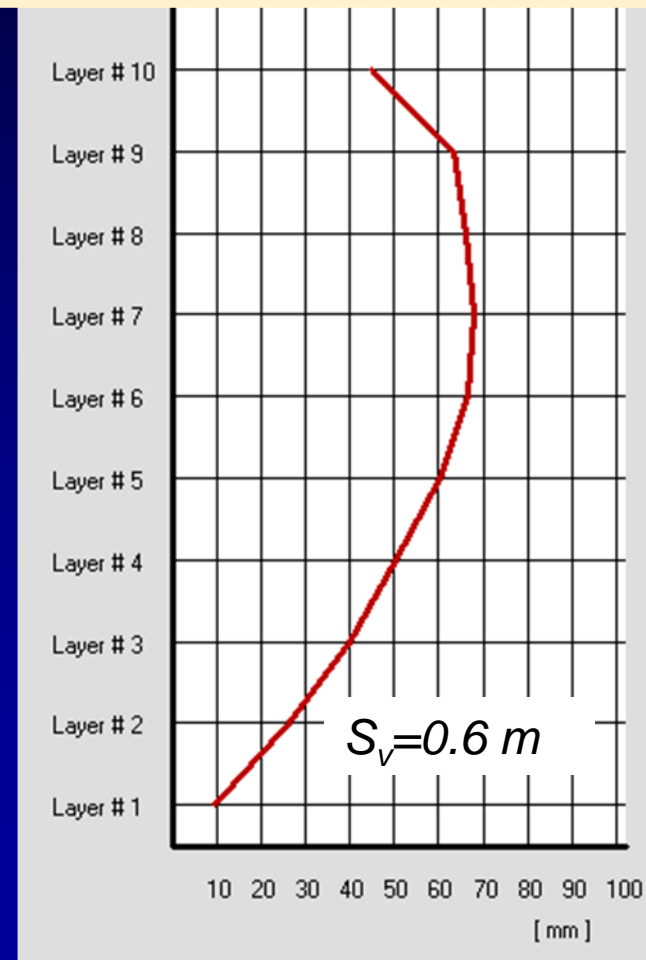


**Generally,  $T_o$  drops nonlinearly when  $S_v$  decreases.  
Reason: Front-end pullout resistance remains constant while  $T_{req}$  drops proportional to spacing**

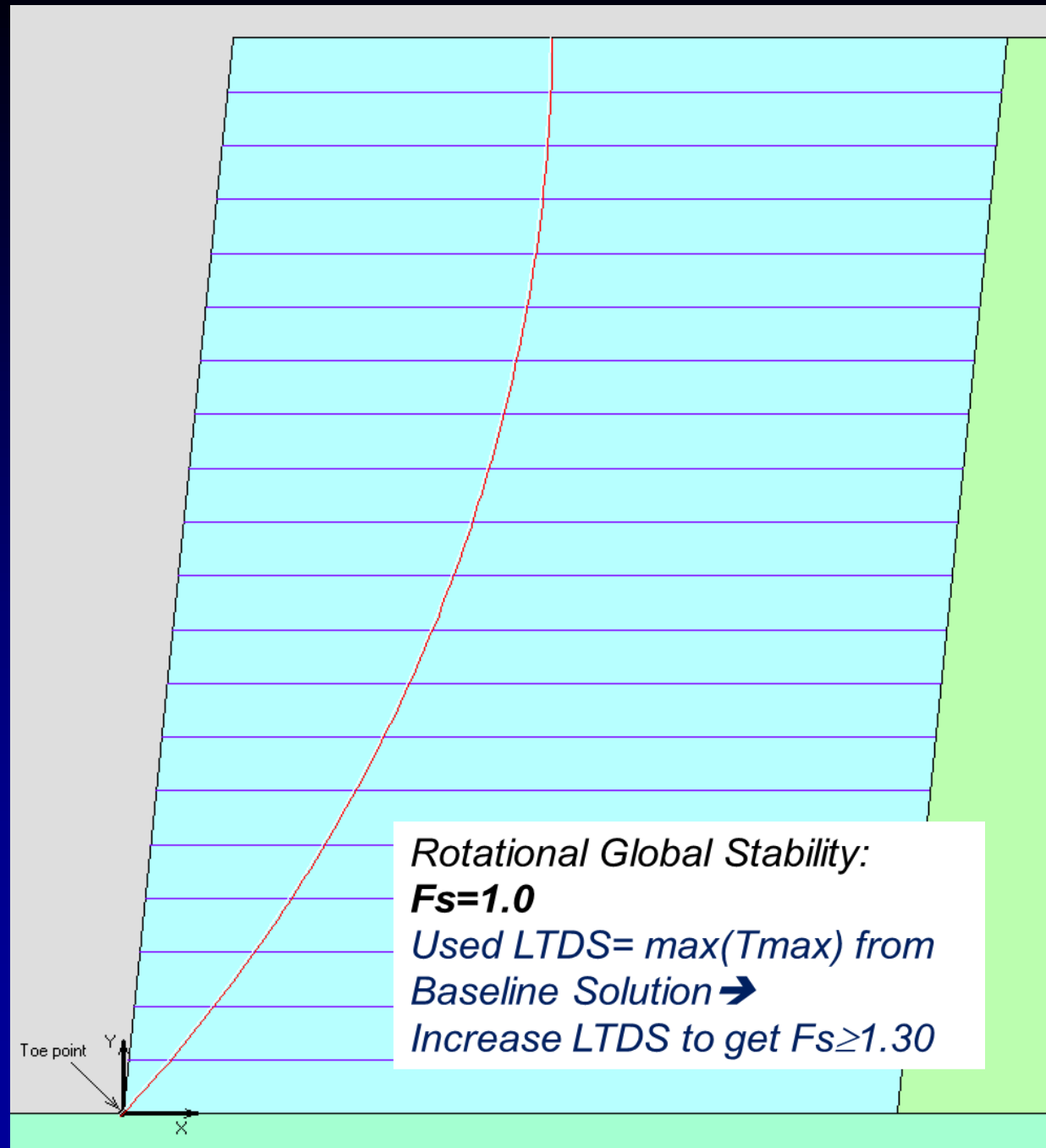
# Effects of Reduced $S_v$ on Displacements



$\Delta$  profile for  $J=500 \text{ kN/m}$   
(For  $F_s=1.0$ ; i.e., soil strength is fully mobilized)

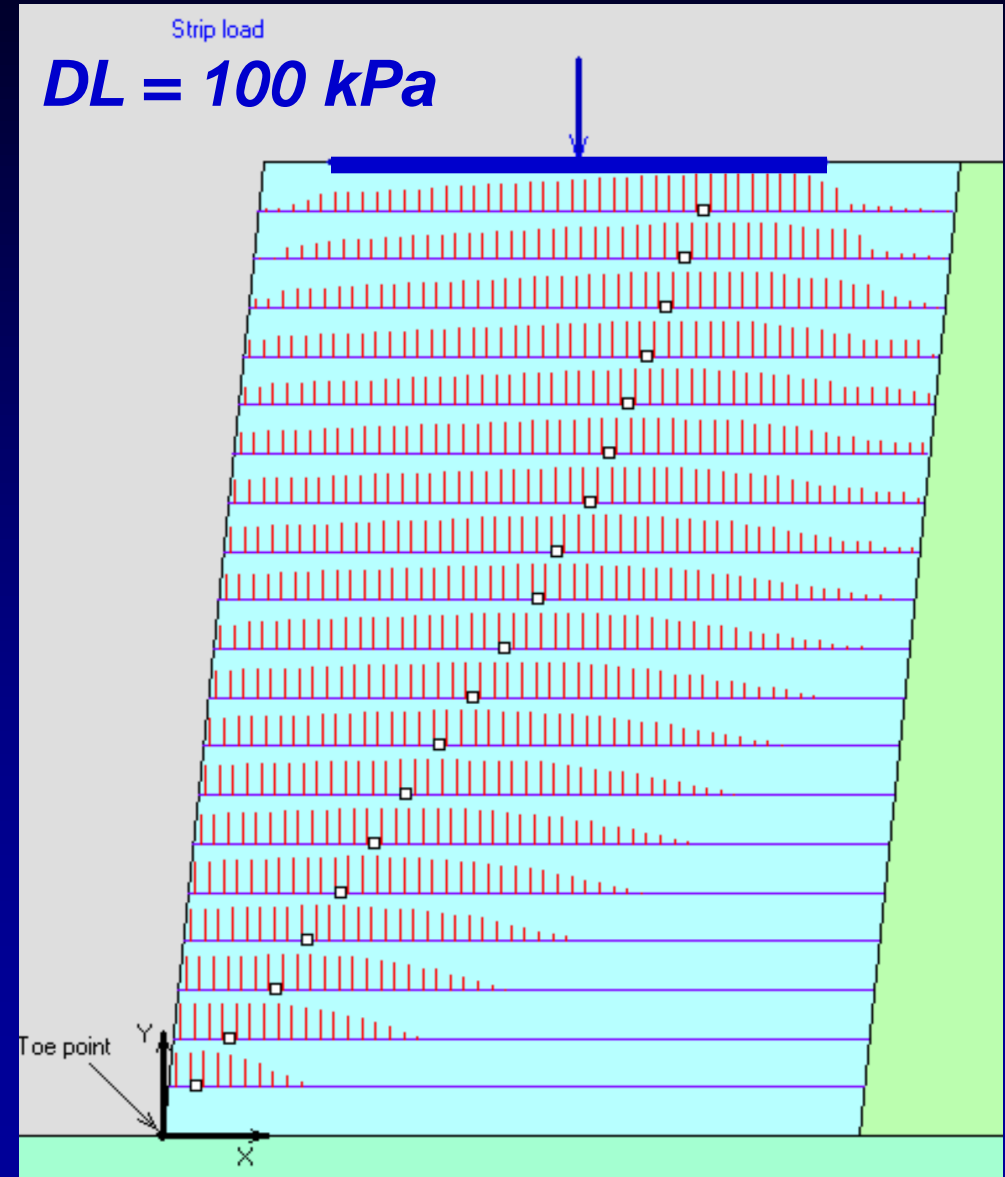
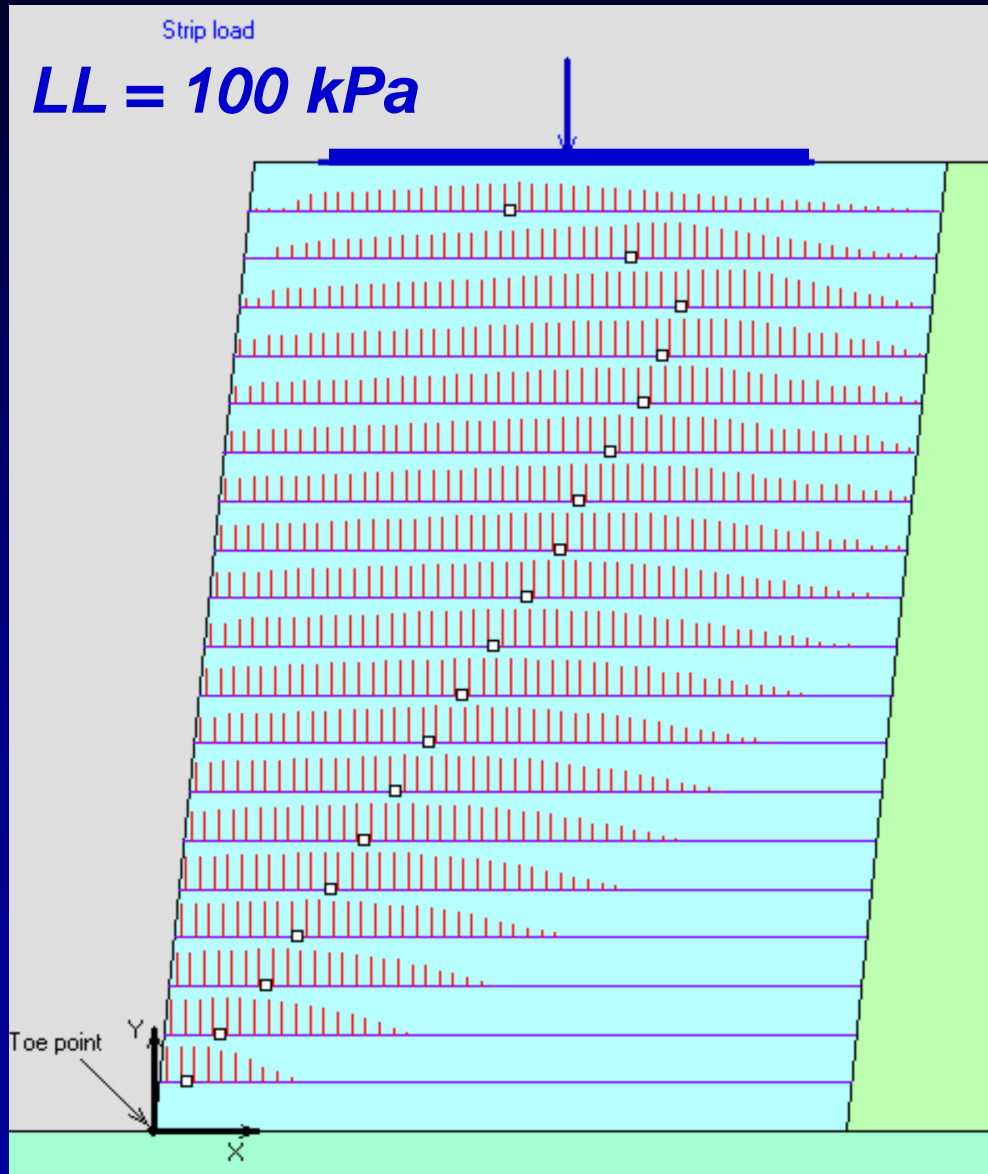


# Global Stability



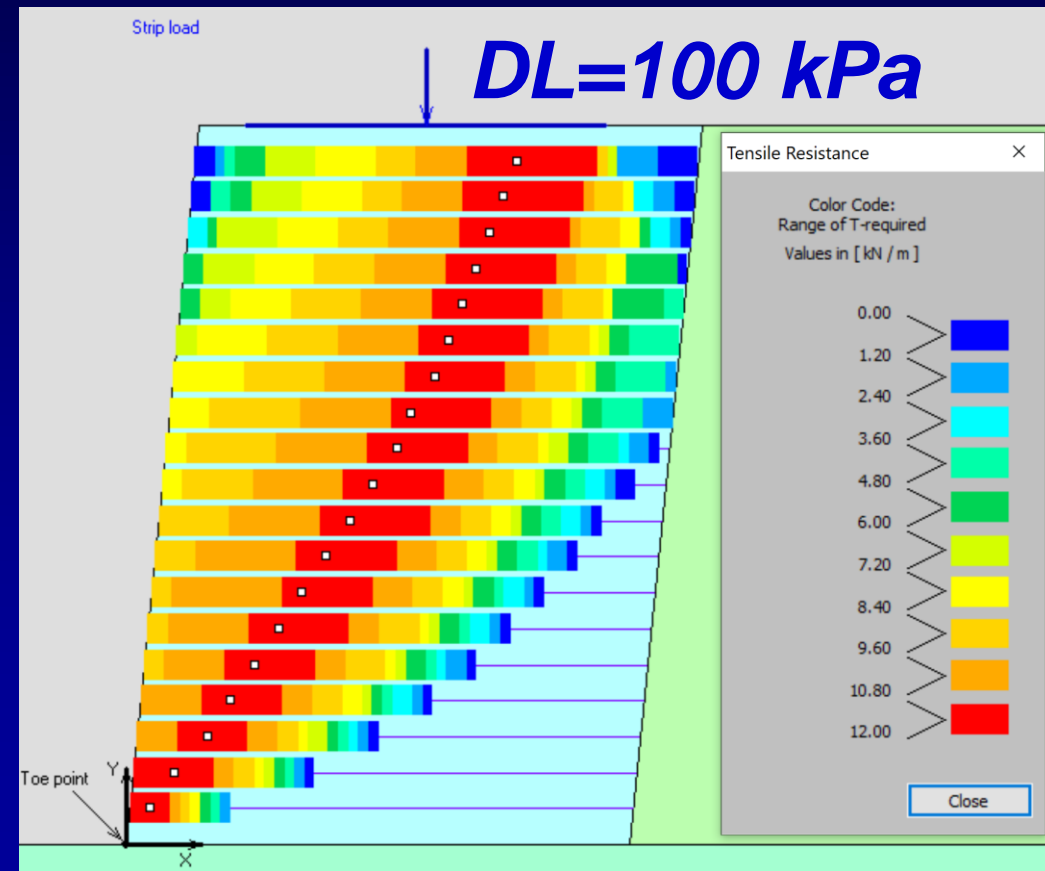
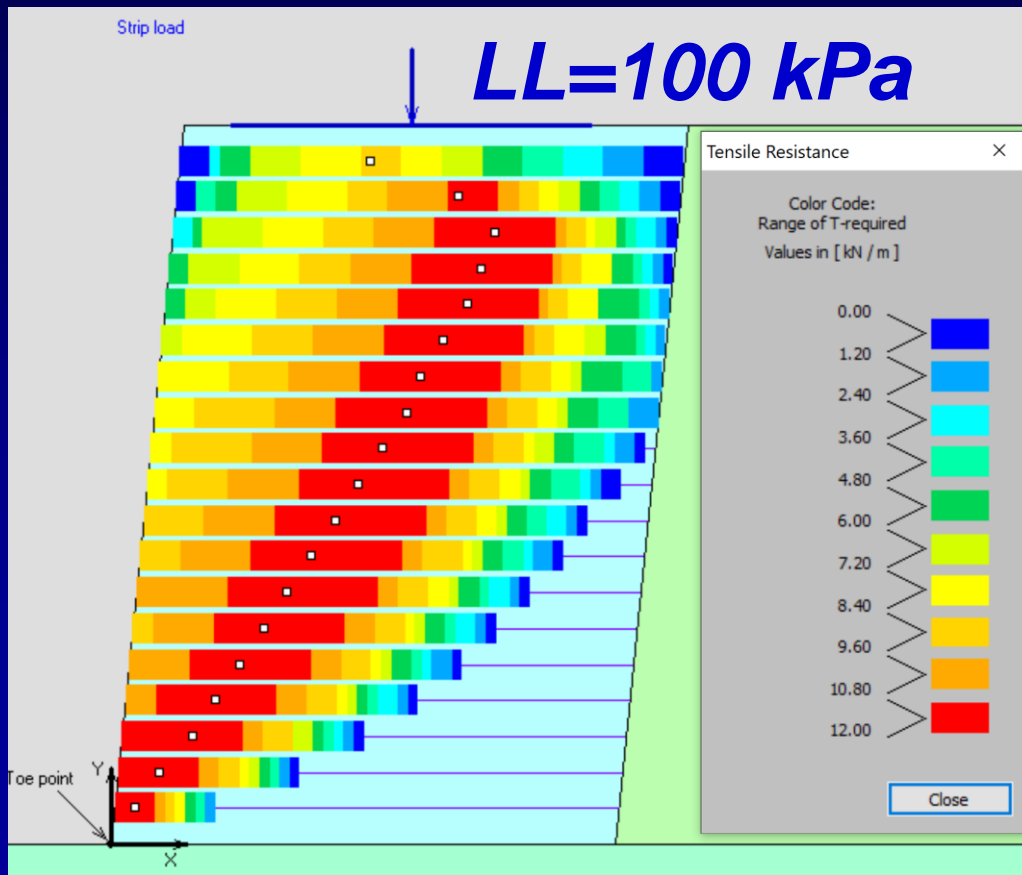
# Close Spacing: Dead and Live Loads

(LL does not affect front and rear pullout; DL affects)

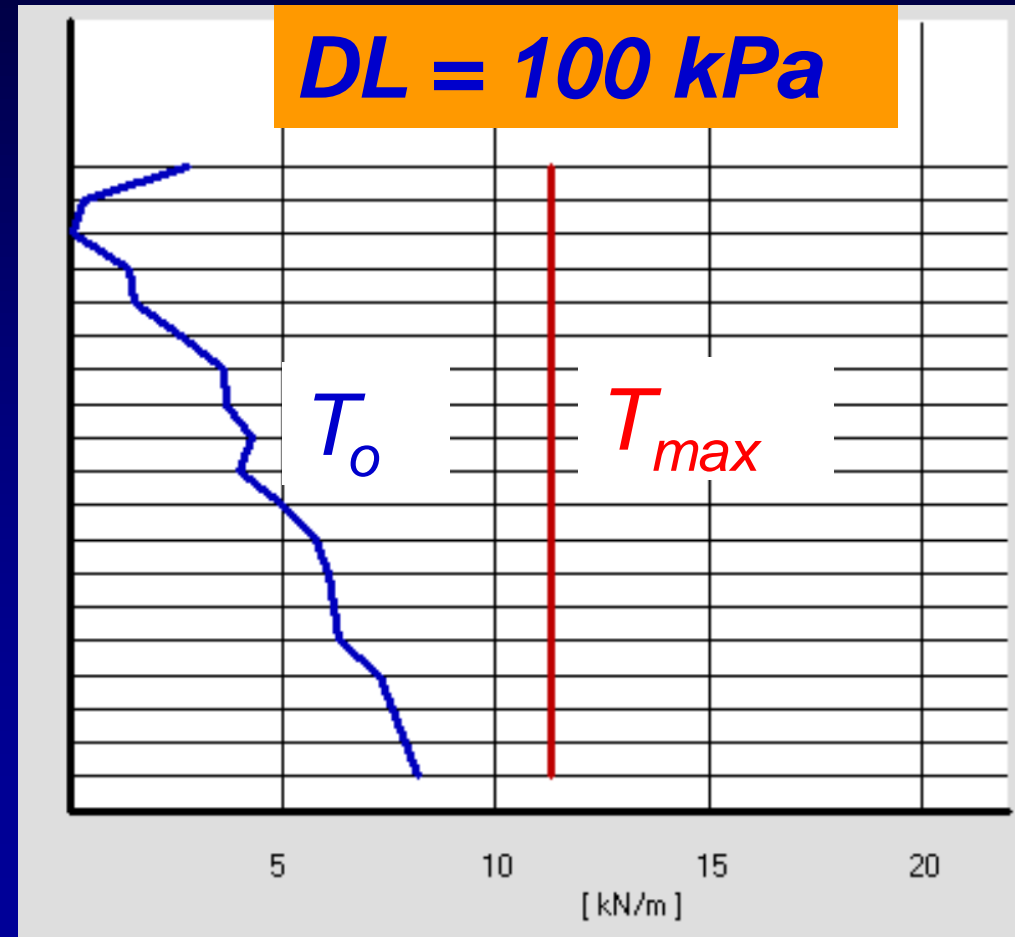
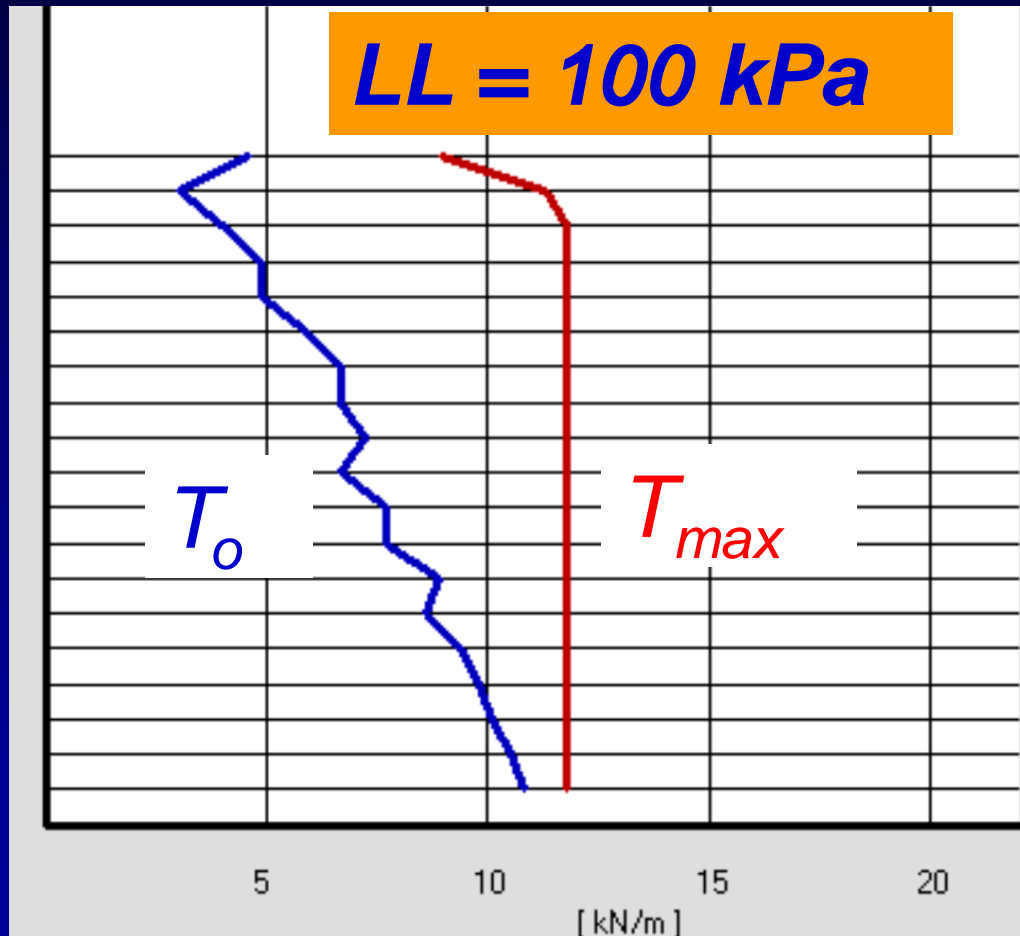


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(LL does not affect front and rear pullout; DL affects)

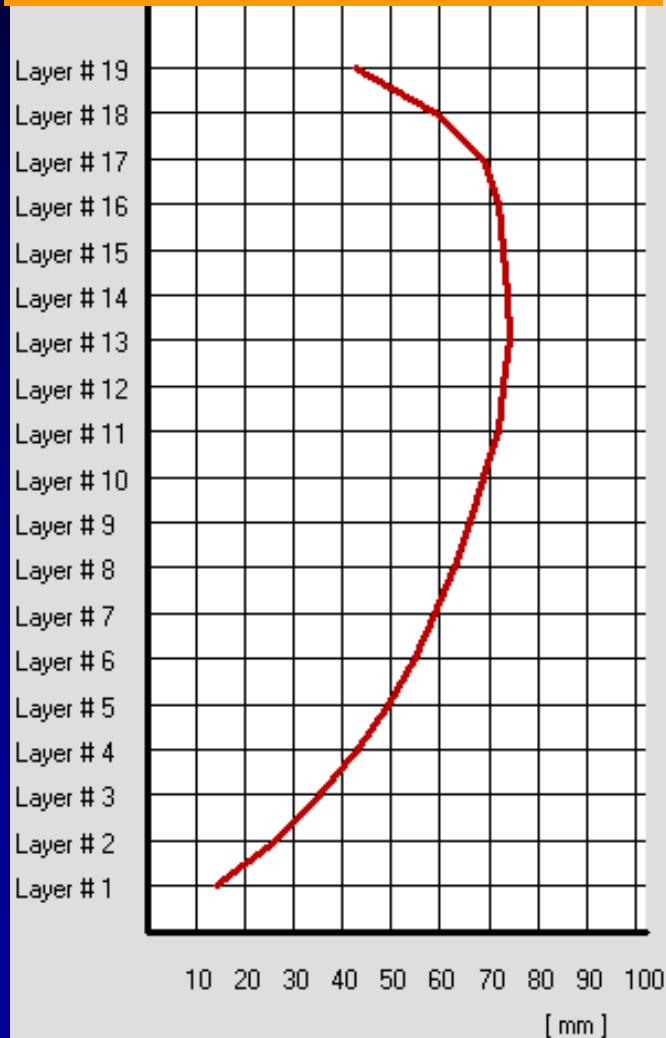


# Close Spacing: Dead and Live Loads (note effects on $T_o$ )

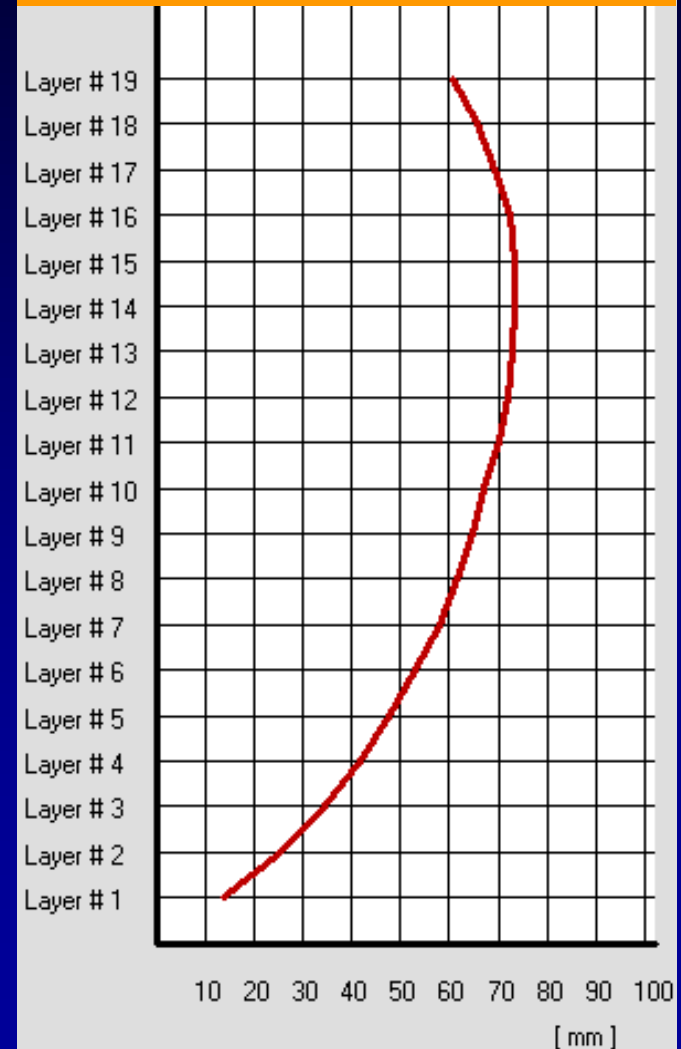


# $S_v = 0.30$ m, DL and LL: Displacements

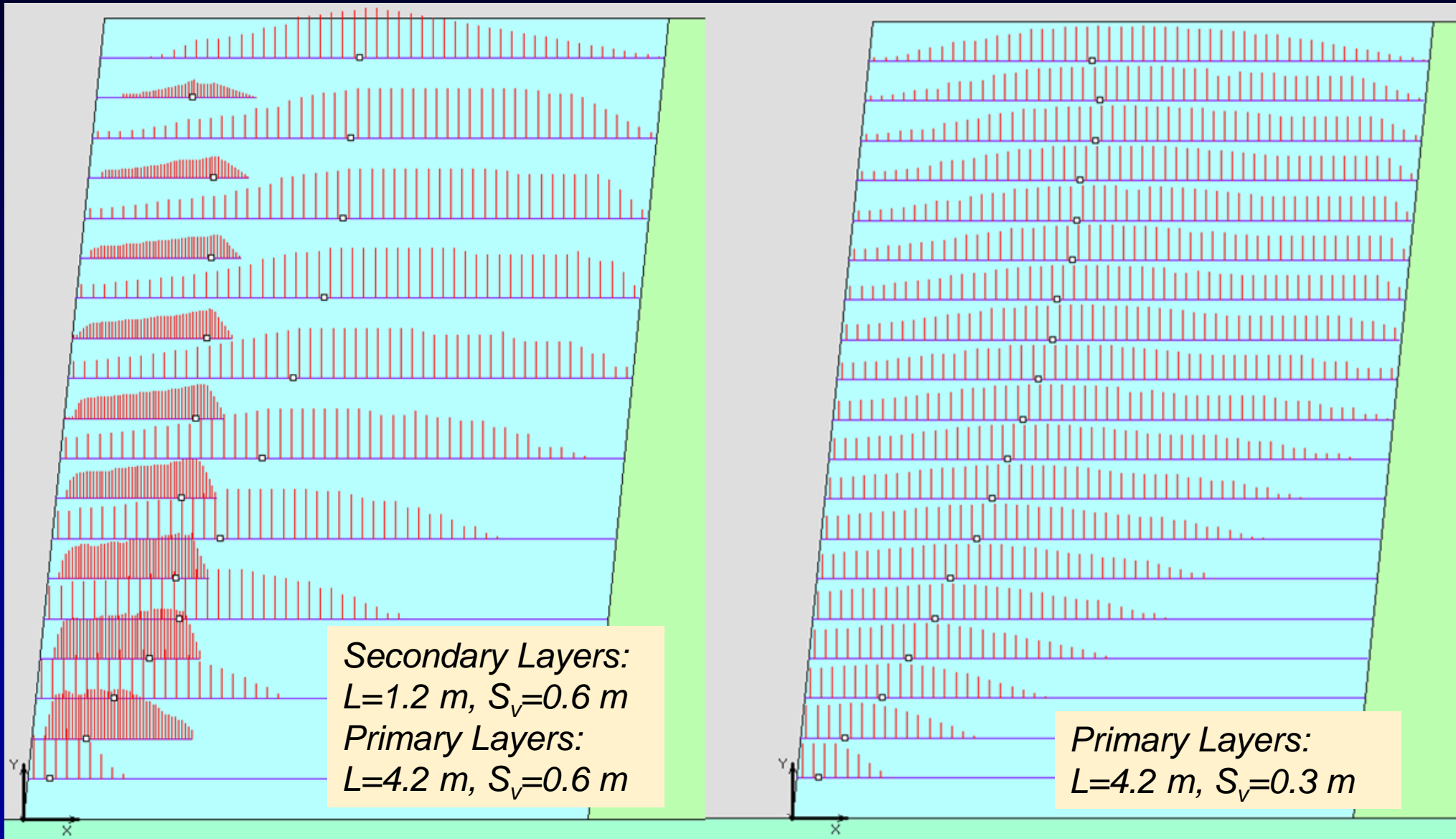
**LL = 100 kPa**



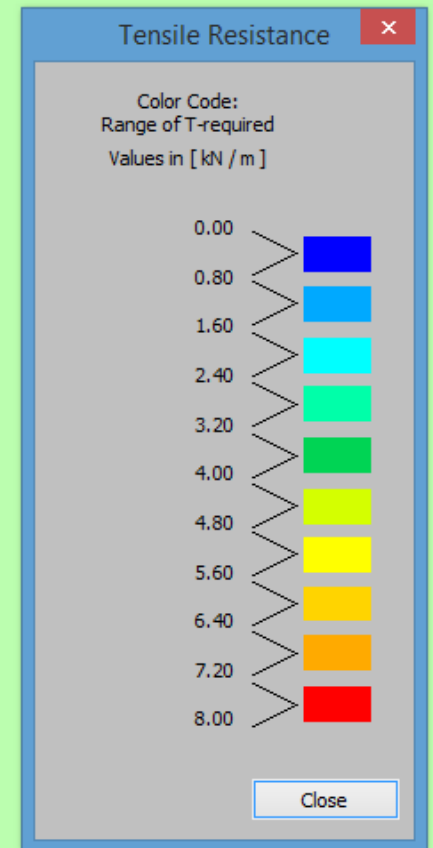
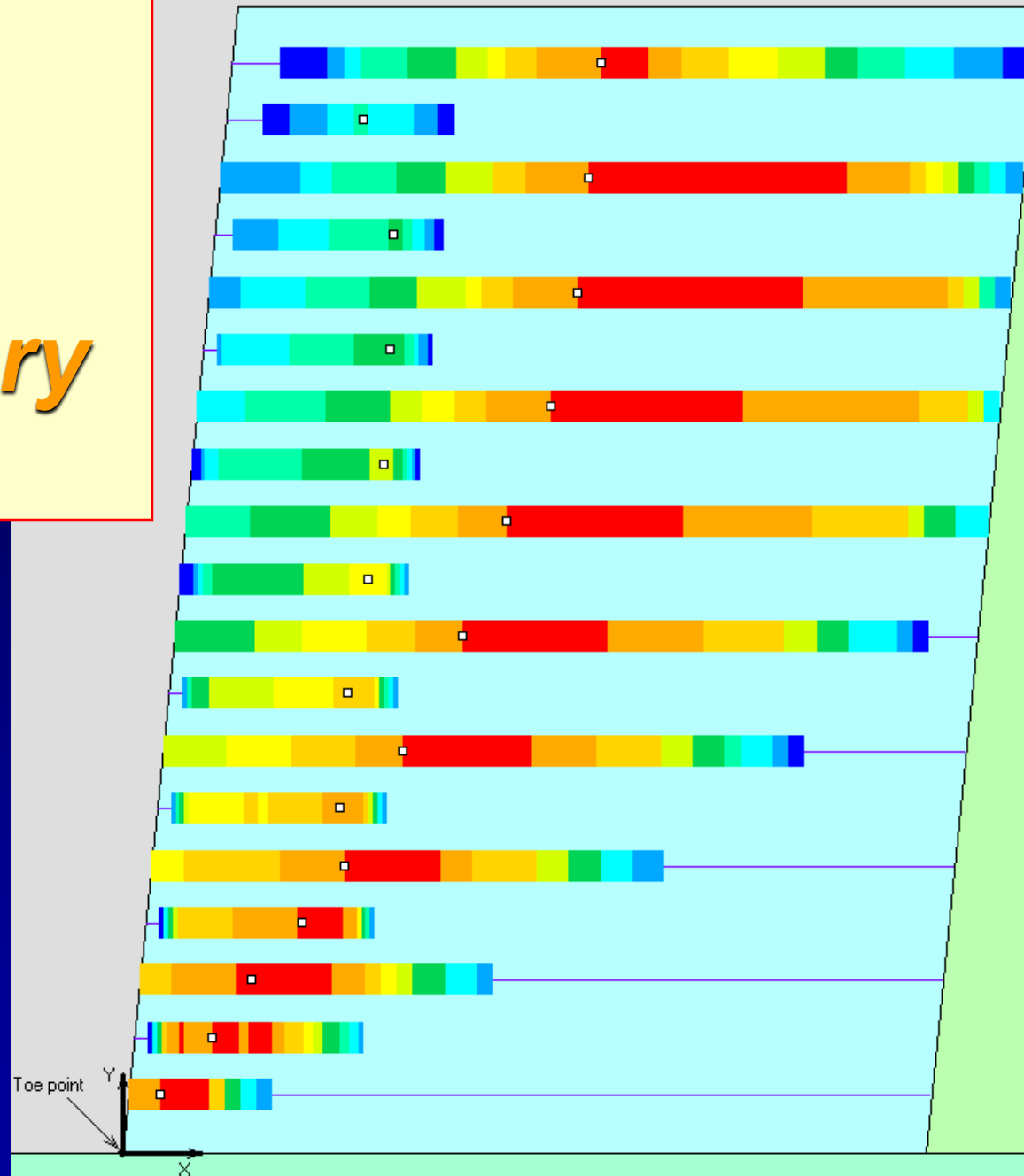
**DL = 100 kPa**



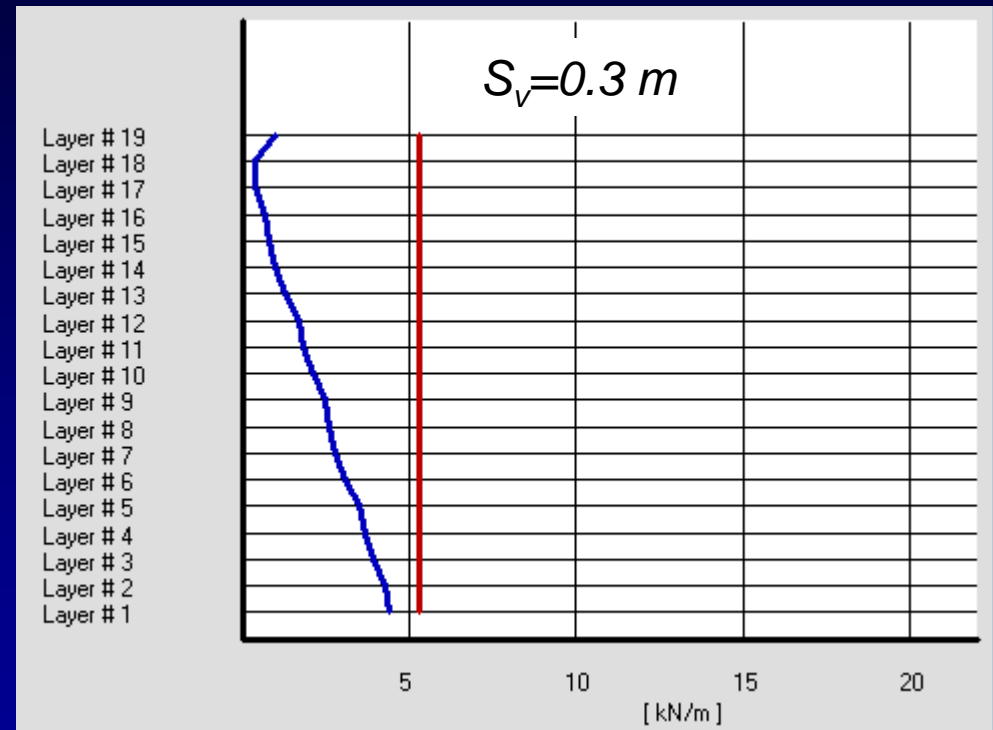
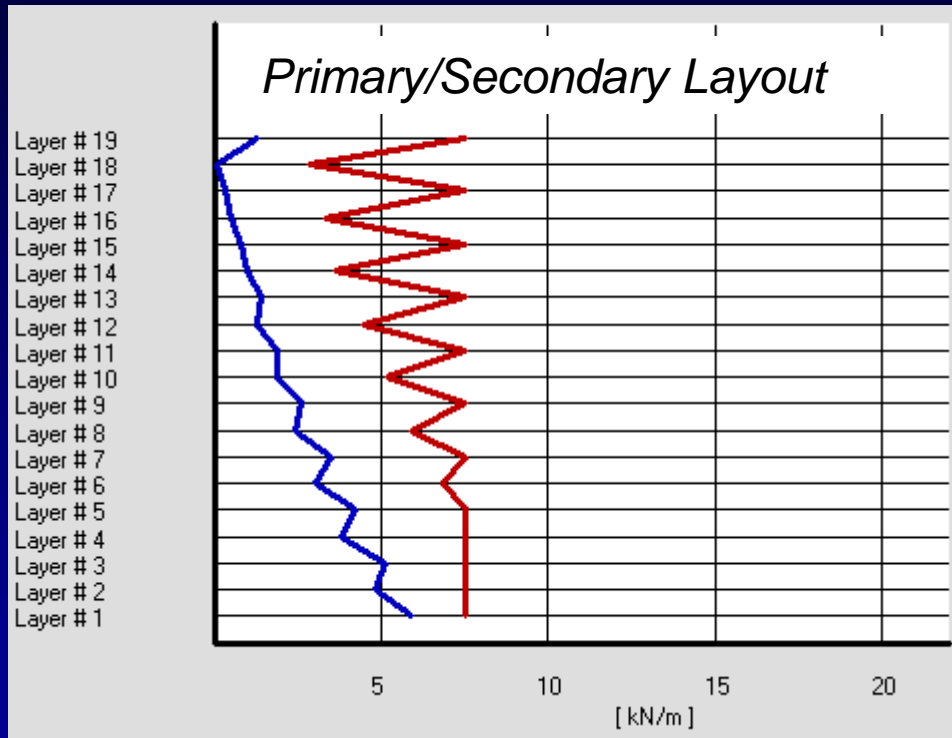
# Effects of Secondary Layers



# Tension Map and Secondary Layers

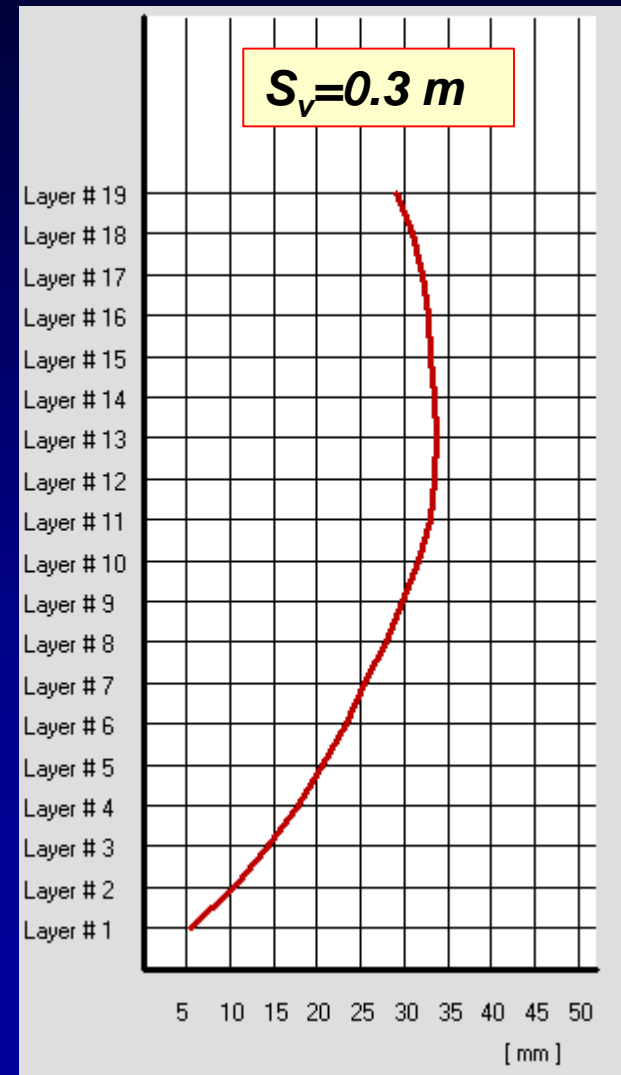
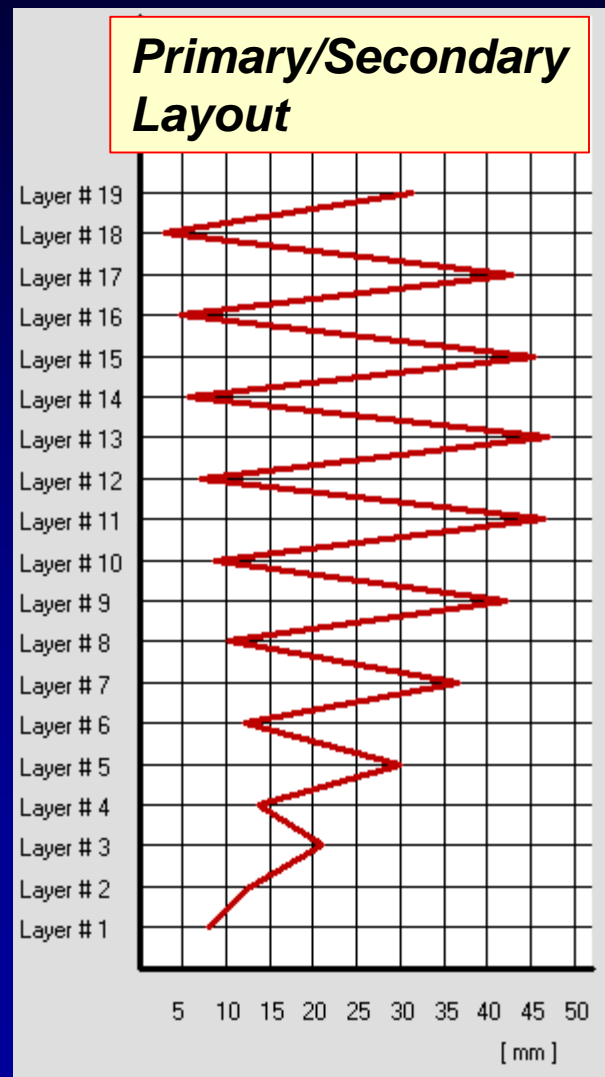


# $T_{max}$ and $T_o$ : Secondary versus Close Spacing

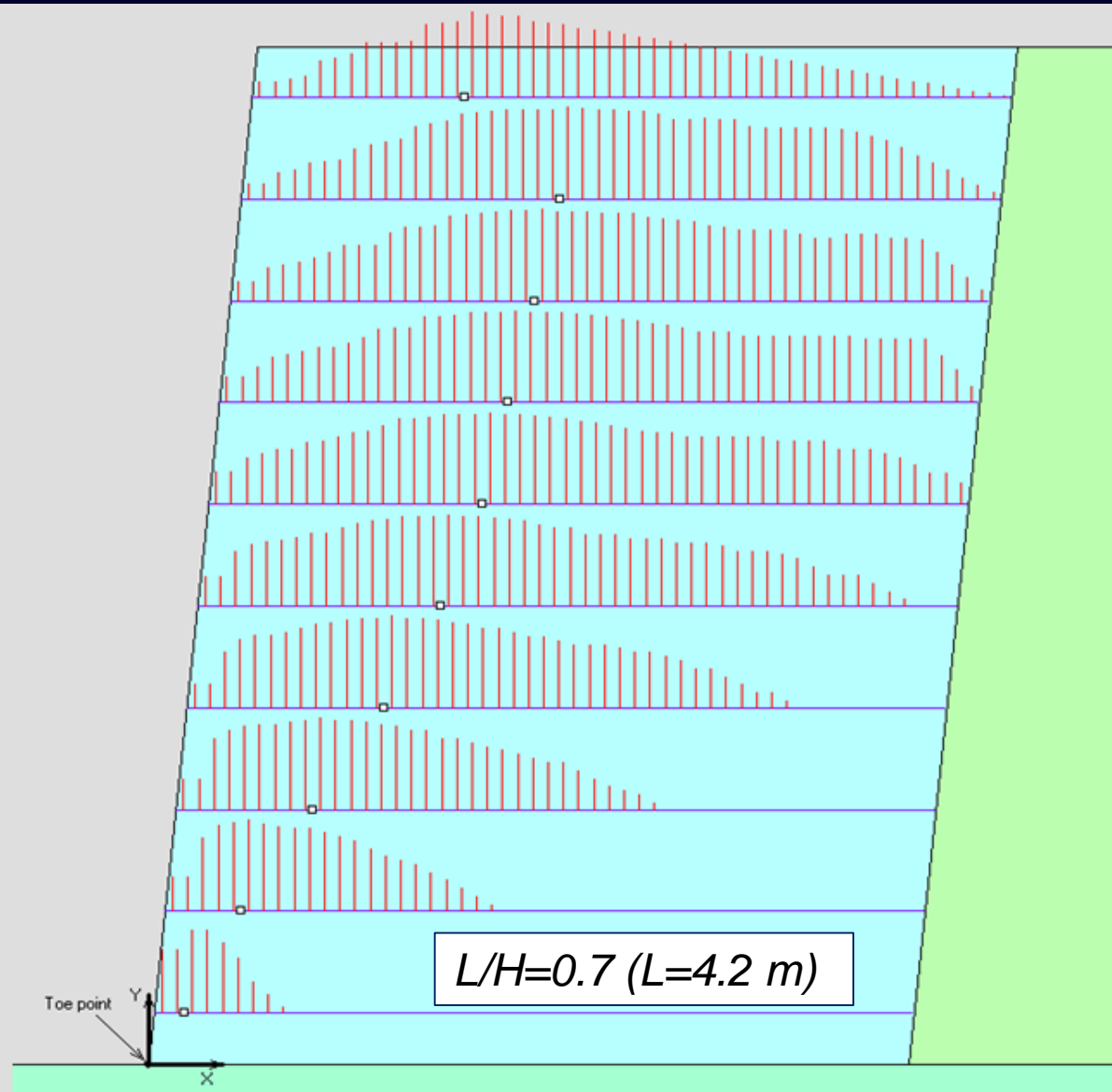
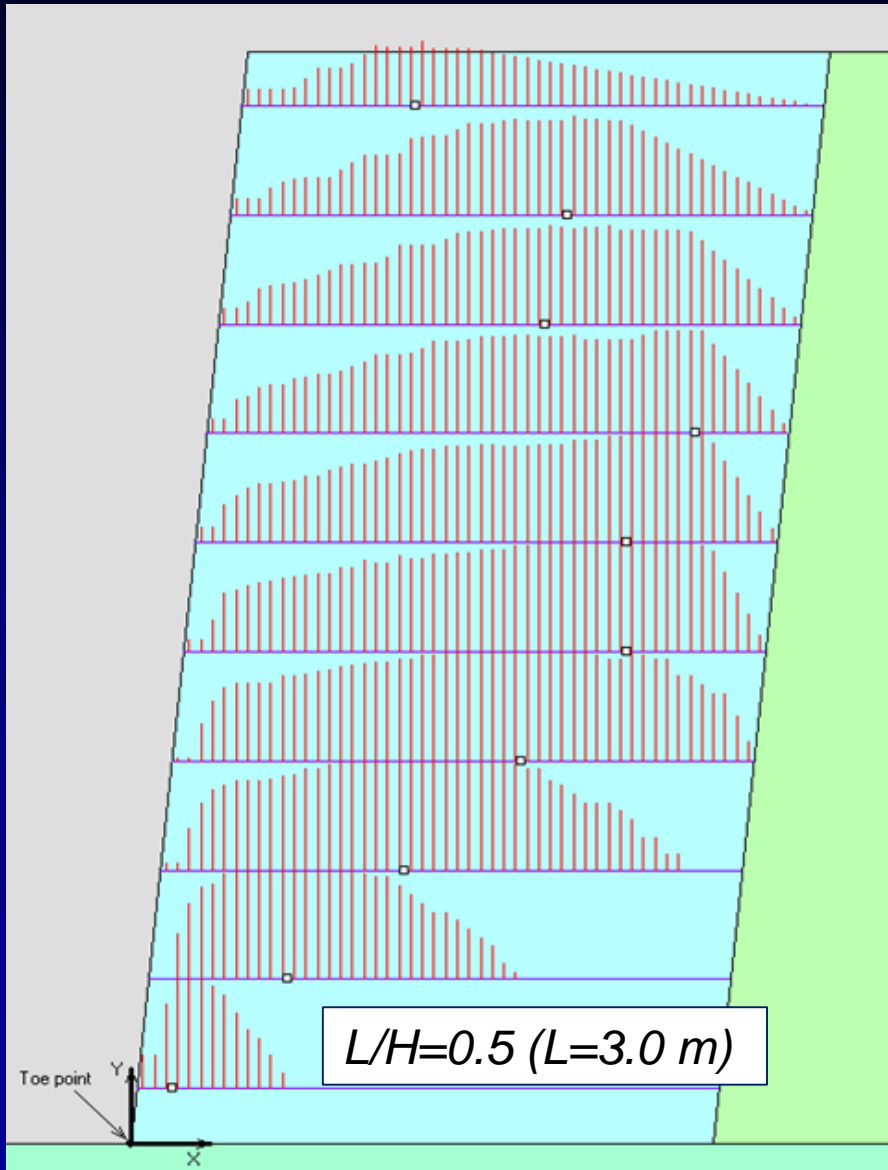


**Depending on relative length of secondary reinforcement, it may decrease  $T_{max}$ . Generally it has significant effects on  $T_o$  (connection loading).**

# Face Displacements: Secondary versus Close Spacing

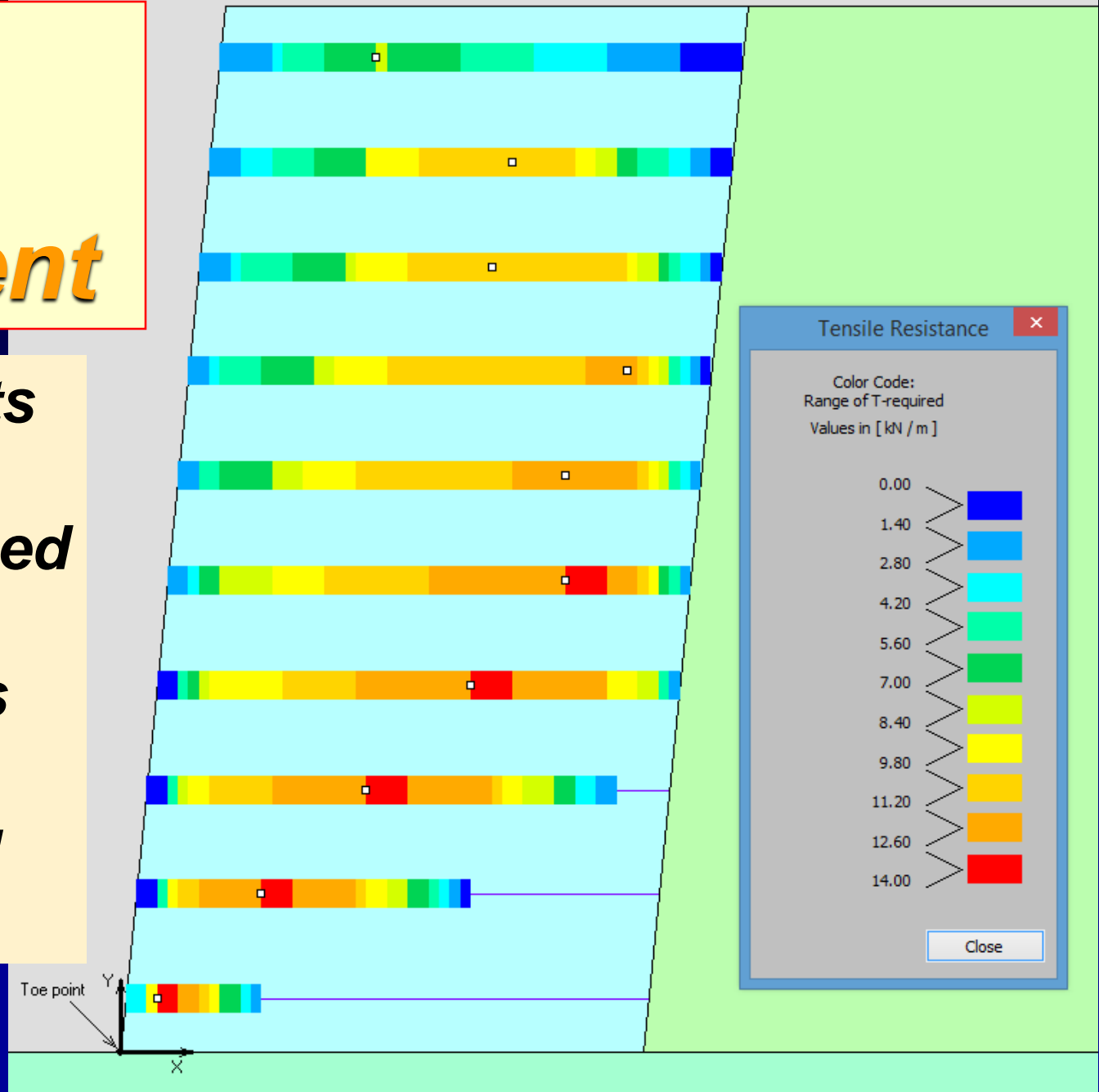


# Effects of Shorter Reinforcement

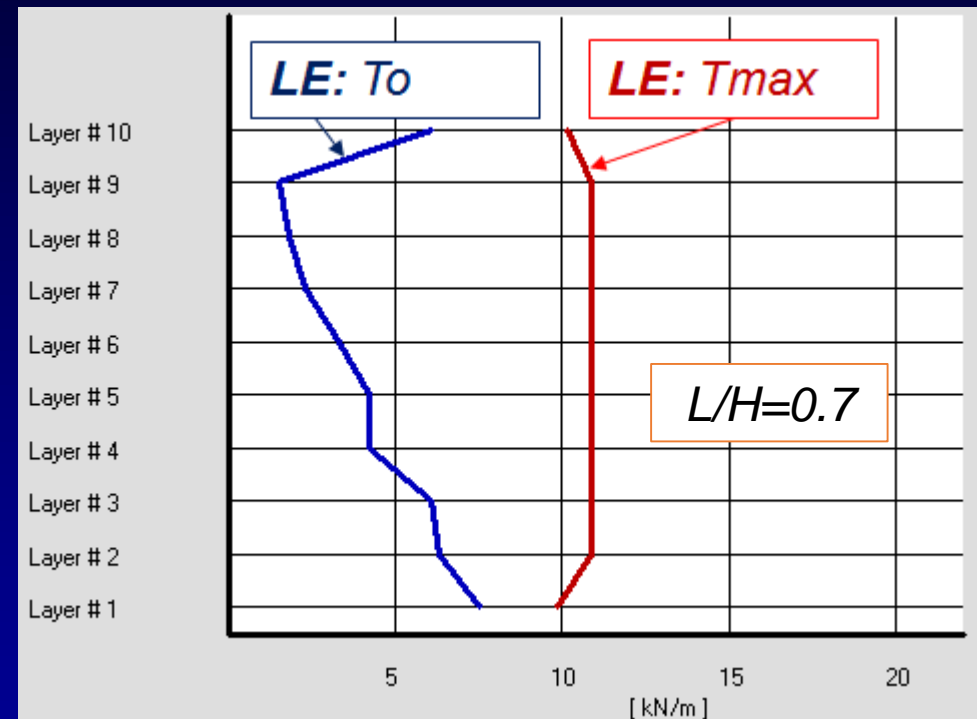
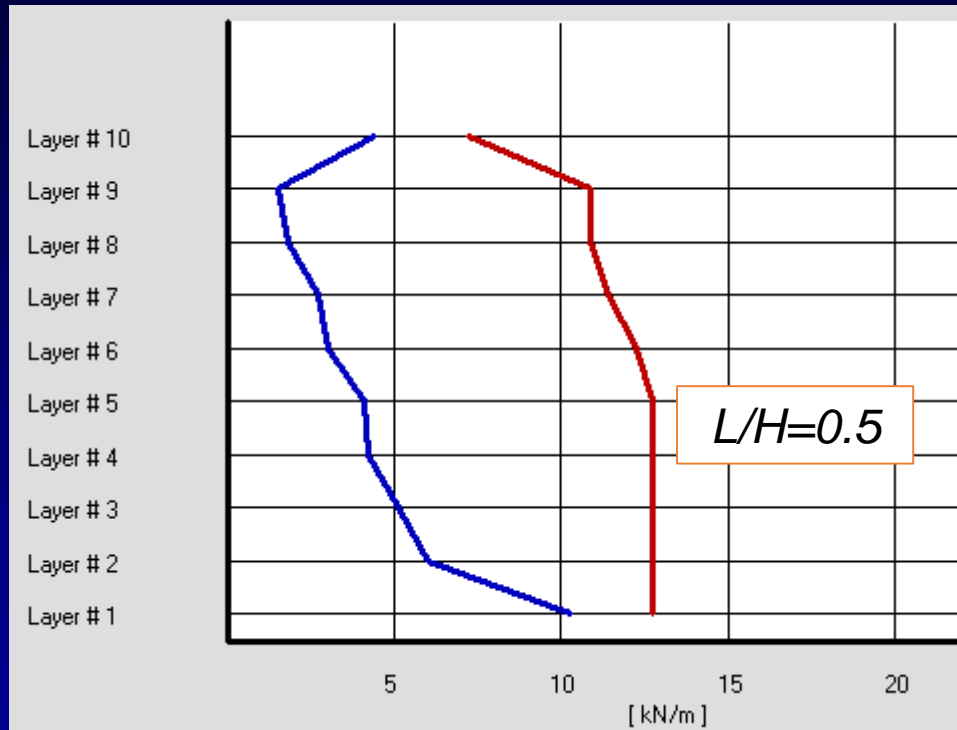


# Effects of Shorter Reinforcement

**Short reinforcements can be considered, but result in increased  $T_{max}$  as compound failure prevails. This can be explicitly accounted for using the LE framework.**



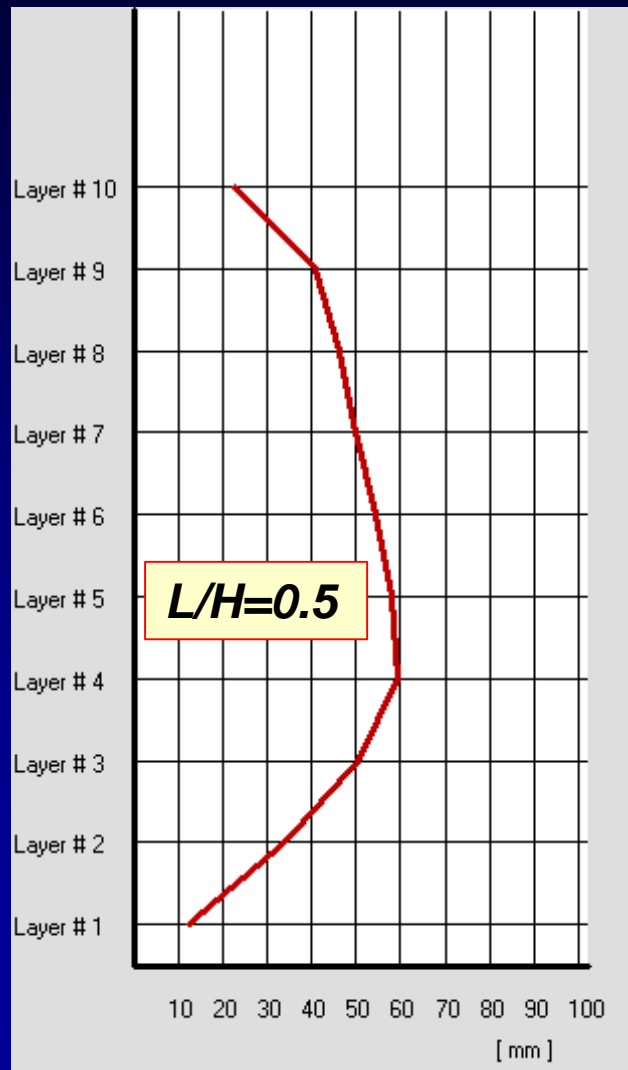
# Effects of Shorter Reinforcement: $T_{max}$ and $T_o$



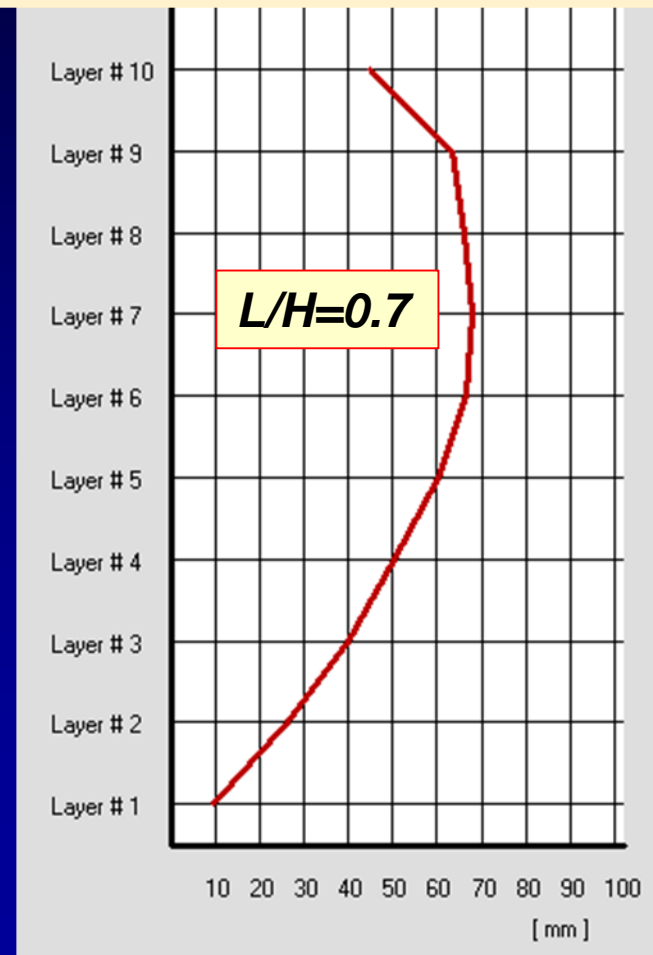
Generally, lower layers carry higher load due to compound failures → Upper layers need to contribute less to produce  $F_s=1.0$  → Upper layer carries marginally less load thus resulting in smaller  $T_{max}$  and  $T_o$

# Effects of Shorter Reinforcement: Displacement

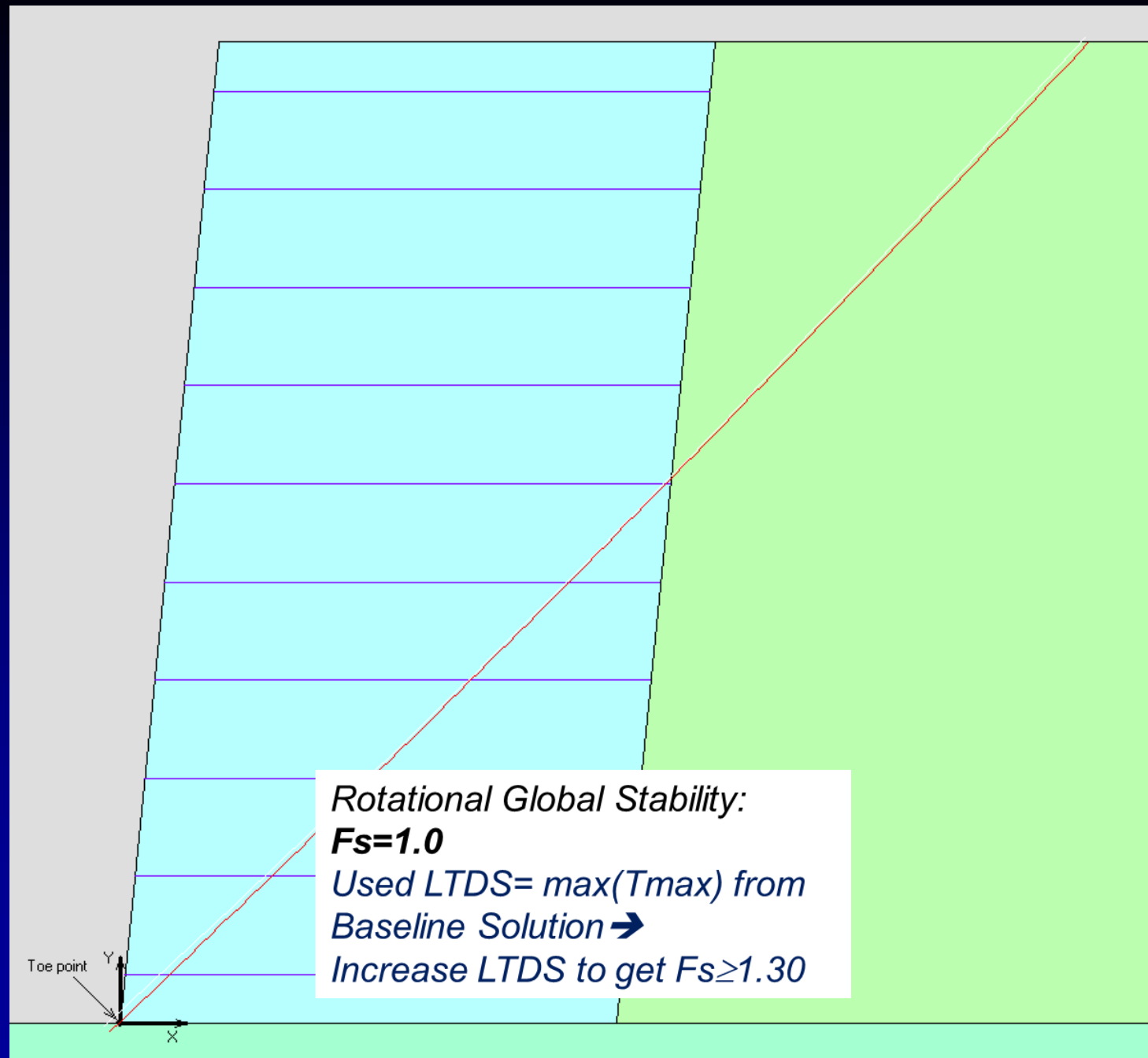
**Note:**  
*Lower layers carry higher load but are shorter, yielding here about the same max displacement as in baseline problem. This is not always the case.*



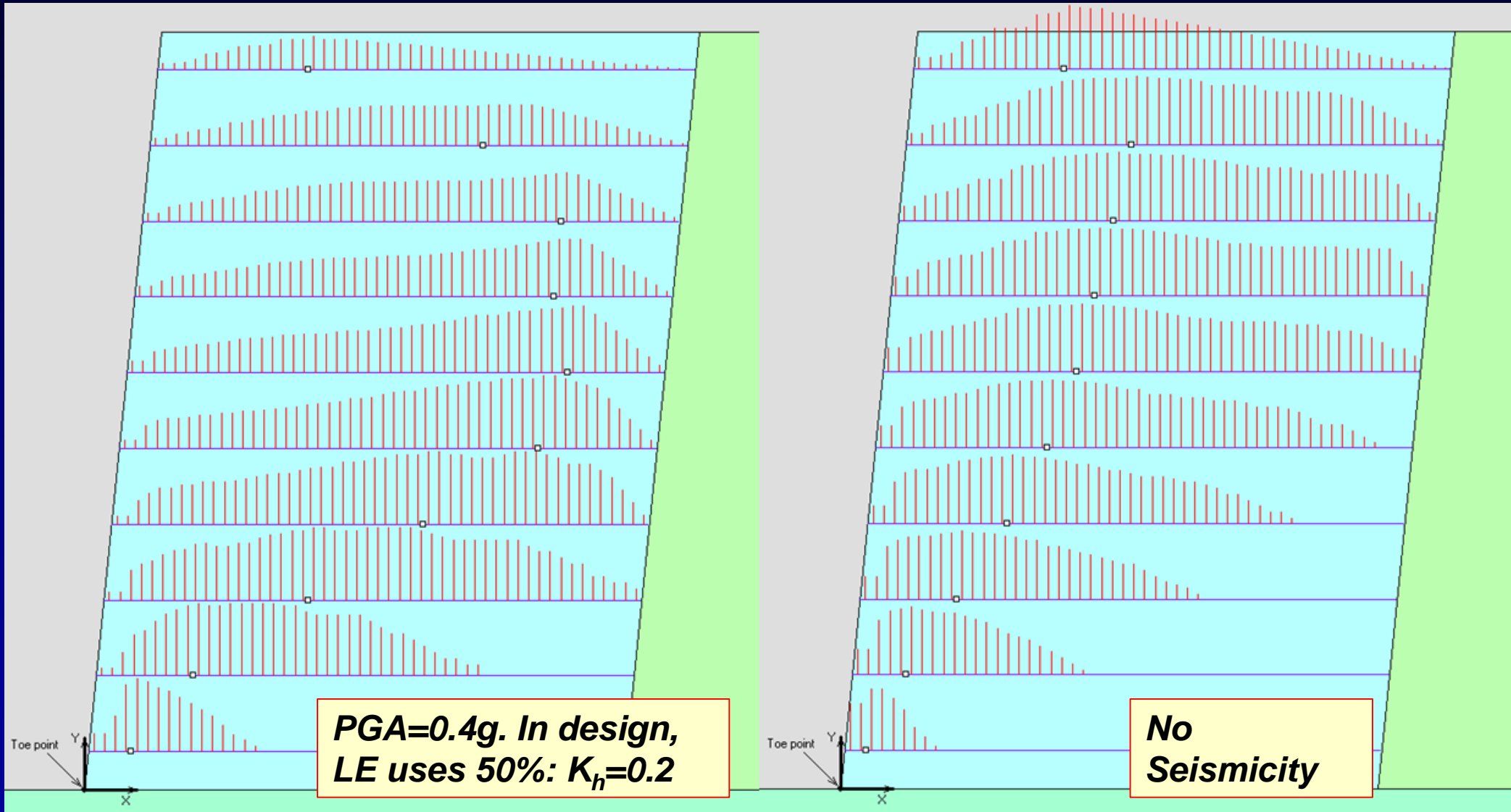
$\Delta$  profile for  $J=500$  kN/m  
(For  $F_s=1.0$ ; i.e., soil strength is fully mobilized)



# Short Layers and Global Stability

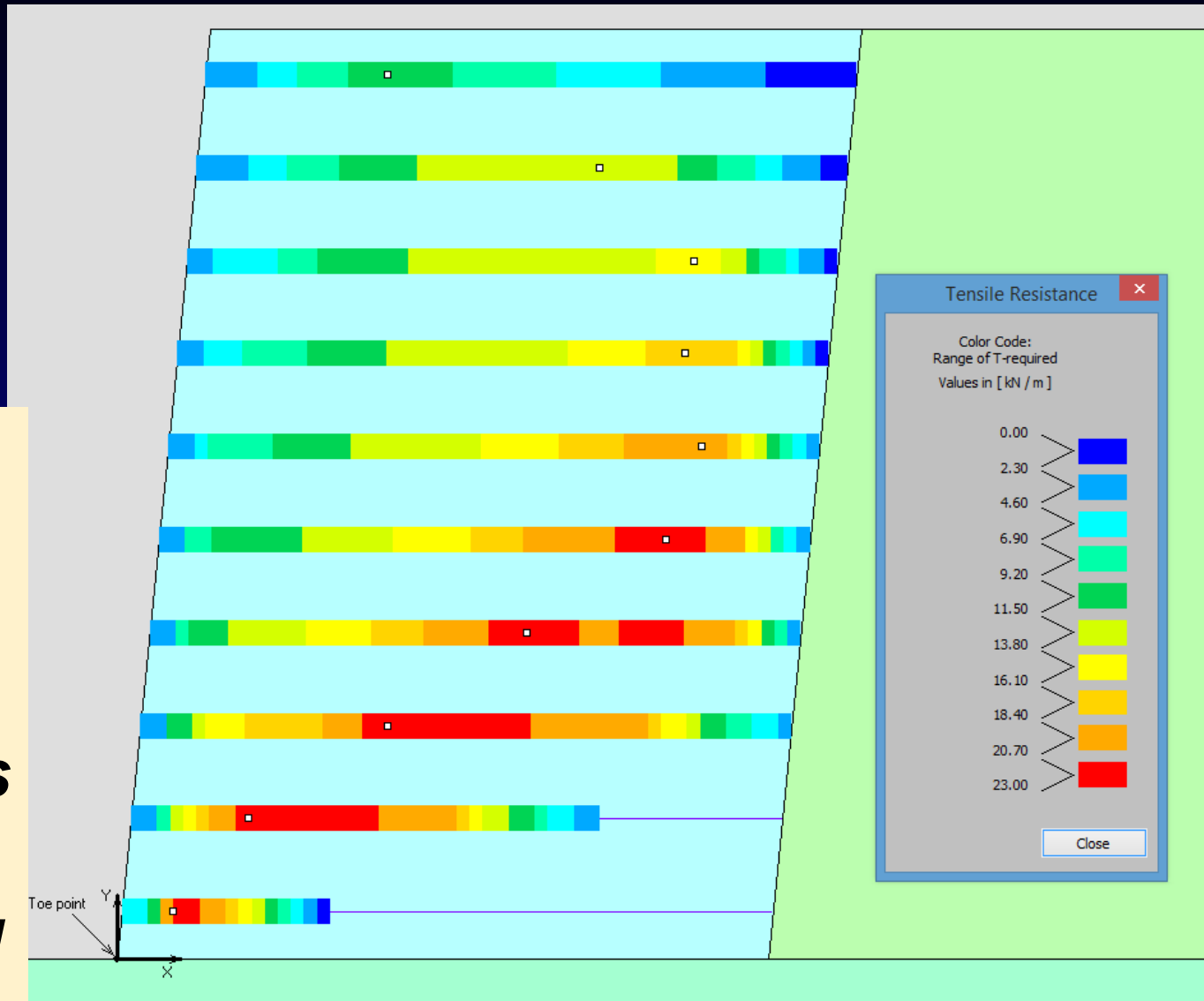


# Effects of Seismicity

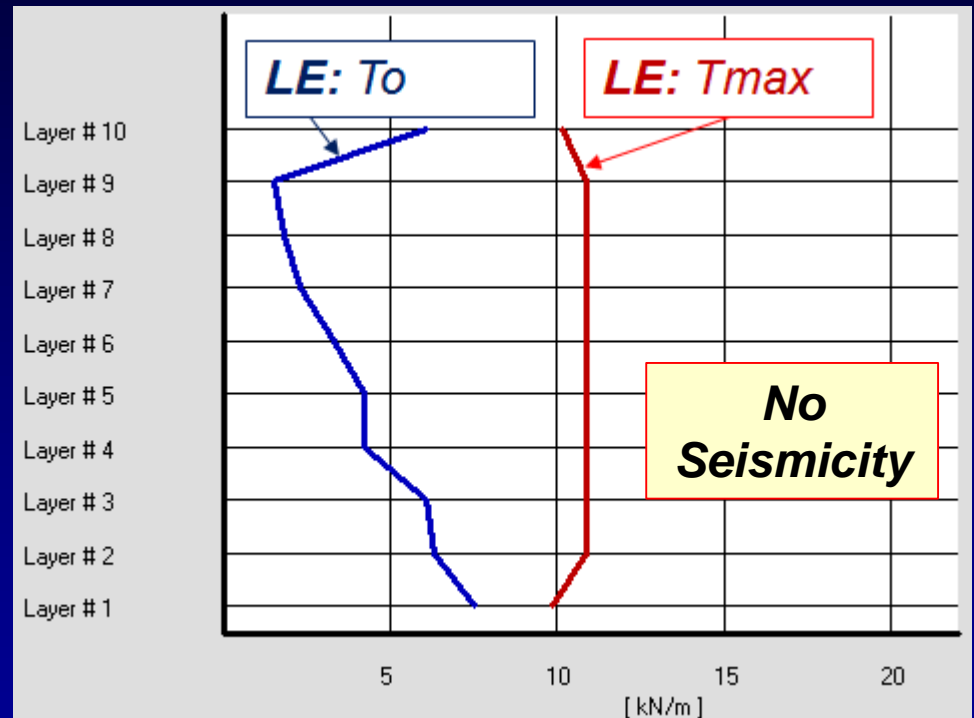
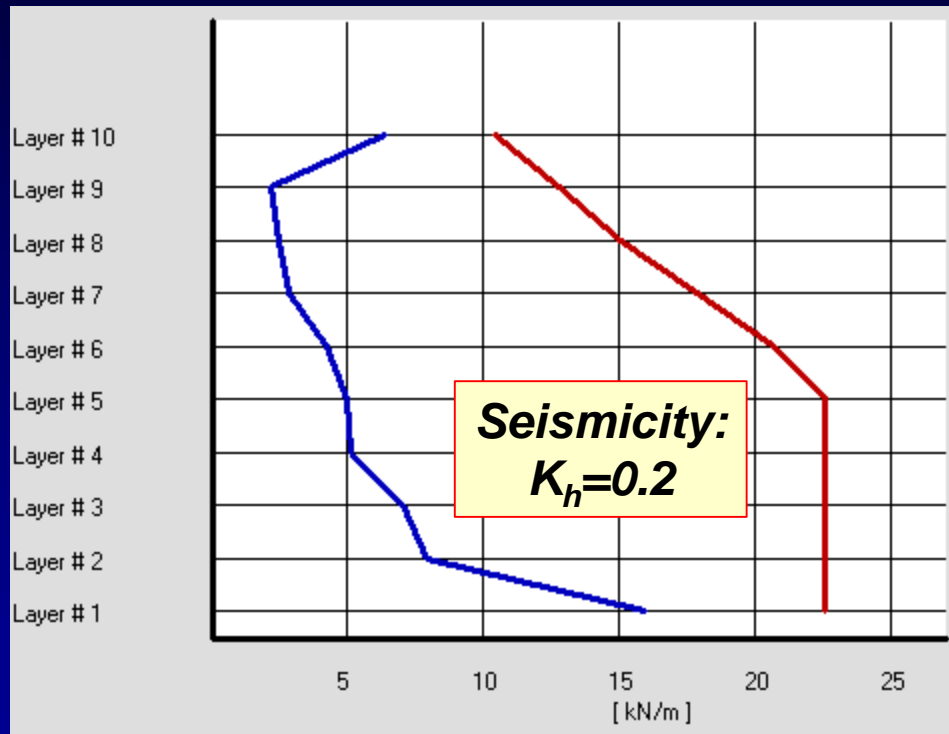


# Tension Map Under Seismic Loading

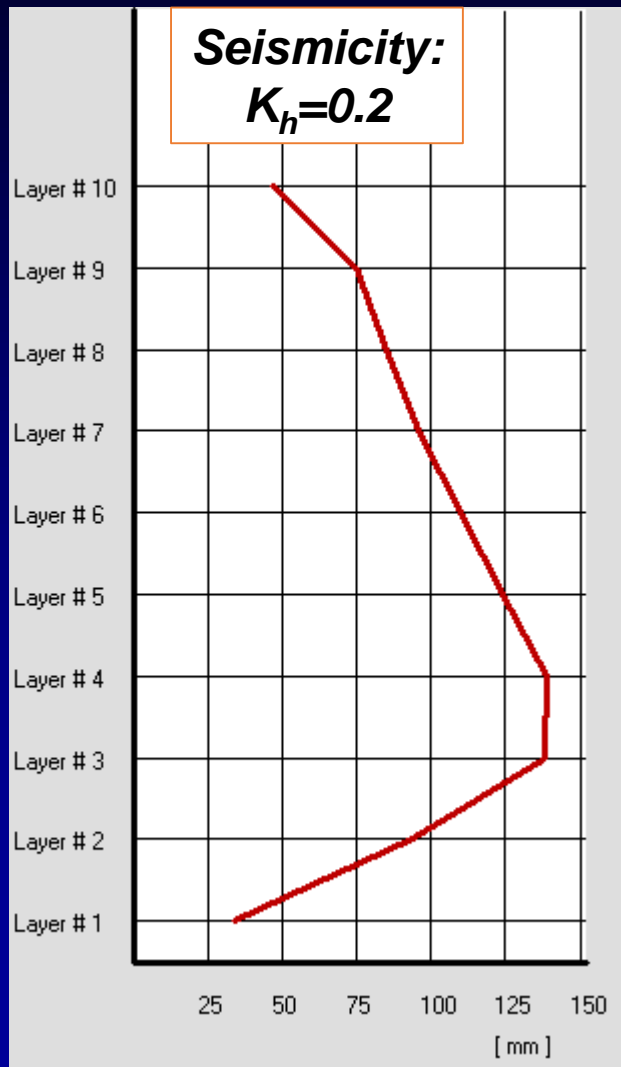
Seismicity can be considered, but results in increased  $T_{max}$  as compound failure prevails. This can be explicitly accounted for using the LE framework.



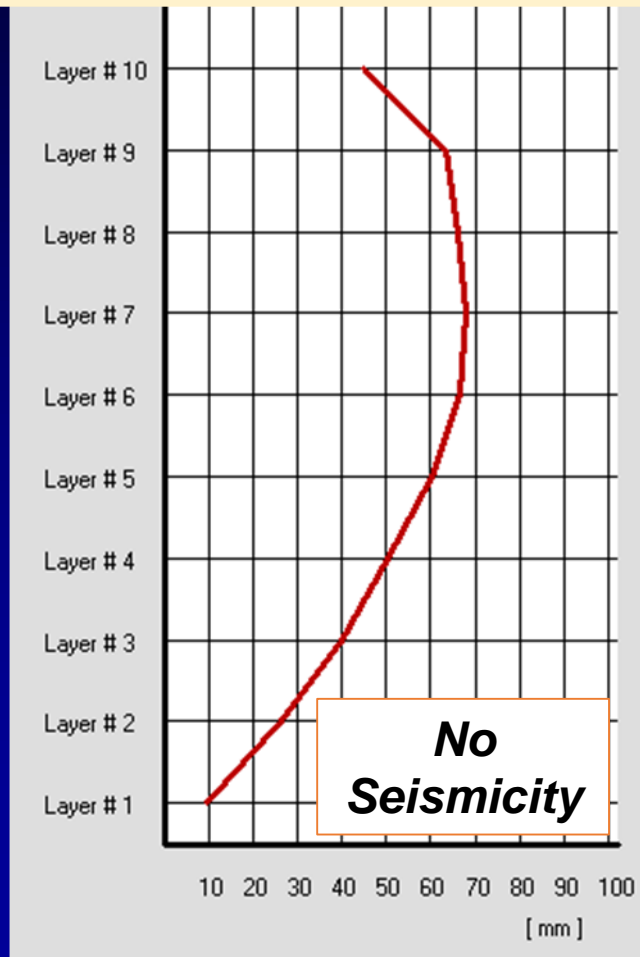
# Seismic Effects: $T_o$ and $T_{max}$



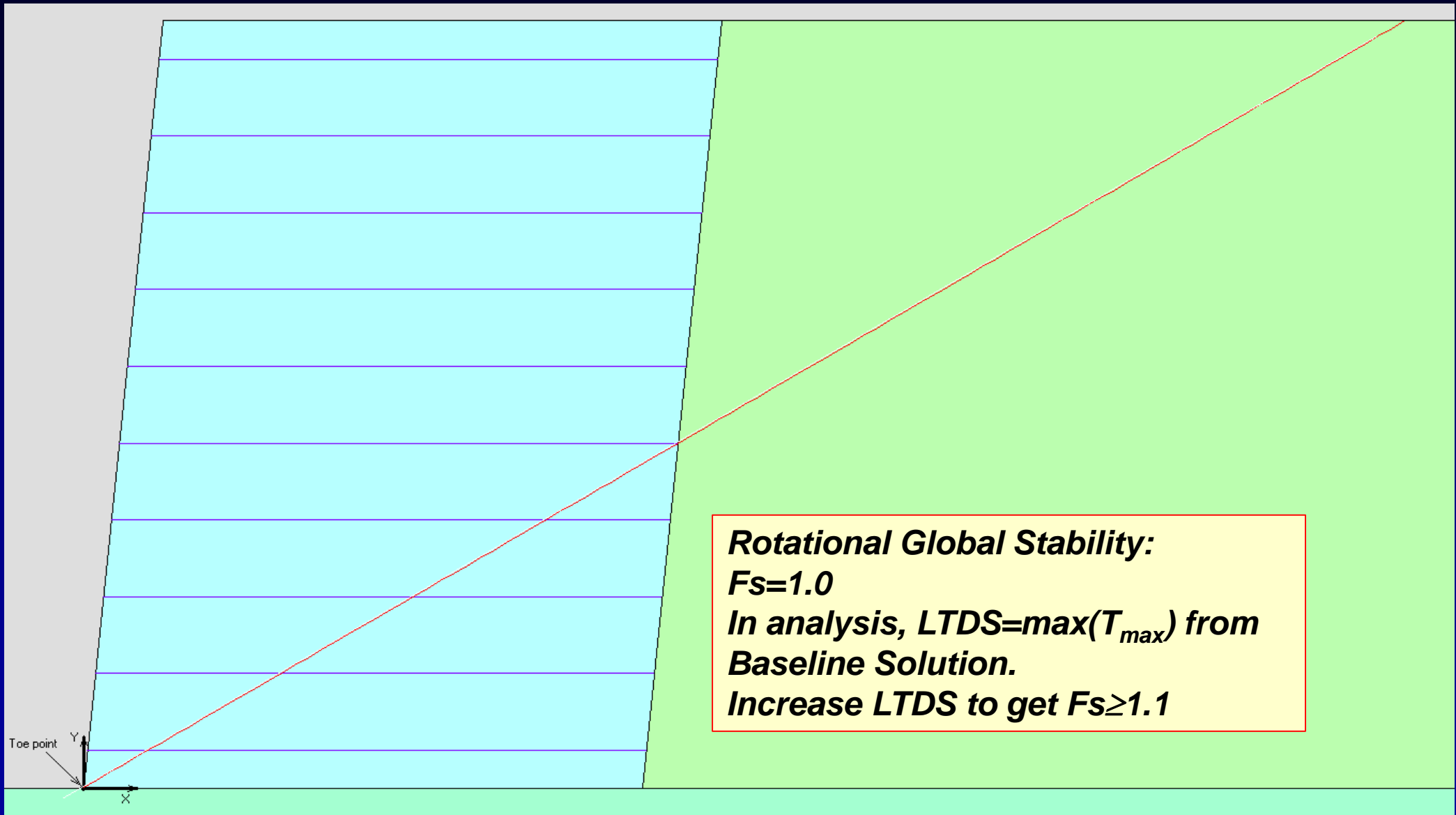
# Seismic Displacements



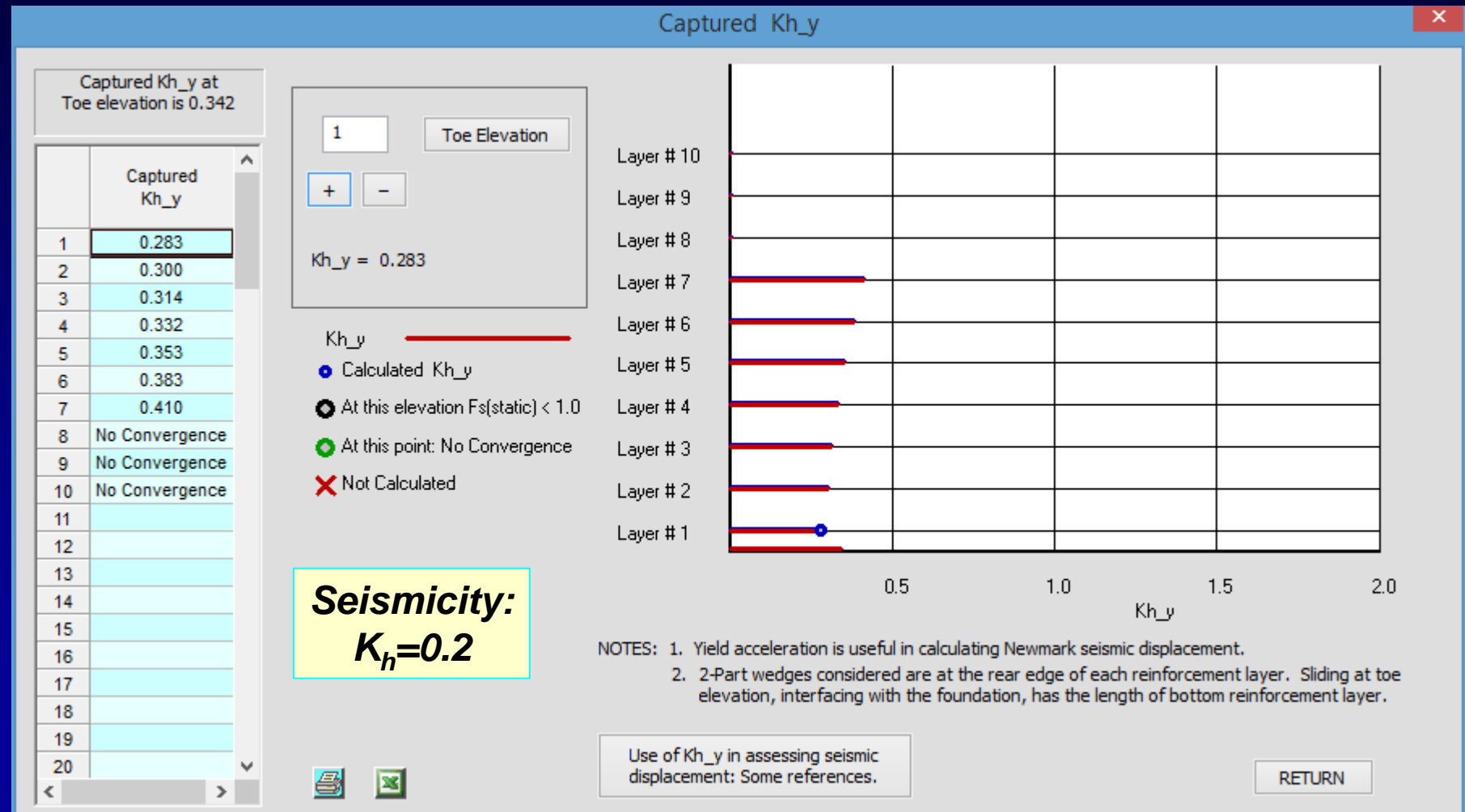
$\Delta$  profile for  $J=500$  kN/m  
(For  $F_s=1.0$ ; i.e., soil strength is fully mobilized)



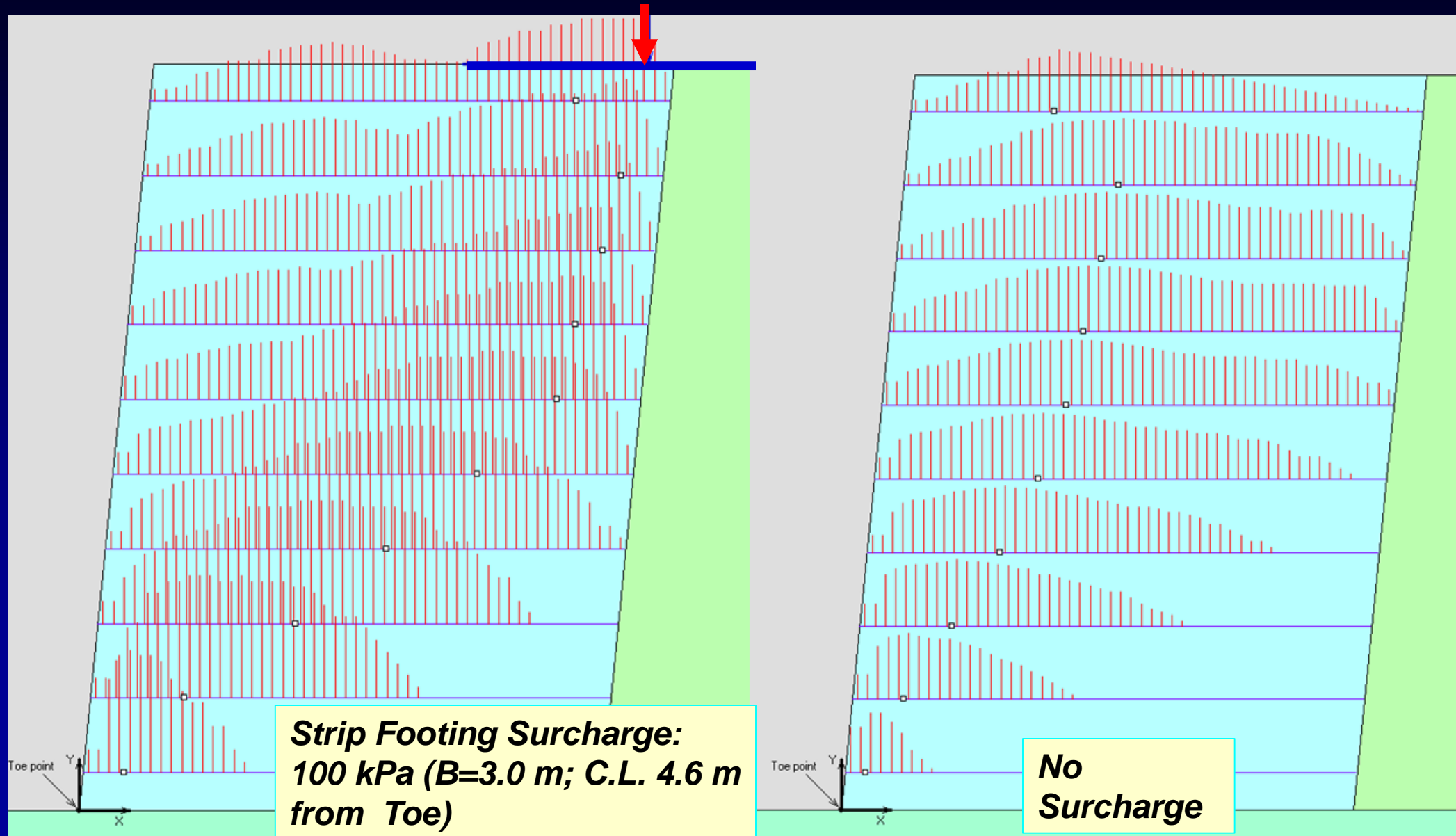
# Seismic Global Rotational Stability



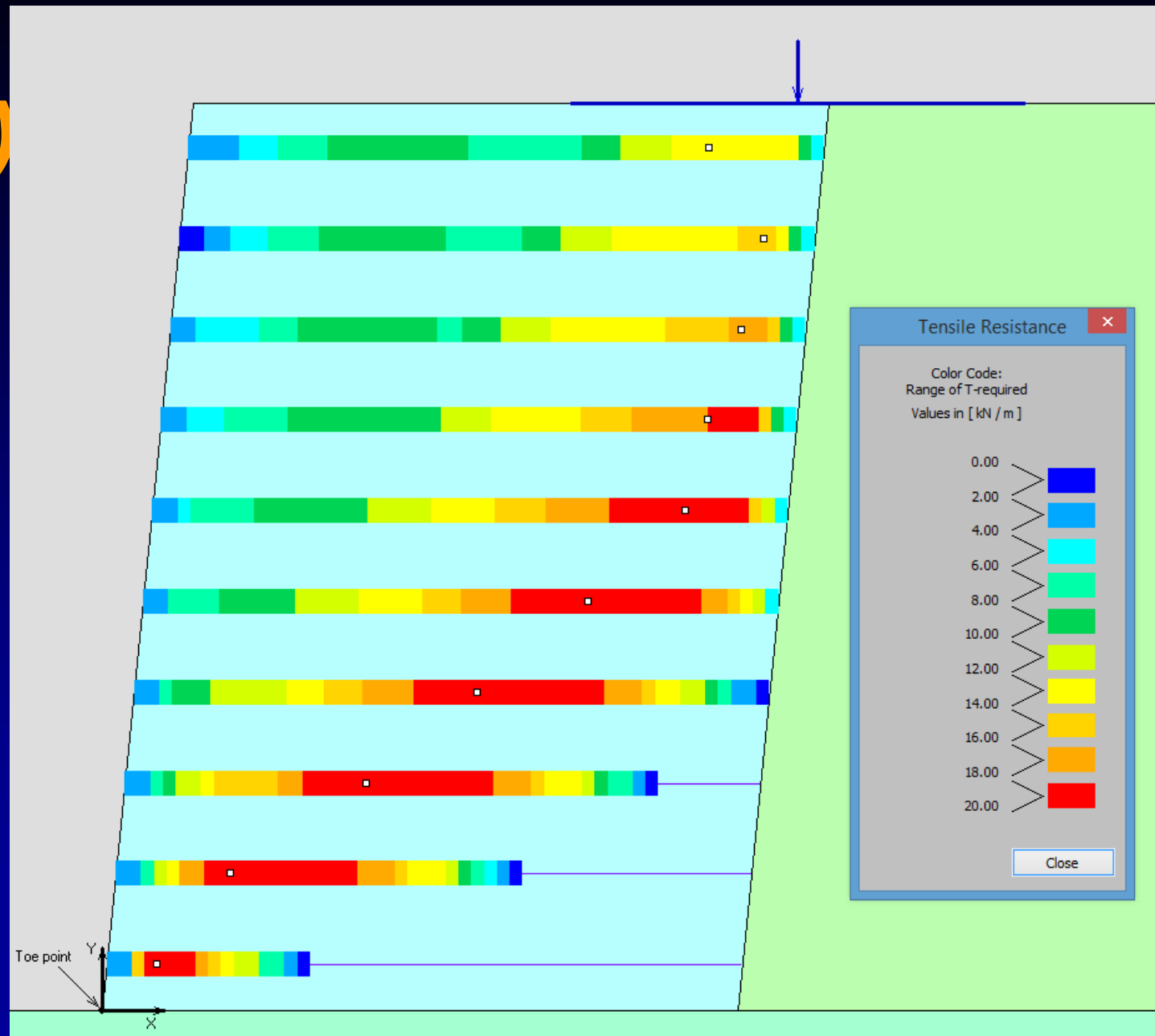
# Computed Yield Acceleration at Each Layer, $K_{h-y}$ , using Spencer 2-part wedge ( $K_{h-y}$ renders $F_s=1.0$ for sliding at each elevation)



# Effects of Surcharge (Dead Load)

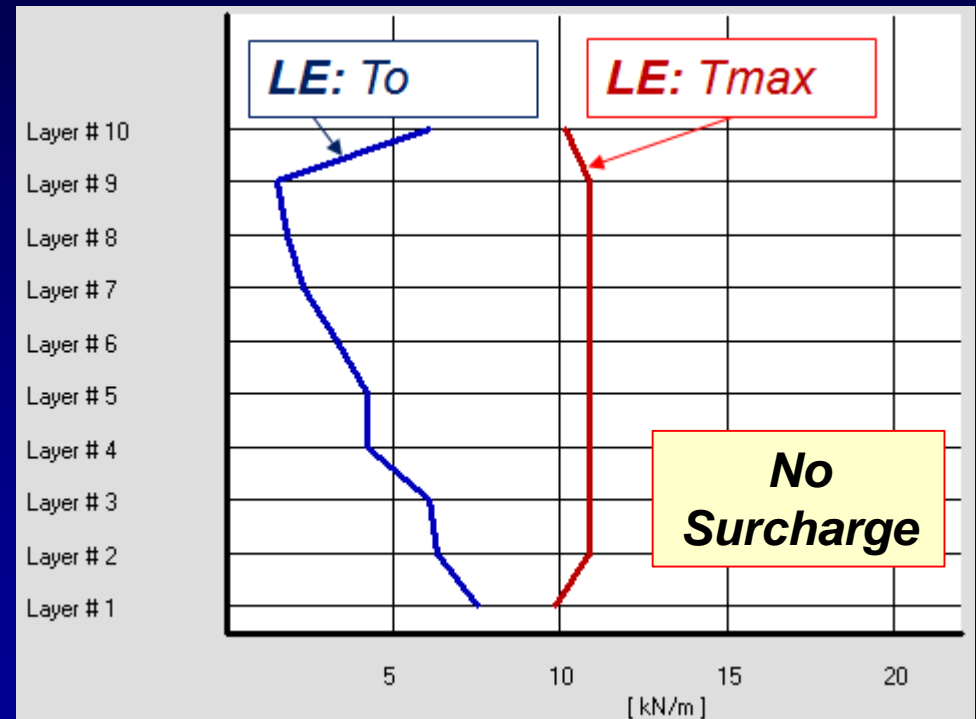
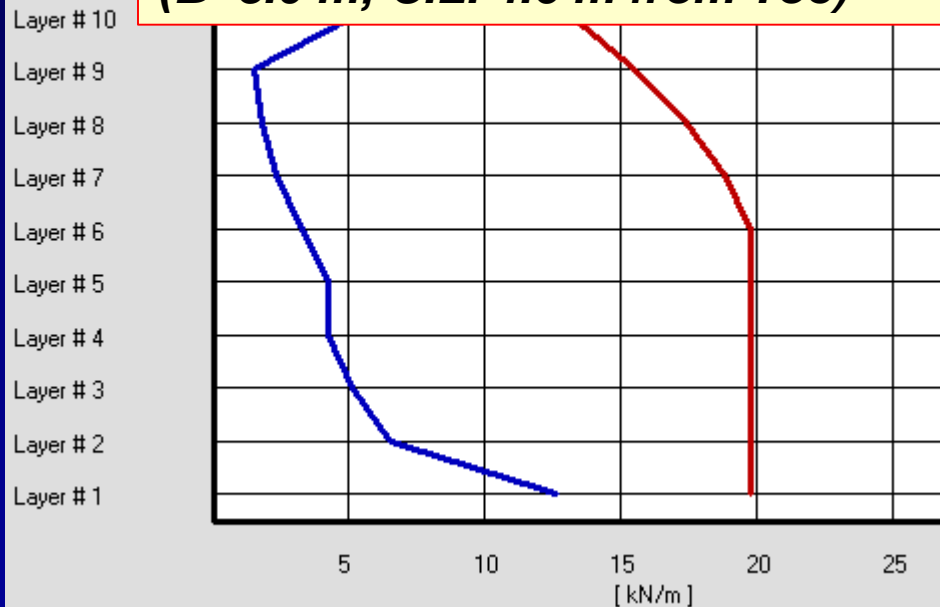


# Surcharge (dead load) and Tension Map



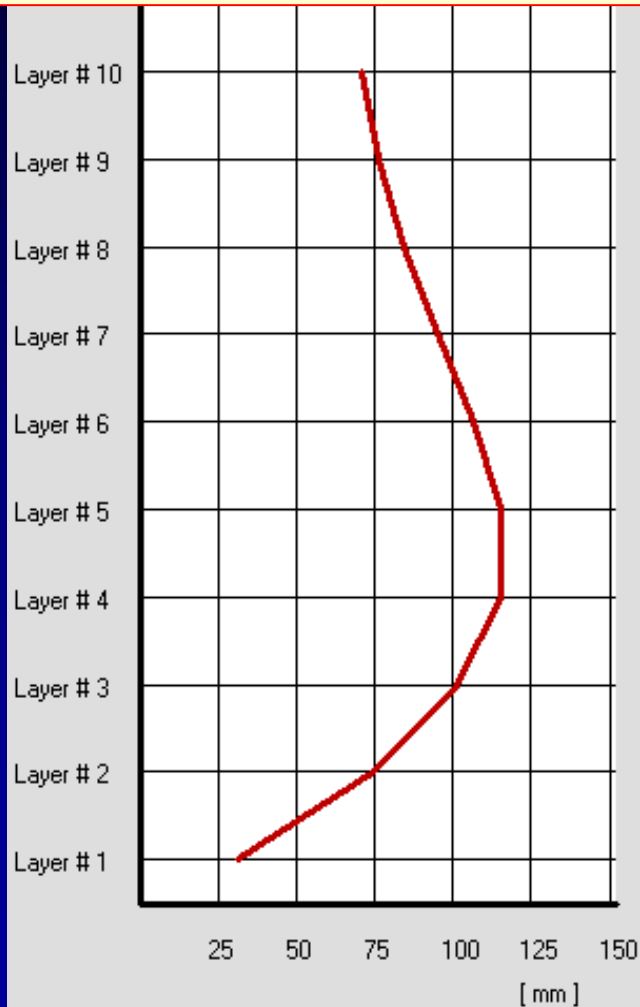
# Effects of Surcharge (dead load): $T_o$ and $T_{max}$

**Strip Footing Surcharge: 100 kPa  
( $B=3.0$  m; C.L. 4.6 m from Toe)**

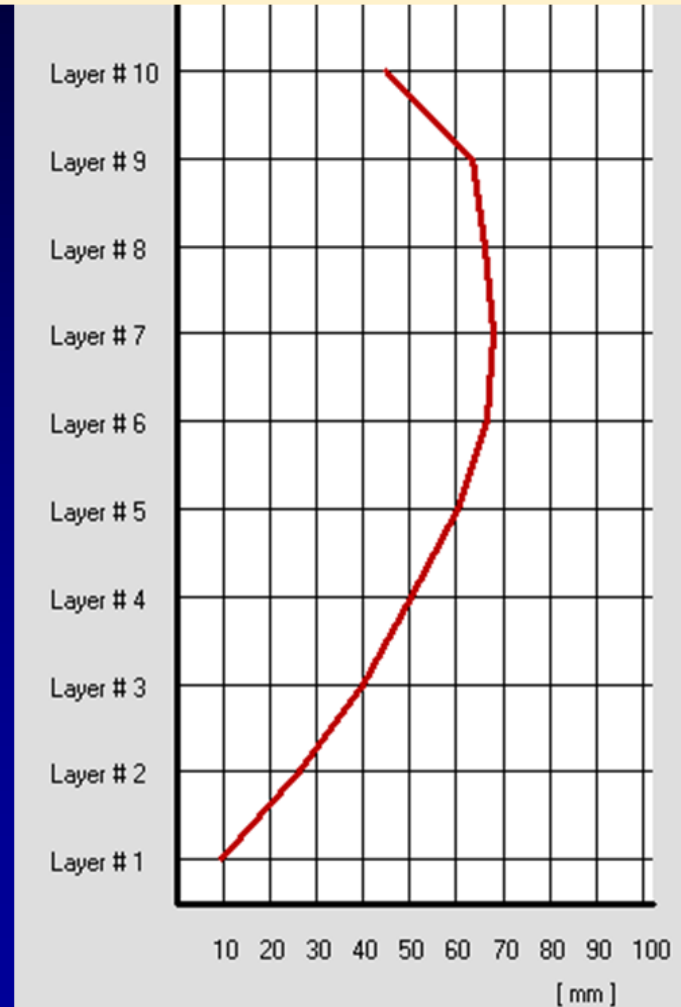


# Surcharge (DL) and Displacements

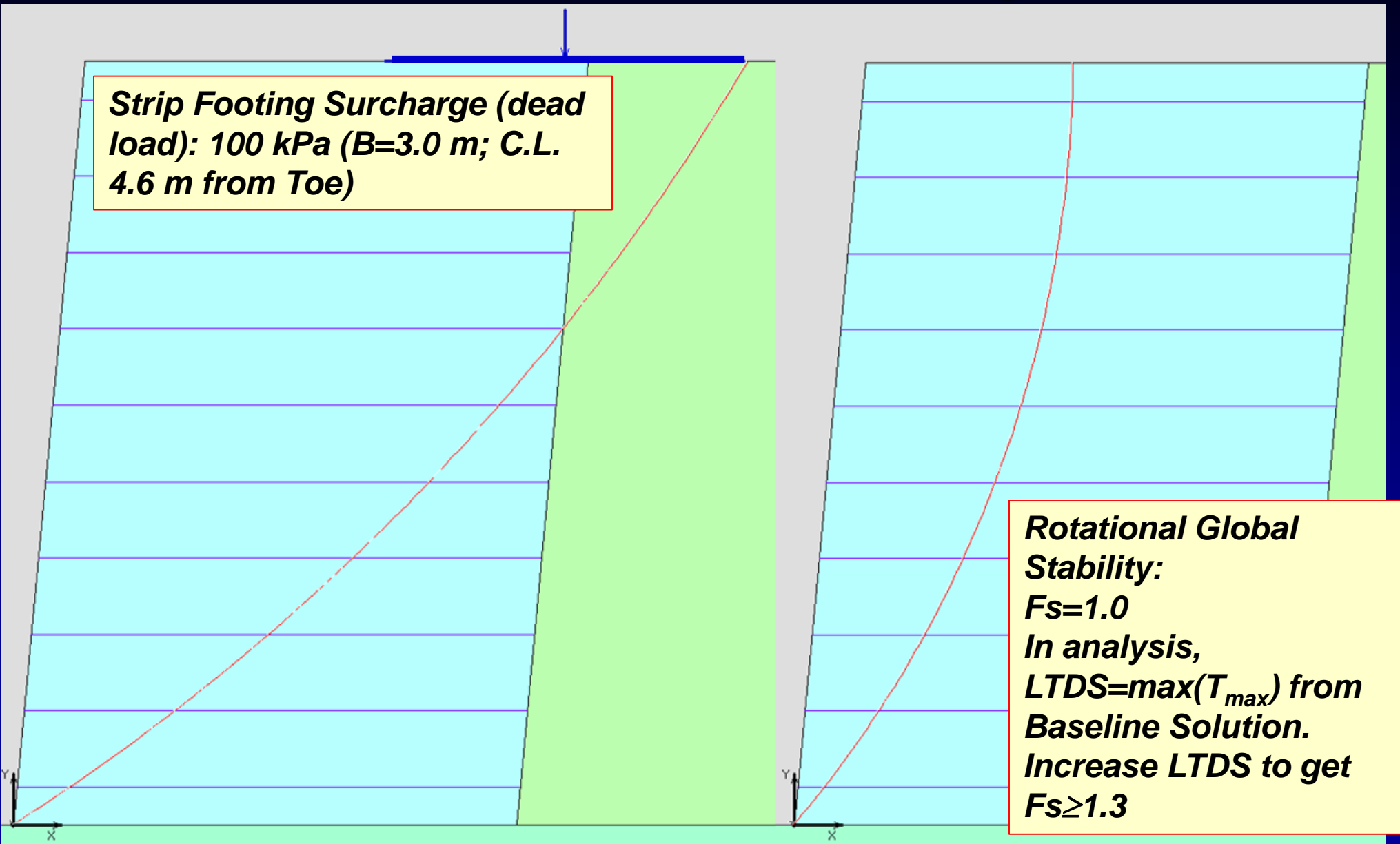
Strip Footing Surcharge: 100 kPa  
( $B=3.0$  m; C.L. 4.6 m from Toe)



$\Delta$  profile for  $J=500$  kN/m  
(For  $F_s=1.0$ ; i.e., soil strength is fully mobilized)



# Rotational Global Stability

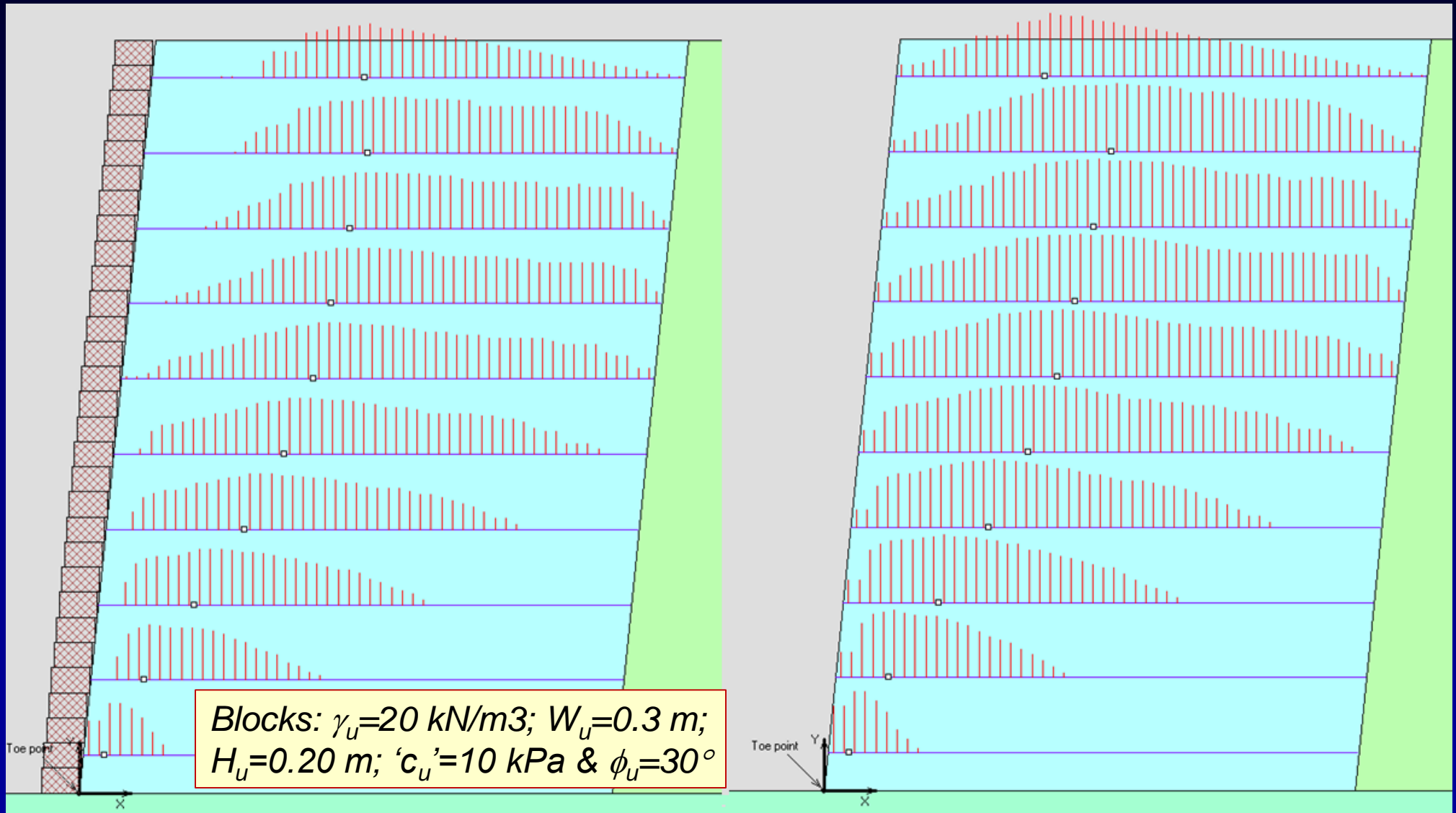


The diagram illustrates rotational global stability analysis for a strip footing. It consists of two side-by-side plots. The left plot shows a failure mechanism with a red dashed line representing the failure surface. A blue arrow points to the footing, which is 3.0 m wide and 4.6 m from the toe. The right plot shows the same failure mechanism but with a different failure surface, indicated by a red solid line. Both plots have a light blue background for the soil and a light green background for the footing. The failure surface is a curve that starts at the toe and extends upwards and to the right. The failure mechanism is defined by a series of horizontal blue lines representing soil layers.

**Strip Footing Surcharge (dead load): 100 kPa ( $B=3.0$  m; C.L. 4.6 m from Toe)**

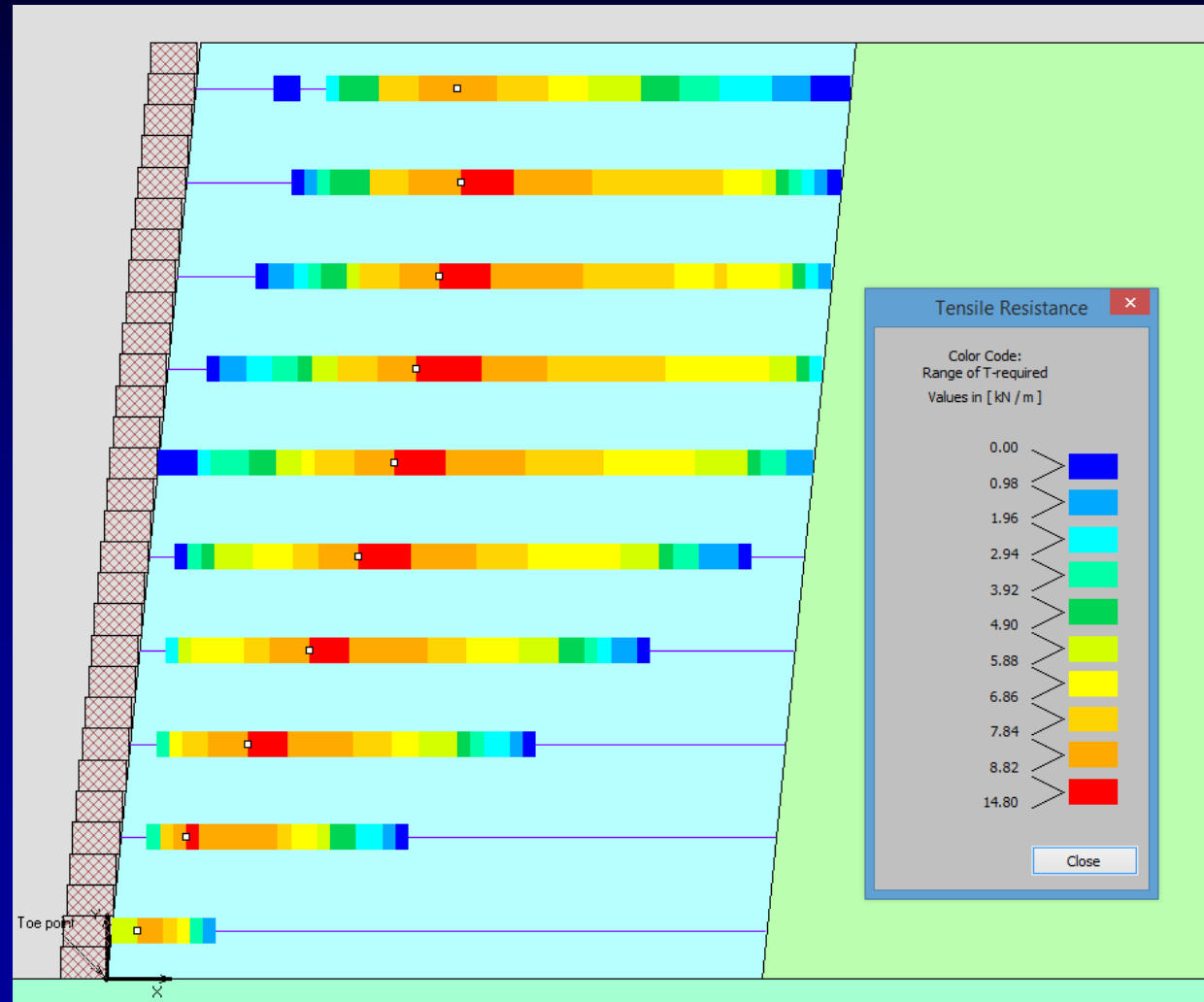
**Rotational Global Stability:**  
 $F_s=1.0$   
In analysis,  
 $LTDS=\max(T_{\max})$  from  
Baseline Solution.  
Increase LTDS to get  
 $F_s \geq 1.3$

# Effects of Small Blocks Facing

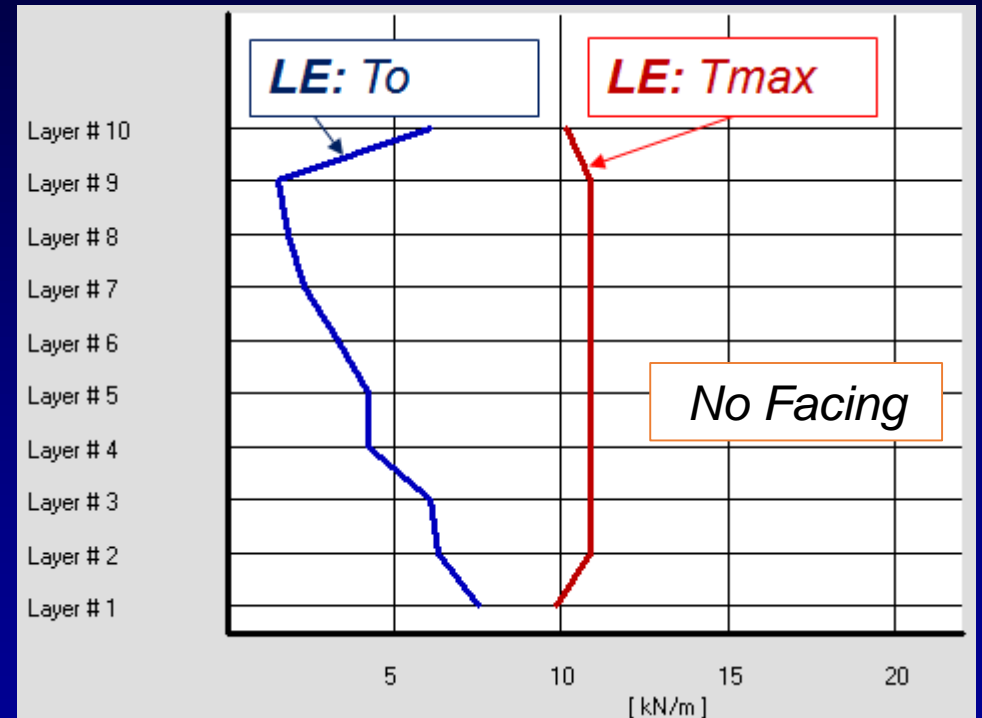
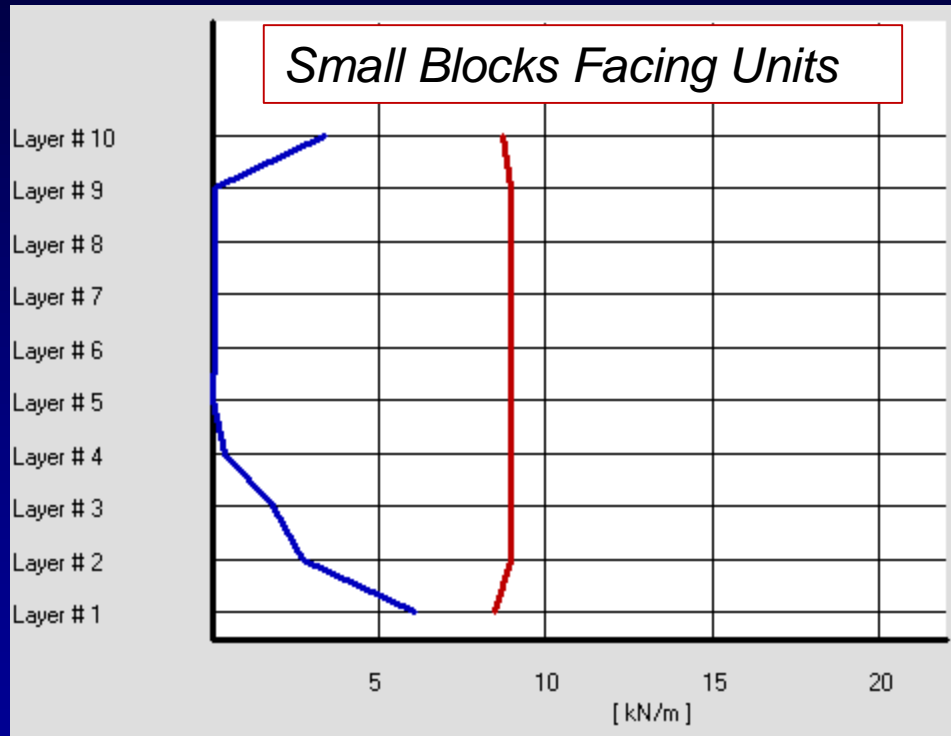


# Facing Units and Tension Map

**Can account for facing units. These components may decrease  $T_{max}$  and connection loading,  $T_o$ .**

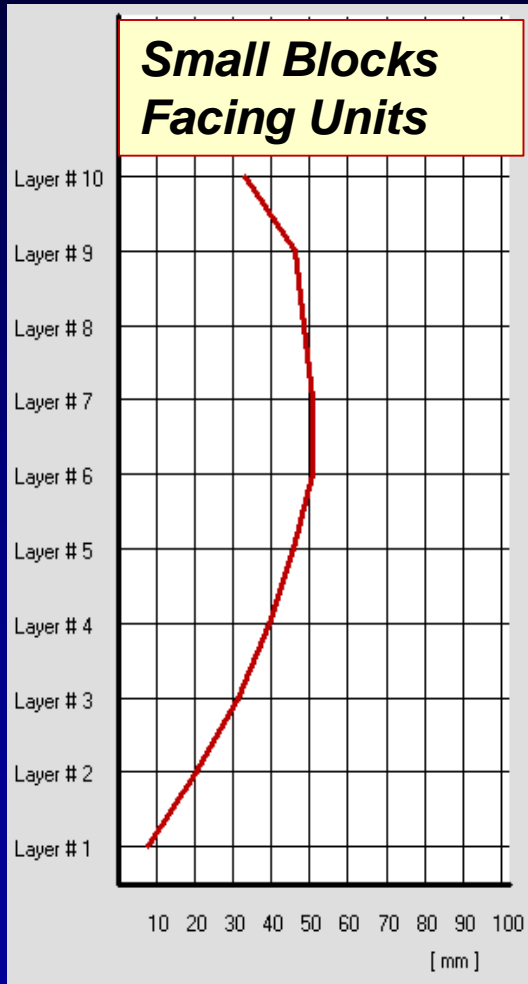


# Effects of Small Blocks Facing: $T_{max}$ and $T_o$

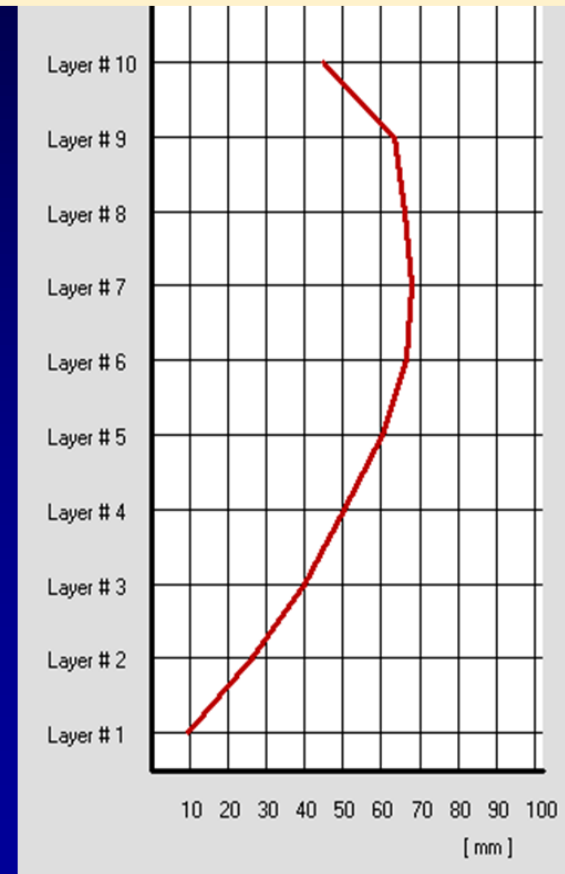


Although  $T(x)$  near the face is zero near top layer,  $T_o$  is required to enable  $T(x)$  at to mobilize without being pulled out. Layers below the top can mobilize  $T(x)$  because sufficient front-end pullout resistance is available even if  $T_o=0$ .

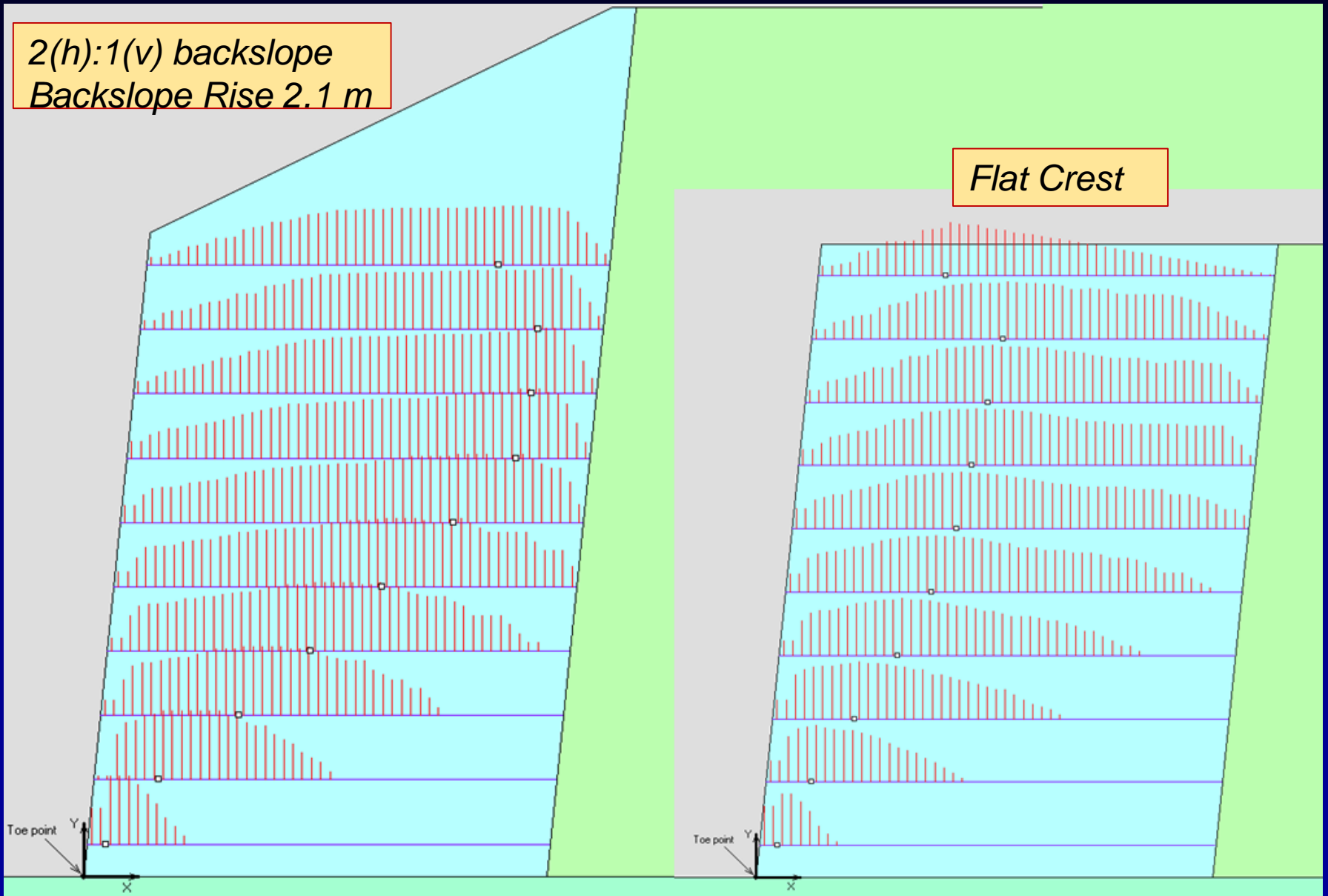
# Impact of Small Blocks Facing on Displacements



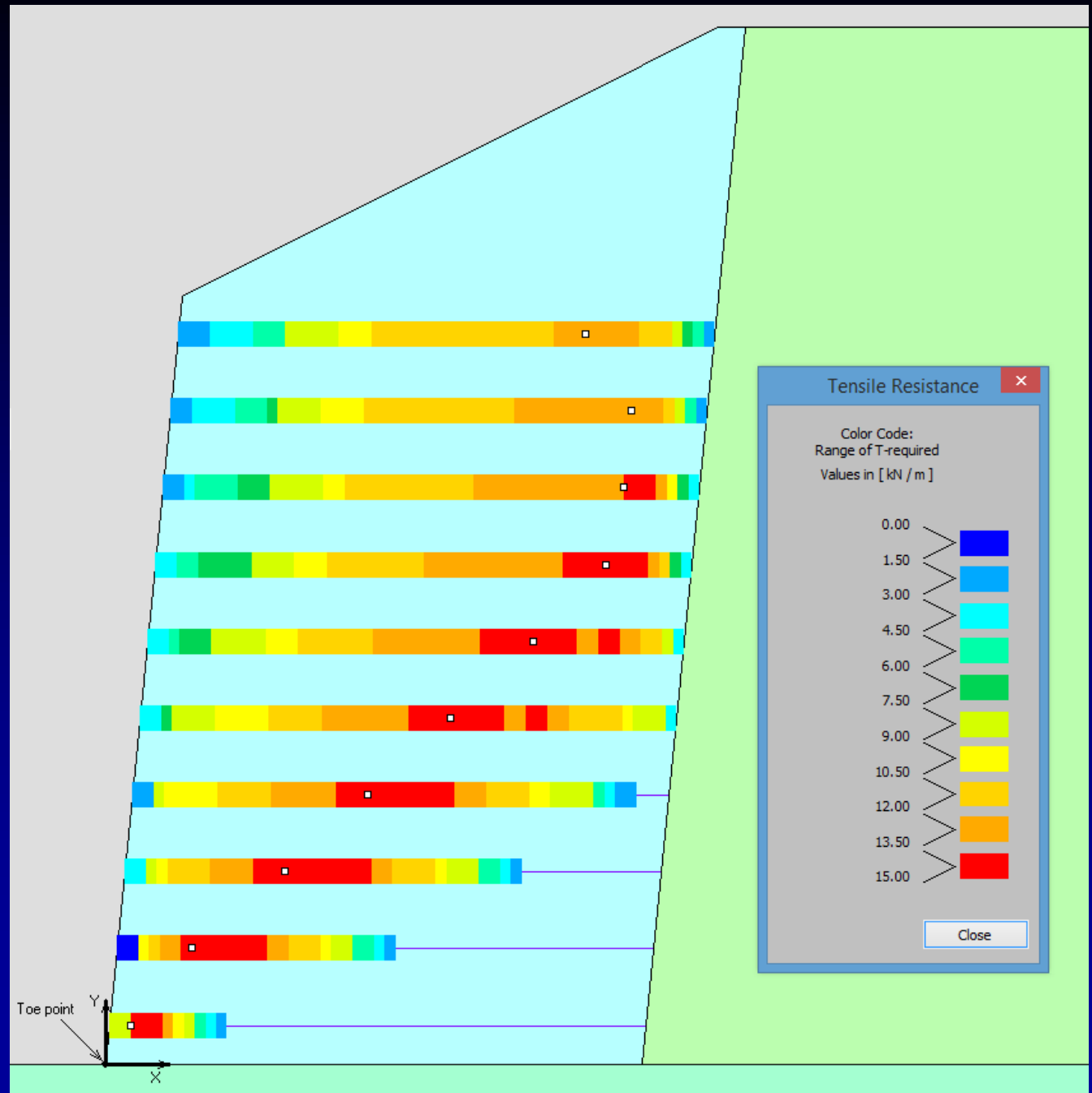
**$\Delta$  profile for  $J=500$  kN/m**  
(For  $F_s=1.0$ ; i.e., soil strength is fully mobilized)



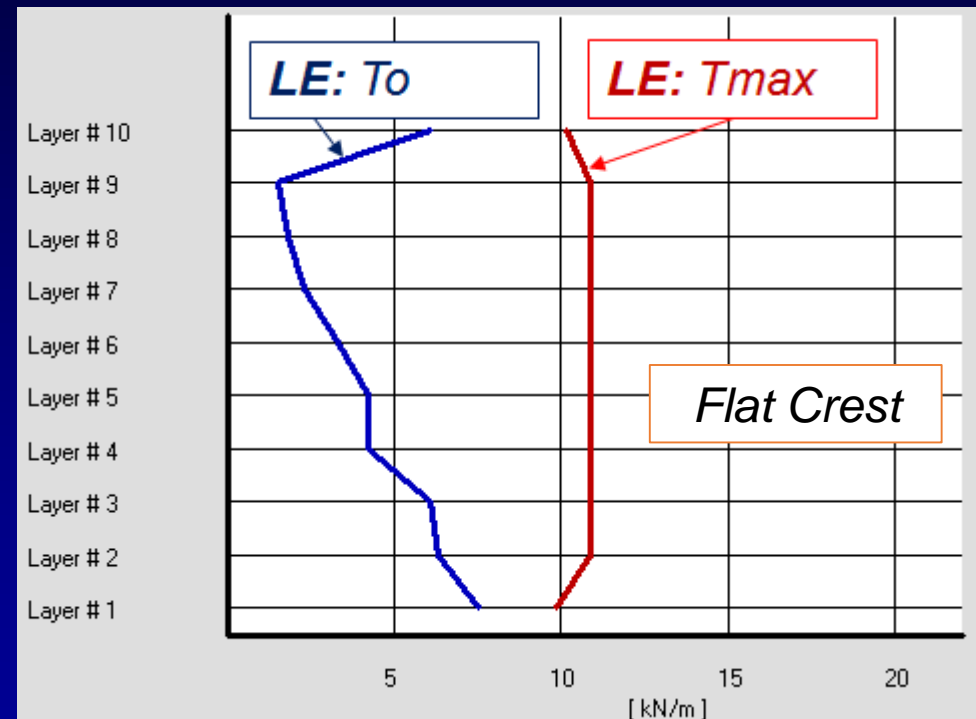
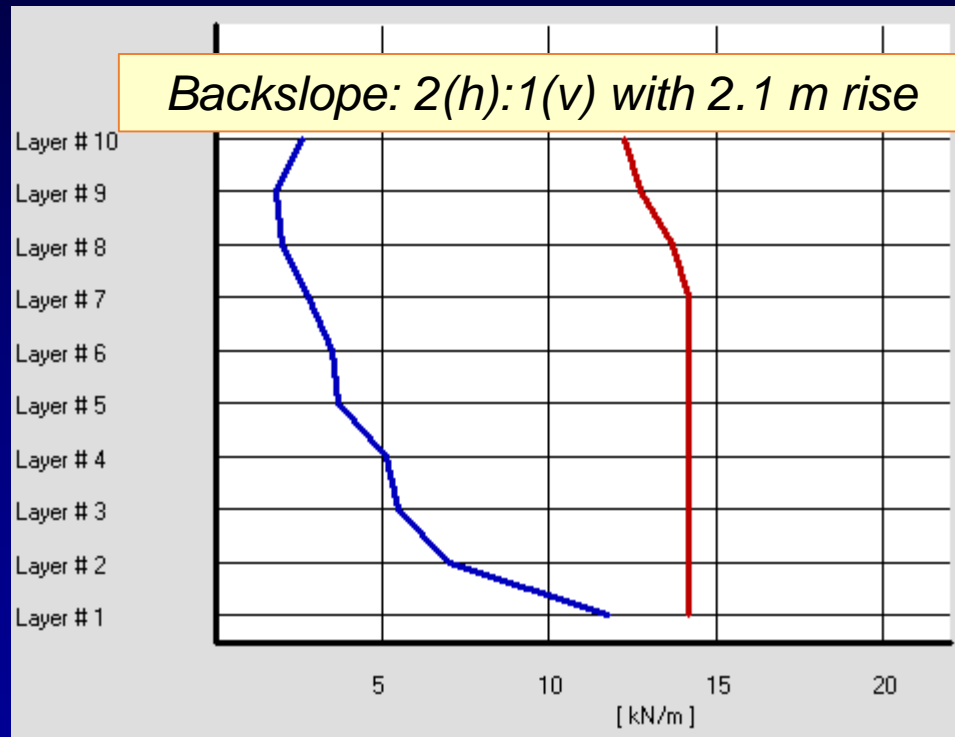
# Effects of Backslope



# Backslope and Tension Map



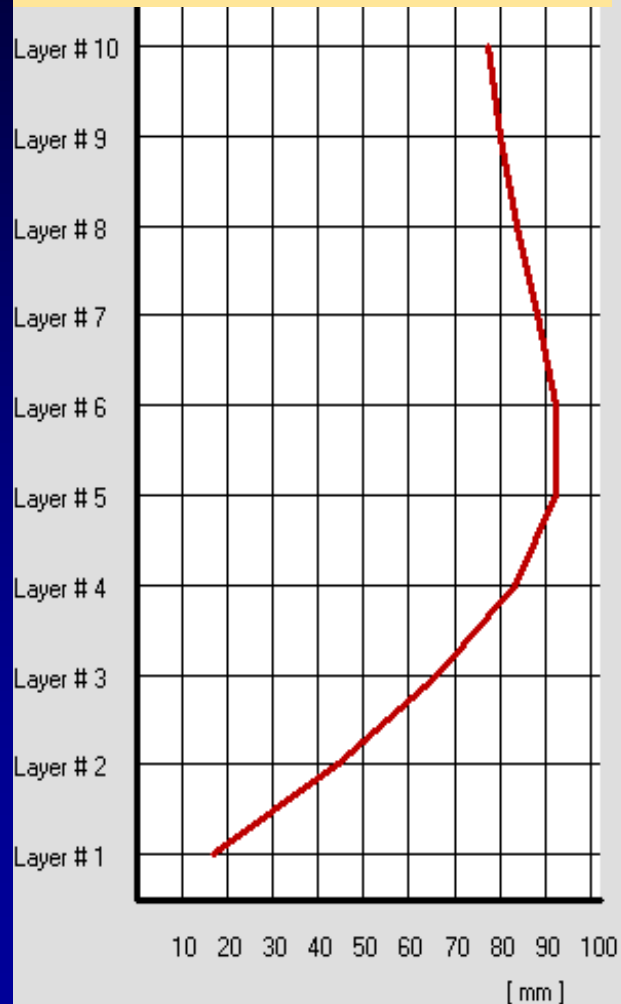
# Effects of Backslope: $T_{max}$ and $T_o$



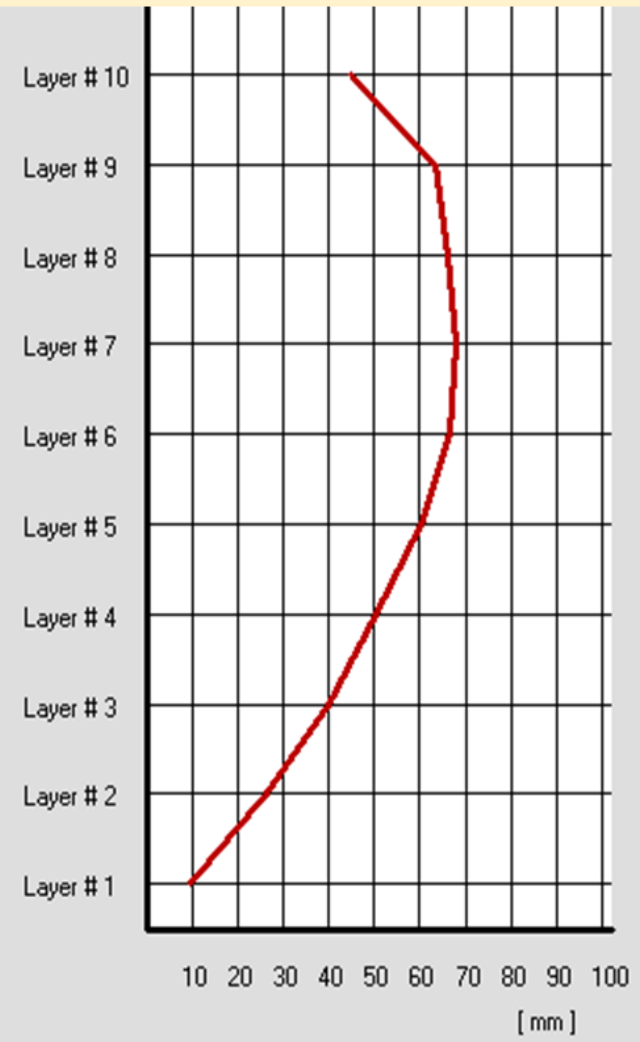
**Note:  $T_o$  in upper layer is smaller for backslope than for flat slope → Rate of increase in  $T(x)$  in front due to backslope is slower than front-end increase in pullout resistance**

# Effects of Backslope on Displacements

2(h):1(v) backslope  
Backslope Rise 2.1 m



$\Delta$  profile for  $J=500$  kN/m  
(For  $F_s=1.0$ ; i.e., soil strength is fully mobilized)



# Global Rotational Stability

2(h):1(v) backslope  
Backslope Rise 2.1 m

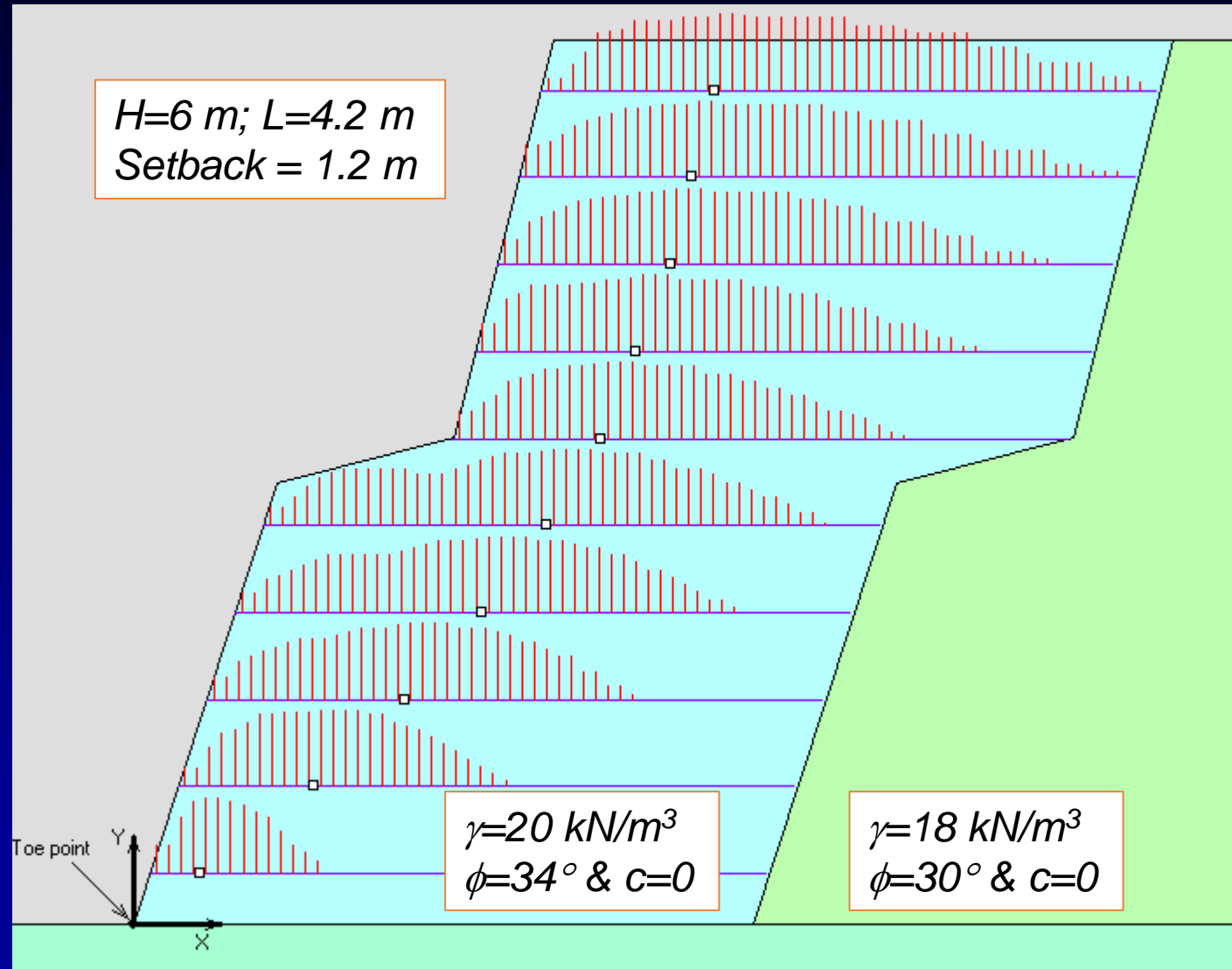
Rotational Global Stability:  
 $F_s = 1.0$   
In analysis,  $LTDS = \max(T_{\max})$   
from Baseline Solution.  
Increase LTDS to get  $F_s \geq 1.3$

Toe point  
Y  
X

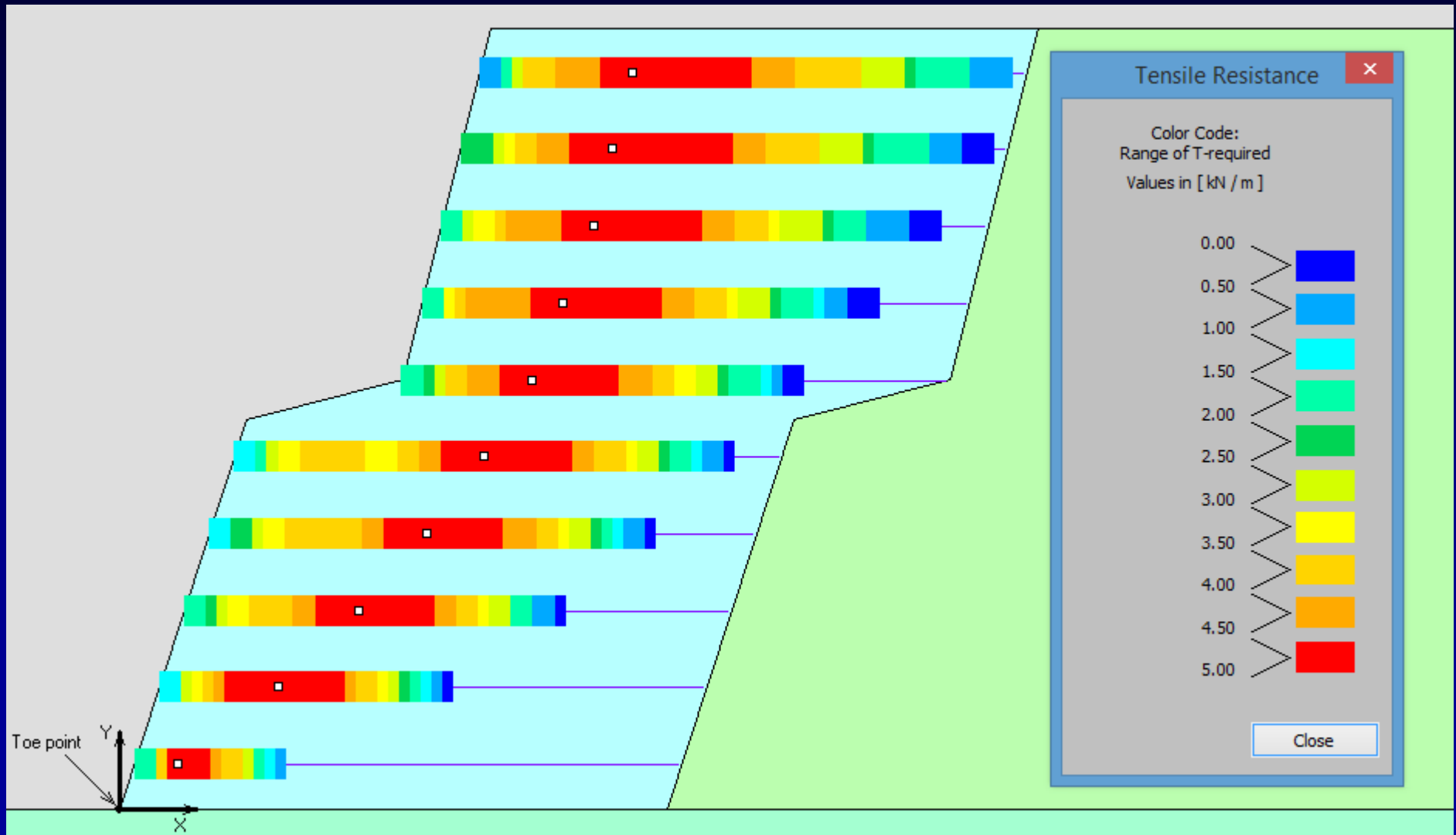
X

# 3(v):1(h) Two-Tier Wall

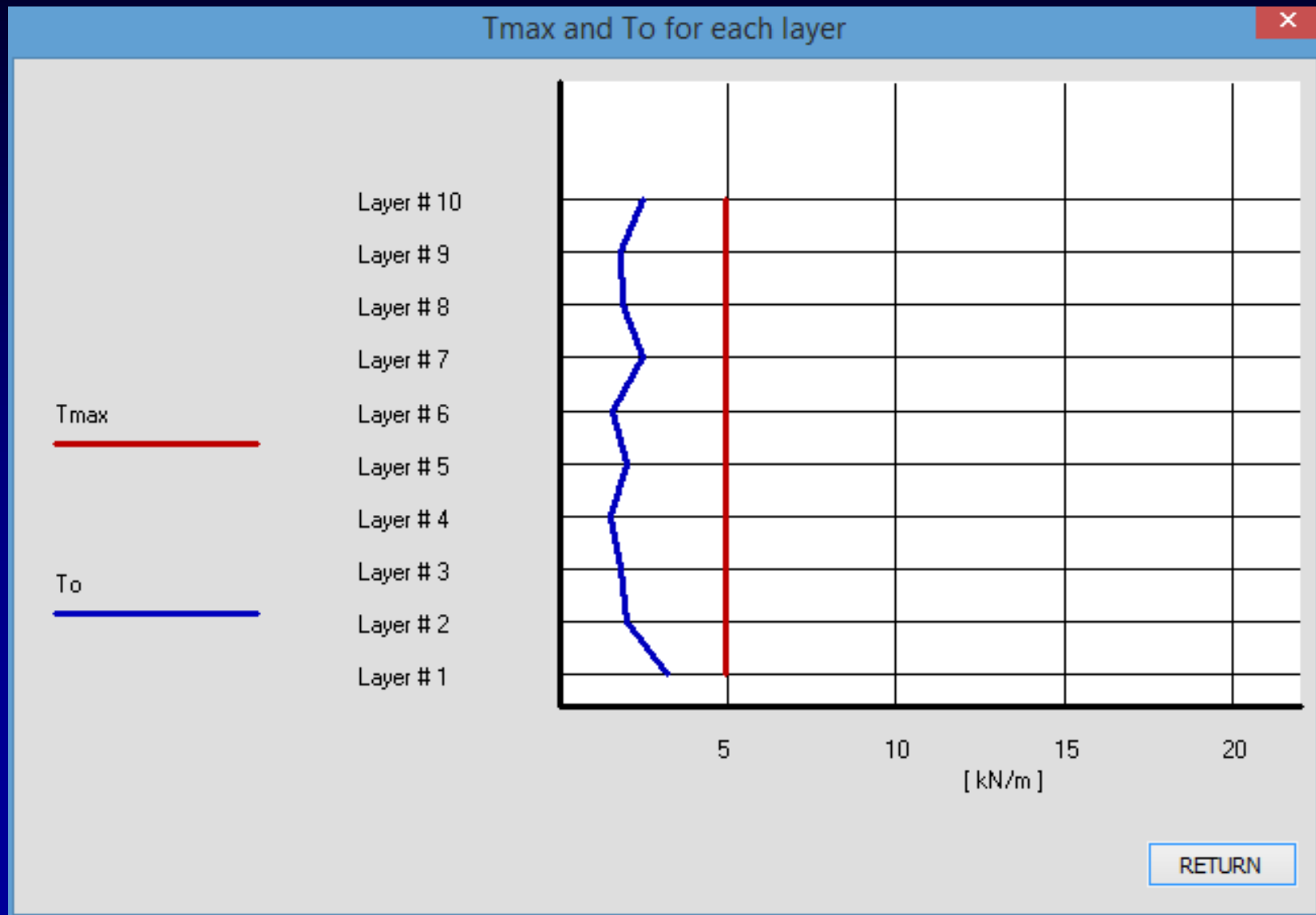
***Actual reinforced structures can be complex in geometry and site conditions. This can be accounted for using the baseline solution.***



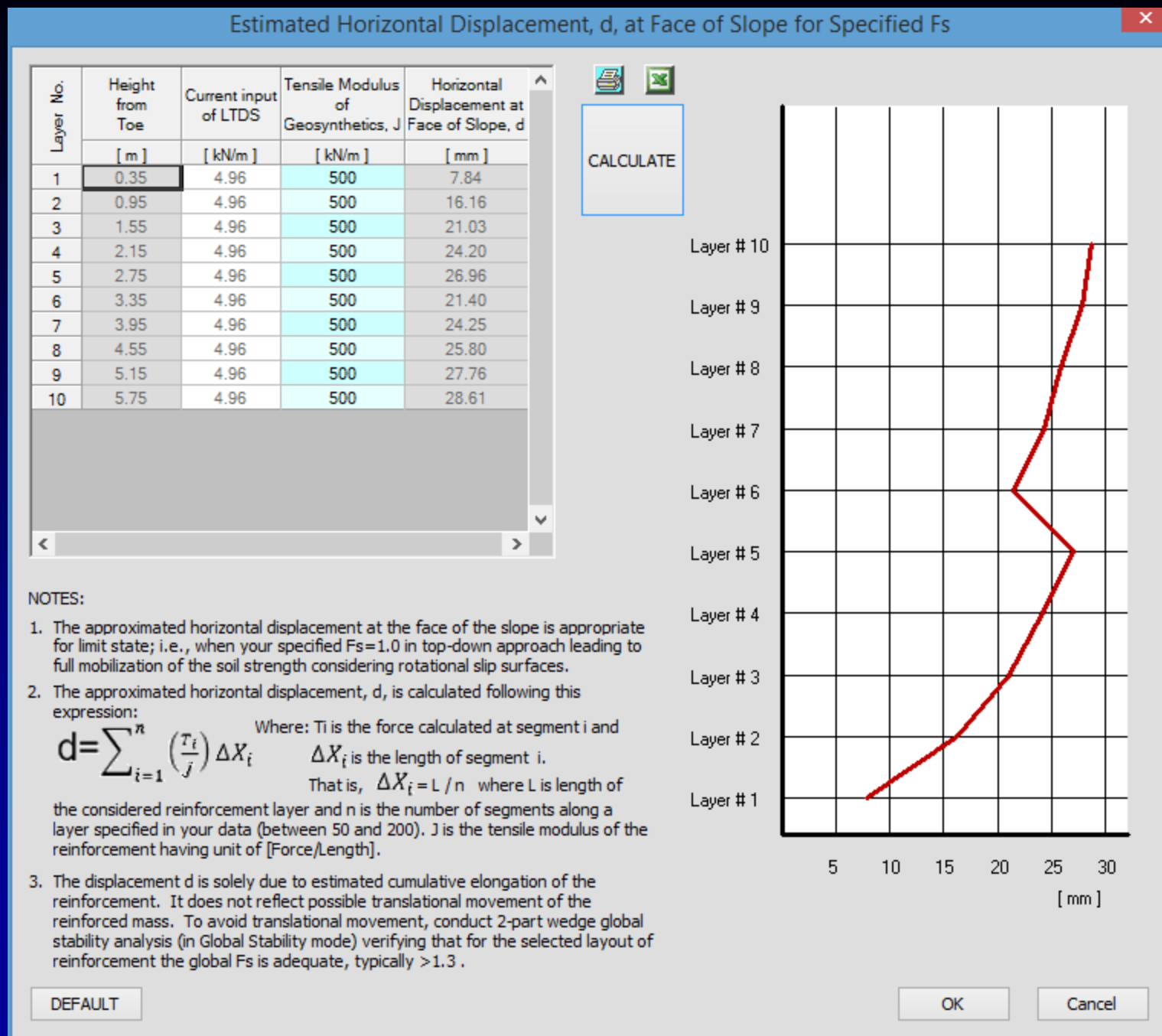
# Tension Map: 2-Tier Wall



# $T_{max}$ and $T_o$ in 2-Tier Wall

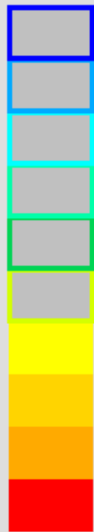


# Displ. in 2-Tier Wall

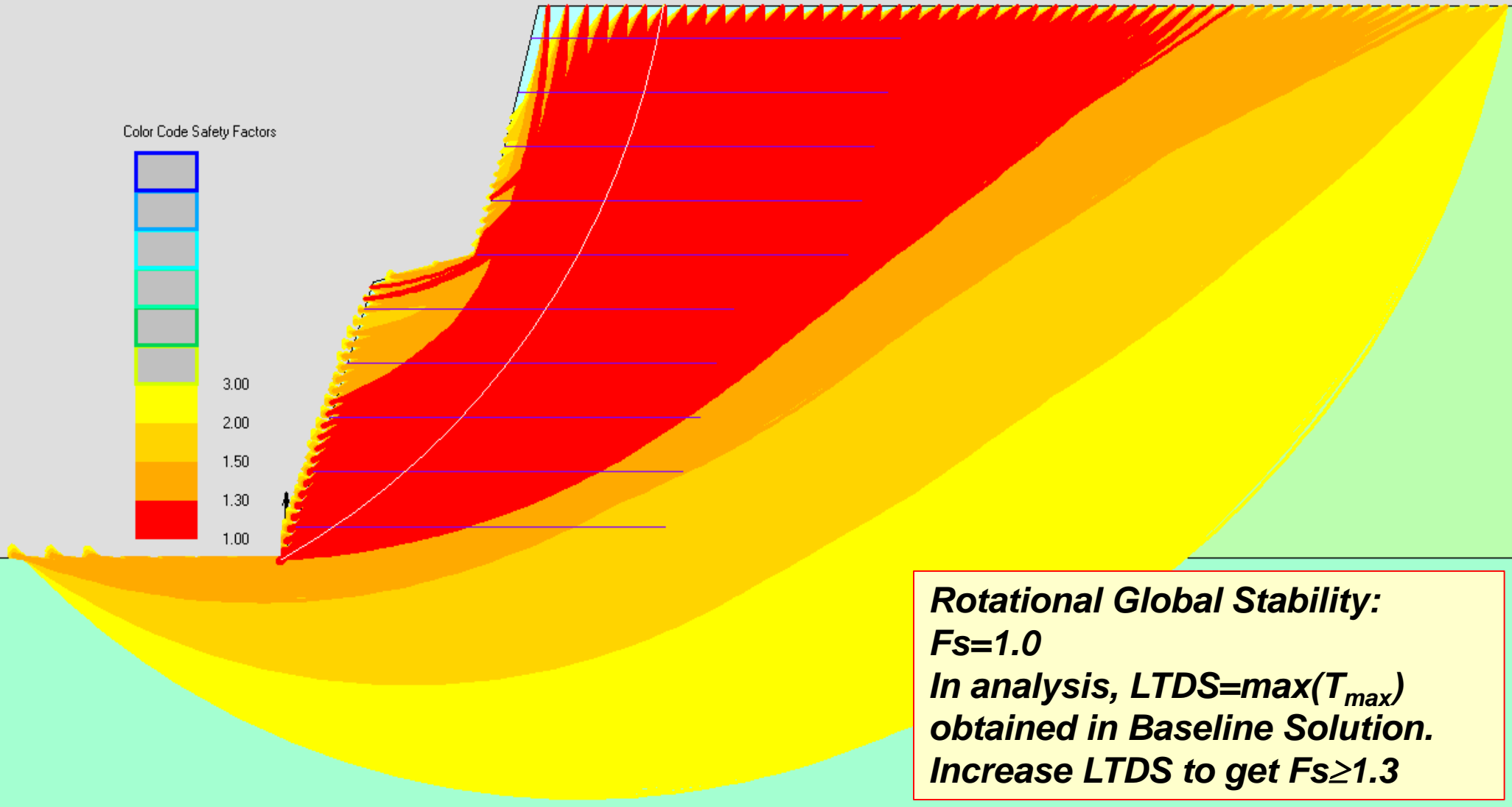


# Safety Map in 2-Tier Wall

Color Code Safety Factors



3.00  
2.00  
1.50  
1.30  
1.00



**Rotational Global Stability:**  
 **$F_s=1.0$**   
***In analysis,  $LTDS=\max(T_{max})$***   
***obtained in Baseline Solution.***  
***Increase LTDS to get  $F_s \geq 1.3$***

# ***Roadmap of Presentation***

- *Why Limit State analysis is needed?*
- *Available Limit State Methods of Analysis*
- *Limit Equilibrium: Global Approach*
- *The Safety Map Tool*
- *Limit Equilibrium Analysis: Baseline Solution (aka Internal Stability)*
- *Limit Equilibrium: Design Approach*
- *Limit Equilibrium: Design Examples*
- **Concluding Remarks**

# Concluding Remarks

## What about LRFD?

- AASHTO does not factor  $\phi$  in its synergistic approach combining results from internal and external stability
- However, AASHTO requires LE global stability, applying only 'resistance factor' =  $(1/F_s)$  → This is an **ad hoc** remedy → Hence, LRFD in global stability,  $F_s > 1.3$ , is considered in **Stage 2**
- In the Baseline Solution, **Stage 1**,  $F_s = 1.0$  is used to determine LTDS, consistent with the internal stability principles → **LRFD can be used as in AASHTO**

# ***Concluding Remarks***

## ***Last Minute News:***

- ***AASHTO has voted to approve the LE approach as presented in FHWA-HIF-17-004 (2016), which is the basis for ReSSA***
- ***It is scheduled to be implemented in AASHTO 2020, presented as an **alternative design approach for Internal Stability*****
- ***The global aspects of LE (Stage 2) has been in use since AASHTO 1998***
- ***AASHTO 2020 suggests some explicit multipliers which should make the internal stability (Stage 1) in ReSSA+ compatible with LRFD***

***Thank You!***